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Bi-flat F-manifolds, Frölicher-Nijenhuis
bicomplexes and integrable systems

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Plan of the talk

1. Frölicher-Nijenhuis bicomplex and integrable systems of hydrodynamic type.

Based on a joint work with **F. Magri** (2005).

2. Frölicher-Nijenhuis bicomplex and Lauricella bi-flat F-manifolds.

Based on a joint work with **S. Perletti** (2023).

3. Bi-flat F-manifolds, lifted Frölicher-Nijenhuis bicomplexes and Gauss-Manin connections.

Based on a joint work with **A. Arsie** (2024).

PART I

Frölicher-Nijenhuis bicomplex and integrable systems of hydrodynamic type.

Based on a joint work with **F. Magri** (2005).

Nijenhuis operators and Frölicher-Nijenhuis bicomplex

Let L be a $(1, 1)$ tensor field L with vanishing Nijenhuis torsion:

$$[LX, LY] - L[X, LY] - L[LX, Y] + L^2[X, Y] = 0.$$

Define d_L as

$$\begin{aligned} (d_L\omega)(X_0, \dots, X_k) &= \sum_{i=0}^k (-1)^i (LX_i)(\omega(X_0, \dots, \hat{X}_i, \dots, X_k)) + \\ &+ \sum_{0 \leq i < j \leq k} (-1)^{i+j} \omega([X_i, X_j]_L, X_0, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_k), \end{aligned}$$

where

$$[X_i, X_j]_L = [LX_i, X_j] + [X_i, LX_j] - L[X_i, X_j].$$

Frölicher-Nijenhuis bicomplex

The Frolicher-Nijeehuis bicomplex is $(d, d_L, \Omega(M))$ where

- ▶ $\Omega(M)$ is the Grasmann algebra of differential forms on M .
- ▶ d is the usual de Rham differential,
- ▶ $d_L^2 = 0$ due to the vanishing of the Nijenhuis torsion.
- ▶ Since $L + I$ has vanishing Nijenhuis torsion we have

$$d \cdot d_L + d_L \cdot d = 0.$$

Classical Lenard-Magri recursion

Starting from a solution of

$$d \cdot d_L a_0 = 0$$

the recursion

$$da_{k+1} = d_L a_k$$

is well defined. Indeed, due to anticommutativity of d and d_L at each step we have

$$d \cdot d_L a_k = -d_L \cdot da_k = -d_L^2 a_{k-1} = 0.$$

Generalized Lenard-Magri recursion

Starting from a solution of

$$d \cdot d_L a_0 = 0$$

it is not difficult to prove that also the recursion

$$da_{k+1} = d_L a_k - a_k da_0$$

is well defined. The sequence of functions a_0, a_1, a_2, \dots , obtained in this way satisfy the equation

$$d \cdot d_L a_k = da_k \wedge da_0.$$

Similar recursion appears in the geometric theory of separation of variables (Falqui, Magri and Pedroni).

Generalized Lenard-Magri chains and integrable systems of hydrodynamic type

Theorem (P.L and F. Magri 2005)

Let a_0, a_1, a_2, \dots be a sequence of functions obtained applying generalized Lenard-Magri recursion and let V_k be the tensor fields of type $(1, 1)$ defined recursively by

$$V_{k+1} = V_k L - a_k I,$$

starting from $V_0 = I$, then the flows

$$\mathbf{u}_{t_k} = V_k \mathbf{u}_x \quad k = 0, 1, 2, \dots$$

commute. Moreover the densities of conservation laws h satisfy the equation

$$d \cdot d_L h = dh \wedge da_0.$$

Generalized ε -system

The system of hydrodynamic type

$$\begin{bmatrix} u_{t_1}^1 \\ \vdots \\ u_{t_1}^n \end{bmatrix} = \begin{bmatrix} u^1 - \sum_{k=1}^n \varepsilon_k u^k & \dots & 0 \\ \vdots & \ddots & \vdots \\ 0 & \dots & u^n - \sum_{k=1}^n \varepsilon_k u^k \end{bmatrix} \begin{bmatrix} u_x^1 \\ u_x^2 \\ \vdots \\ u_x^n \end{bmatrix}$$

has been obtained by Pavlov as finite component reduction of an infinite hydrodynamic chain. It can be written as

$$\mathbf{u}_{t_1} = (L - a_0 I) \mathbf{u}_x$$

with $a_0 = \sum_{k=1}^n \varepsilon_k u^k$ and $L = \text{diag}(u^1, \dots, u^n)$. The system for densities of conservation laws

$$d \cdot d_L h = dh \wedge da_0$$

reduces to the Euler-Darboux-Poisson system that appears in the study of Whitham equations (F.R.Tian 1994, T. Grava 2001).

Kodama-Konopelchenko system, 2015

The system of hydrodynamic type

$$\begin{bmatrix} u_{t_1}^1 \\ u_{t_1}^2 \\ \vdots \\ u_{t_1}^{n-1} \\ u_{t_1}^n \end{bmatrix} = \begin{bmatrix} u^1 & 1 & 0 & \dots & 0 \\ 0 & u^1 & 1 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & 0 & u^1 & 1 \\ 0 & \dots & 0 & 0 & u^1 \end{bmatrix} \begin{bmatrix} u_x^1 \\ u_x^2 \\ \vdots \\ u_x^{n-1} \\ u_x^n \end{bmatrix} \quad (1)$$

can be written as $\mathbf{u}_{t_1} = (L - a_0 I)\mathbf{u}_x$ with $a_0 = -u^1$ and

$$L = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \dots & 0 & 0 & 1 \\ 0 & \dots & 0 & 0 & 0 \end{bmatrix}.$$

(see also Konopelchenko-Ortenzi 2017)

Clearly L has vanishing Nijenhuis torsion and $dd_L a_0 = 0$.
Applying the first step of the recursive procedure we have

$$\partial_1 a_1 = -a_0 \partial_1 a_0 = -u^1$$

$$\partial_2 a_1 = \partial_1 a_0 - a_0 \partial_2 a_0 = -1$$

$$\partial_3 a_1 = 0$$

\vdots

$$\partial_n a_1 = 0.$$

This implies (up to an inessential constant) $a_1 = -u^2 - \frac{(u^1)^2}{2}$.
Therefore the first commuting flow

$$\mathbf{u}_t = (L^2 - a_0 L - a_1 I) \mathbf{u}_x.$$

PART II

Frölicher-Nijenhuis bicomplex and Lauricella bi-flat
F-manifolds.

Based on a joint work with **S. Perletti** (2023).

Flat F -manifolds (Manin)

Definition

A **flat F -manifold** (M, ∇, \circ, e) a manifold equipped with a product

$$\circ : TM \times TM \rightarrow TM$$

with structure functions c_{jk}^i , a connection ∇ with Christoffel symbols a_{jk}^i and a distinguished vector field e s.t.

- ▶ the one parameter family of connections ∇_λ

$$a_{jk}^i - \lambda c_{jk}^i$$

is flat and torsionless for any λ .

- ▶ e is the unit of the product.
- ▶ e is flat: $\nabla e = 0$.

For a given λ the torsion and the curvature are

$$T_{ij}^{(\lambda)k} = a_{ij}^k - a_{ji}^k + \lambda(c_{ij}^k - c_{ji}^k)$$

$$R_{ijl}^{(\lambda)k} = R_{ijl}^k + \lambda(\nabla_i c_{jl}^k - \nabla_j c_{il}^k) + \lambda^2(c_{im}^k c_{jl}^m - c_{jm}^k c_{il}^m),$$

We obtain

1. the connection ∇ is torsionless,
2. the product \circ is commutative,
3. the connection ∇ is flat,
4. the tensor field $\nabla_i c_{ij}^k$ is symmetric in the low indices,
5. the product \circ is associative.

The above conditions imply

$$c_{jk}^i = \partial_j \partial_k F^i.$$

Bi-flat F manifolds (A. Arsie, P.L 2012)

Definition

A *bi-flat* F-manifold is a manifold M equipped with a pair of flat structures (∇, \circ, e) and $(\nabla^*, *, E)$ related by the following conditions:

- ▶ E is an Euler vector field for the first structure

$$[e, E] = e, \quad \mathcal{L}_{E \circ} = 0$$

and at a generic point the operator $E \circ$ is assumed to be invertible.

- ▶ $*$ is the product defined by E , i.e. $X * Y = (E \circ)^{-1} X \circ Y$.
- ▶ $(d_{\nabla} - d_{\nabla^*})(X \circ) = 0$, where d_{∇} is the exterior covariant derivative of vector-valued differential forms.

Regular bi-flat F-manifolds

Definition

A bi-flat F-manifold is called regular if at a generic point the Jordan canonical form of the operator $L = E \circ$ has n Jordan blocks of sizes m_1, \dots, m_n with distinct eigenvalues.

Semisimple bi-flat F-manifolds are regular bi-flat F-manifolds where $m_1 = \dots = m_n = 1$.

In semisimple case there exist local coordinates (called canonical coordinates) such that:

$$e = \sum_{s=1}^n \frac{\partial}{\partial u^s}, \quad E = \sum_{s=1}^n u^s \frac{\partial}{\partial u^s}, \quad c_{jk}^i = \delta_j^i \delta_k^i$$

David-Hertling canonical coordinates

Theorem

Let $(M, \nabla, \circ, e, \nabla^*, *, E)$ be a regular bi-flat F -manifold. Then there exists local coordinates such that

$$e = \frac{\partial}{\partial u^1} + \frac{\partial}{\partial u^{m_1+1}} + \frac{\partial}{\partial u^{m_1+m_2+1}} + \cdots + \frac{\partial}{\partial u^{m_1+\cdots+m_{n-1}+1}},$$
$$E = \sum_{s=1}^{m_1+\cdots+m_n} u^s \frac{\partial}{\partial u^s},$$
$$c_{ij}^l = \delta_{i+j-1}^l, \quad i, j, l = m_1 + \cdots + m_{k-1} + 1, \dots, m_1 + \cdots + m_{k-1} + m_k$$
$$c_{ij}^l = 0, \quad \text{otherwise.}$$

Remark: the result holds true under weaker assumptions.

Operator of multiplication by E

The tensor field $L = E \circ$ contains n blocks L_1, \dots, L_n of dimension m_1, \dots, m_n respectively. Each block has the form

$$L_k = \begin{bmatrix} u^{k,1} & 0 & \dots & 0 \\ u^{k,2} & u^{k,1} & \dots & 0 \\ \vdots & \ddots & \ddots & \vdots \\ u^{k,m_k} & \dots & u^{k,2} & u^{k,1} \end{bmatrix}$$

where $u^{k,l} = u^{m_1 + \dots + m_{k-1} + l}$.

Dubrovin-Frobenius manifolds

To define a Dubrovin-Frobenius manifold we need

- ▶ a metric η satisfying the conditions

$$\eta_{il}c_{jk}^l = \eta_{jl}c_{ik}^l, \quad \nabla\eta = 0.$$

It turns out that $c_{jk}^i = \eta^{il}\partial_l\partial_j\partial_k F$ where F is a solution of WDVV equations.

- ▶ Duality for Dubrovin-Frobenius manifold (almost-dual structure, Dubrovin 2004): it is defined by the data $(g, *, E)$ where E is the Euler vector field,

$$g = (E \circ)\eta^{-1}, \quad X * Y = (E \circ)^{-1}X \circ Y$$

Notice that $\nabla^{(g)}E \neq 0$ but there exists μ such that $\nabla^{(g)} - \nabla^* = \mu *$.

Integrable hierarchy associated with flat F-manifolds

Given a flat F-manifold (M, ∇, \circ, e) the flows of the associated integrable hierarchy have the form

$$\mathbf{u}_t = X \circ \mathbf{u}_x$$

where X is a solution of the equation

$$d_{\nabla}(X \circ) = 0.$$

A sequence of solutions of this equation can be obtained starting from flat vector fields X_0 by means of the following recursive relation

$$d_{\nabla} X_{(\alpha+1)} = X_{(\alpha)} \circ .$$

This sequence is called **principal hierarchy**.

Some results on bi-flat F-manifolds

Bi-flat F-manifolds structures naturally appear:

- ▶ on the orbit space of reflection groups:
M. Kato, T. Mano, J. Sekiguchi (2015),
A. Arsie and P. L (2016),
Y. Konishi, S. Minabe and Y. Shiraishi (2016).
- ▶ in relation with Painlevé transcendents:
A. Arsie, P. L (2012 and 2015)
P. L (2013),
H. Kawakami and T. Mano (2017).
- ▶ as genus 0 part of F-cohomological field theories:
A. Arsie, A. Buryak, P. L and P. Rossi (2020).

Problem

Given a bi-flat F-structure $(\nabla, \circ, e, \nabla^*, *, E)$ is well known that the operator

$$L = E \circ$$

has vanishing Nijenhuis torsion. In the regular case in David-Hertling canonical coordinates L has block diagonal form and each block has lower triangular Toeplitz form. Consider

$$V = L - a_0 I, \quad d \cdot d_L a_0 = 0$$

Question: there exists a bi-flat F-manifolds such that

$$d_{\nabla} V = 0, \quad ?$$

Regular Lauricella bi-flat F-manifolds

Theorem (P. L, S. Perletti 2023)

For any choice of $\varepsilon_1, \dots, \varepsilon_r$ there exists a unique regular bi-flat structure $(\nabla, \nabla^, \circ, *, e, E)$ with canonical coordinates $\{u^1, \dots, u^n\}$ such that $d_{\nabla}(E \circ -a_0 I) = 0$, where r is the number of the Jordan blocks (of sizes m_1, \dots, m_r) of $E \circ$ and, set $m_0 = 0$,*

$$a_0 = \sum_{\alpha=1}^r m_{\alpha} \varepsilon_{\alpha} u^{1(\alpha)} = \sum_{\alpha=1}^r m_{\alpha} \varepsilon_{\alpha} u^{m_0 + m_1 + \dots + m_{\alpha-1} + 1}.$$

The case of a 2×2 Jordan block

In this case

$$L = \begin{bmatrix} u^1 & 0 \\ u^2 & u^1 \end{bmatrix}, \quad e = \frac{\partial}{\partial u^1} \quad a_0 = 2\varepsilon_1 u^1.$$

The non vanishing Christoffel symbol of $\nabla^{(1)}$ is

$$\Gamma_{22}^2 = -\frac{2\varepsilon_1}{u^2}.$$

3 × 3 Jordan block

$$L = \begin{bmatrix} u^1 & 0 & 0 \\ u^2 & u^1 & 0 \\ u^3 & u^2 & u^1 \end{bmatrix}, \quad \mathbf{e} = \frac{\partial}{\partial u^1}, \quad \mathbf{a}_0 = 3\varepsilon_1 u^1$$

The non vanishing Christoffel symbols Γ_{jk}^i (up to exchange of j with k) are

$$\Gamma_{22}^2 = \Gamma_{23}^3 = -\frac{3\varepsilon_1}{u^2}, \quad \Gamma_{22}^3 = \frac{3\varepsilon_1 u^3}{(u^2)^2}$$

$2 \times 2 + 1 \times 1$ Jordan blocks

$$L = \begin{bmatrix} u^1 & 0 & 0 \\ u^2 & u^1 & 0 \\ 0 & 0 & u^3 \end{bmatrix}, \quad e = \frac{\partial}{\partial u^1} + \frac{\partial}{\partial u^3}, \quad a_0 = 2\varepsilon_1 u^1 + \varepsilon_3 u^3$$

The non vanishing Christoffel symbols Γ_{jk}^i (up to exchange of j with k) are

$$\Gamma_{22}^2 = -\frac{2\varepsilon_1}{u^2}, \quad \Gamma_{13}^1 = \Gamma_{23}^2 = -\Gamma_{11}^1 = -\Gamma_{33}^1 = -\Gamma_{12}^2 = \frac{\varepsilon_3}{u^1 - u^3}$$
$$\Gamma_{11}^3 = \Gamma_{33}^3 = -\Gamma_{13}^3 = \frac{2\varepsilon_1}{u^1 - u^3}, \quad \Gamma_{21}^2 = \Gamma_{33}^2 = -\Gamma_{13}^2 = \frac{\varepsilon_3 u^2}{(u^1 - u^3)^2}$$

Work in progress

What happens for arbitrary solutions of the equation

$$d \cdot d_L a_0 = 0 \quad ?$$

Conjectural answer: $a_0 \rightarrow (\nabla, \circ, e)$ where ∇ is still compatible with the product but the flatness condition is replaced by

$$Z \circ R(W, Y)(X) + W \circ R(Y, Z)(X) + Y \circ R(Z, W)(X) = 0.$$

Joint work with with **S. Perletti** and **K. van Gemst**.

PART III

Bi-flat F-manifolds, lifted Frölicher-Nijenhuis bicomplexes and Gauss-Manin connections.

Based on a joint work with **A. Arsie** (2024).

From bi-flat structures to a differential bicomplex

$$\begin{array}{ccc} & (M, \nabla, \circ, e, \nabla^*, *, E) & \\ \swarrow & & \searrow \\ (d_\nabla, d_{E \circ \nabla^*}, \mathcal{T}_M \otimes_{\mathcal{O}_M} \Omega_M^\bullet) & \longleftrightarrow & \nabla_{GM} \end{array}$$

The bicomplex $(d_\nabla, d_{E \circ \nabla^*}, \mathcal{T}_M \otimes_{\mathcal{O}_M} \Omega_M^\bullet)$ can be thought as a “lift” of the Frölicher-Nijenhuis bicomplex on the space of vector valued forms.

Exterior covariant derivative

d_{∇} acts on $\mathcal{T}_M \otimes_{\mathcal{O}_M} \Omega_M^k$ as follows

$$(d_{\nabla}\omega)(X_0, \dots, X_k) = \sum_{i=0}^k (-1)^i \nabla_{X_i}(\omega(X_0, \dots, \hat{X}_i, \dots, X_k)) + \sum_{0 \leq i < j \leq k} (-1)^{i+j} \omega([X_i, X_j], X_0, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_k).$$

On an open ball the cohomology (for $k \geq 1$) of d_{∇} is trivial this follows from the triviality of the usual de Rham cohomology).

It turns out $d_{\nabla}^2 = 0$ due to the flatness of ∇ .

L -exterior covariant derivative (A. Arsie, P.L 2012)

Given a flat connection ∇ and a $(1, 1)$ -tensor field with vanishing Nijenhuis torsion it is possible to define another differential on $\mathcal{T}_M \otimes_{\mathcal{O}_M} \Omega_M^k$. $d_{L\nabla}$ acts as follows

$$(d_{L\nabla}\omega)(X_0, \dots, X_k) = \sum_{i=0}^k (-1)^i \nabla_{LX_i}(\omega(X_0, \dots, \hat{X}_i, \dots, X_k)) + \sum_{0 \leq i < j \leq k} (-1)^{i+j} \omega([X_i, X_j]_L, X_0, \dots, \hat{X}_i, \dots, \hat{X}_j, \dots, X_k).$$

It turns out $d_{L\nabla}^2 = 0$ due to the flatness of ∇ and the vanishing of the Nijenhuis torsion of L .

A differential bicomplex (A. Arsie, P.L 2024)

Theorem

On any bi-flat F -manifold M , d_{∇} and $d_{L\nabla^}$ determine a differential bicomplex structure on $\mathcal{T}_M \otimes_{\mathcal{O}_M} \Omega_M^\bullet$.*

Due to the previous results it remains to prove that d_{∇} and $d_{L\nabla^*}$ anticommute. We skip the proof since it is equivalent to the vanishing of the curvature of a family of connections we are going to introduce.

Lenard-Magri chains

Let $X_{(0)}$ be a local section of \mathcal{T}_M for ∇ satisfying the equation

$$d_{\nabla} \cdot d_{L\nabla^*} X_{(0)} = 0. \quad (2)$$

Then we can define “higher” local sections of \mathcal{T}_M by using the following recurrence relations

$$d_{\nabla} X_{(\alpha+1)} = d_{L\nabla^*} X_{(\alpha)}, \quad \alpha \in \mathbb{N} \quad (3)$$

Indeed, equation (2) tell us that $d_{L\nabla^*} X_{(0)}$ is a d_{∇} -cocycle in degree 1. Therefore, there exists locally a vector field $X_{(1)}$ such that

$$d_{\nabla} X_{(1)} = d_{L\nabla^*} X_{(0)}.$$

Since d_{∇} and $d_{L\nabla^*}$ anticommute we have

$$d_{L\nabla^*} \cdot d_{\nabla} X_{(1)} = -d_{\nabla} \cdot d_{L\nabla^*} X_{(0)} = 0$$

and we can repeat the previous argument.

Gauss-Manin connections

The Gauss-Manin connections associated with a bi-flat structure are

$$\nabla_X^{GM} Y = \nabla_X^* Y + \lambda(\nabla_{(E_0 - \lambda e_0)^{-1} X}^* Y - \nabla_{(E_0 - \lambda e_0)^{-1} X} Y).$$

Denoting by a_{jk}^i and b_{jk}^i the Christoffel symbols of the connections ∇ and ∇^* respectively, the Christoffel symbols are

$$\Gamma_{hk}^j := b_{hk}^j + \lambda((L_\lambda)^{-1})_h^s (b_{sk}^j - a_{sk}^j), \quad (4)$$

or

$$\Gamma_{hk}^j = b_{hk}^j + \lambda((L_\lambda)^{-1})_h^s c_{sk}^l \nabla_l^* e^j, \quad (5)$$

or

$$\Gamma_{hk}^j = b_{hk}^j - \lambda((L_\lambda)^{-1})_h^s c_{sk}^l \nabla_l E^j, \quad (6)$$

Theorem

(A. Arsie, P.L 2024) The family of Gauss-Manin connections is flat and torsionless for any fixed λ on the open set where L_λ is invertible.

$$\begin{aligned}
 (R^{GM})^j_{ilk} (L_\lambda)^l_h (L_\lambda)^i_t = & \\
 (R_{\nabla^*})^j_{ilk} (L_\lambda)^l_h (L_\lambda)^i_t + \lambda^2 & ((R_{\nabla^*})^j_{htk} - (R_{\nabla})^j_{htk}) \\
 + \lambda \left(L^l_h ((R_{\nabla^*})^j_{tlk} - (R_{\nabla})^j_{tlk}) + L^l_t & ((R_{\nabla^*})^j_{hlk} - (R_{\nabla})^j_{hlk}) \right) \\
 - \lambda (\nabla_t c^s_{hk} - \nabla_h c^s_{tk}) \nabla_s E^j - \lambda (c^s_{hk} \nabla_t \nabla_s E^j - c^s_{tk} \nabla_h \nabla_s E^j) & \\
 + \lambda (N_L)^m_{th} \left((L_\lambda)^{-1} \right)^s_m (L^{-1})^r_s c^t_{rk} \nabla_t E^j = 0. &
 \end{aligned}$$

From this formula it follows that ∇^* can be replaced with $\nabla^* + \mu^*$. In the case of Dubrovin-Frobenius manifolds with a suitable choice of μ one gets the Levi-Civita connection of g_λ .

Theorem

Let X be a local section $X \in \mathcal{T}_M$ that is flat with respect to ∇_{GM} . Then, viewing X as an element of $\mathcal{T}_M[[\lambda^{-1}]]$, then the formal power series coefficients satisfy the Lenard-Magri recurrence relations (3).

From $\nabla^{GM} X = 0$, using arbitrary sections $Y \in \mathcal{T}_M$, we have

$$\begin{aligned}\nabla_{L_\lambda Y}^{GM} X &= \nabla_{L_\lambda Y}^* X + \lambda(\nabla_Y^* X - \nabla_Y X) \\ &= \nabla_{LY}^* X - \lambda \nabla_Y^* X + \lambda(\nabla_Y^* X - \nabla_Y X) \\ &= \nabla_{LY}^* X - \lambda \nabla_Y X = 0.\end{aligned}$$

Substituting

$$X = X_{(0)} + \frac{X_{(1)}}{\lambda} + \frac{X_{(2)}}{\lambda^2} + \dots$$

we get Lenard-Magri recurrence relations (3).

Extended Gauss-Manin system: dependence on λ

Proposition

Let (t^1, \dots, t^n) be flat coordinates of ∇ such that $e = \frac{\partial}{\partial t^1}$. In such coordinates, the solutions of the system $\nabla^{GM}\theta = 0$ have the form

$$\theta = \theta(t^1 - \lambda, t^2, \dots, t^n).$$

Moreover

$$(L - \lambda I)_i^j \partial_\lambda \theta_j = -L_i^l b_{l1}^j \theta_j.$$

Bibliography

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