

SCALE along any straight line through the centre

No. of circles

Miles

Black Hole Evolutions:

Lessons from bifurcation theory

arXiv:2605.30458 + in progress

Matt's Journey Through Space and Time
(Trieste, 2026)

Ivan Booth

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- During a merger what happens to the original black holes?
- What happens inside the final black after the new apparent horizon forms?
- More specifically : Do the original black holes end?
- What does this question even mean?

How do black holes end?

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```
graph TD; A["How do black holes end?"] --> B["How do"]; A --> C["black holes"]; A --> D["end?"]
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Should be:

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- ii. distinguishable from
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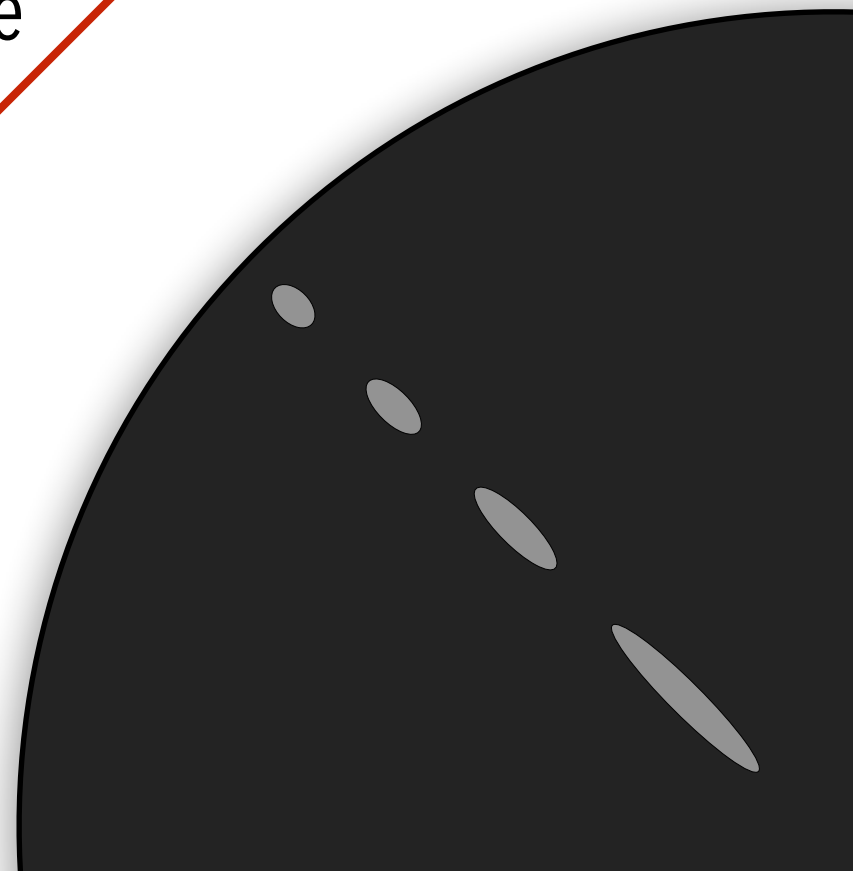
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- "external fields"
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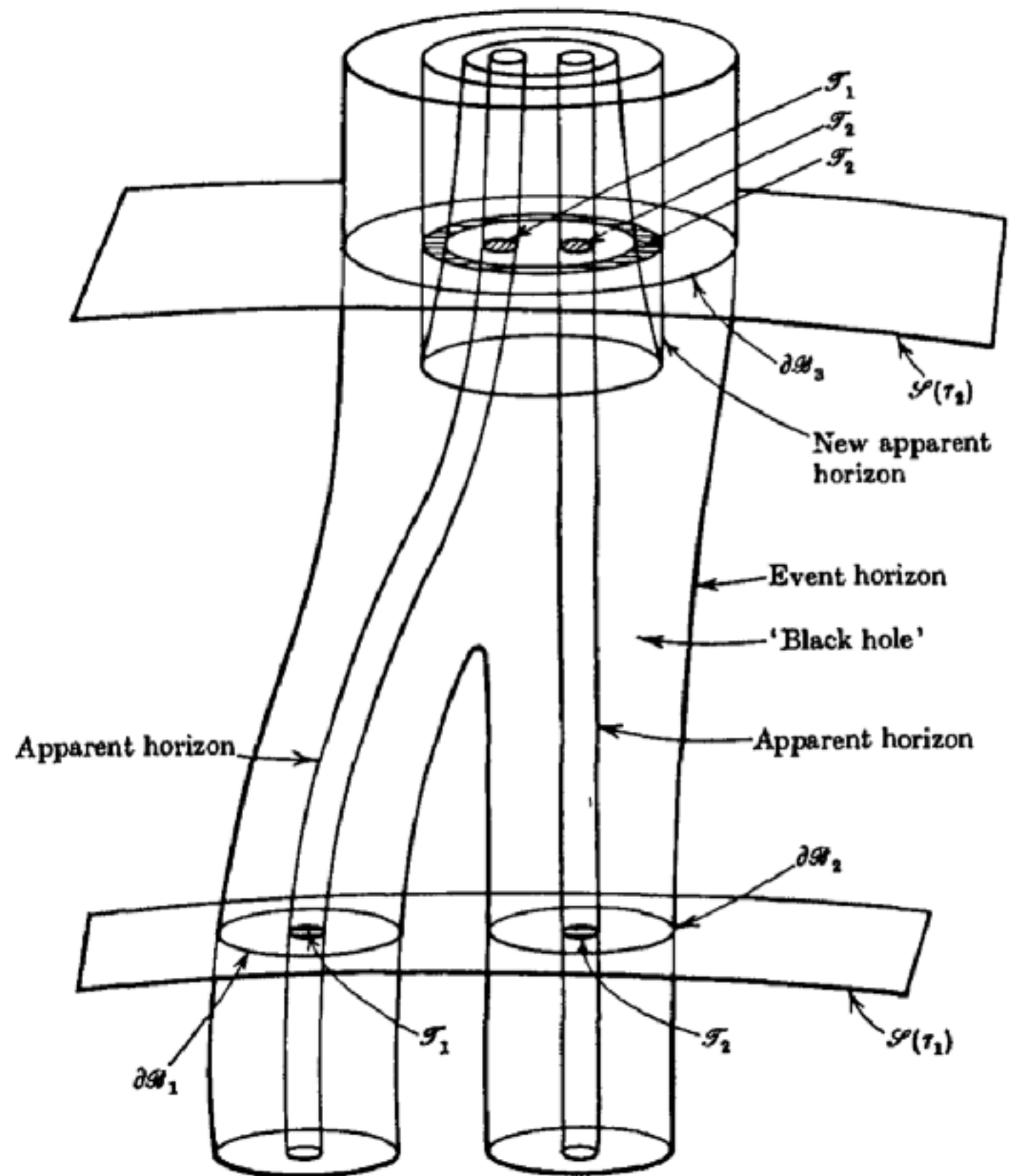
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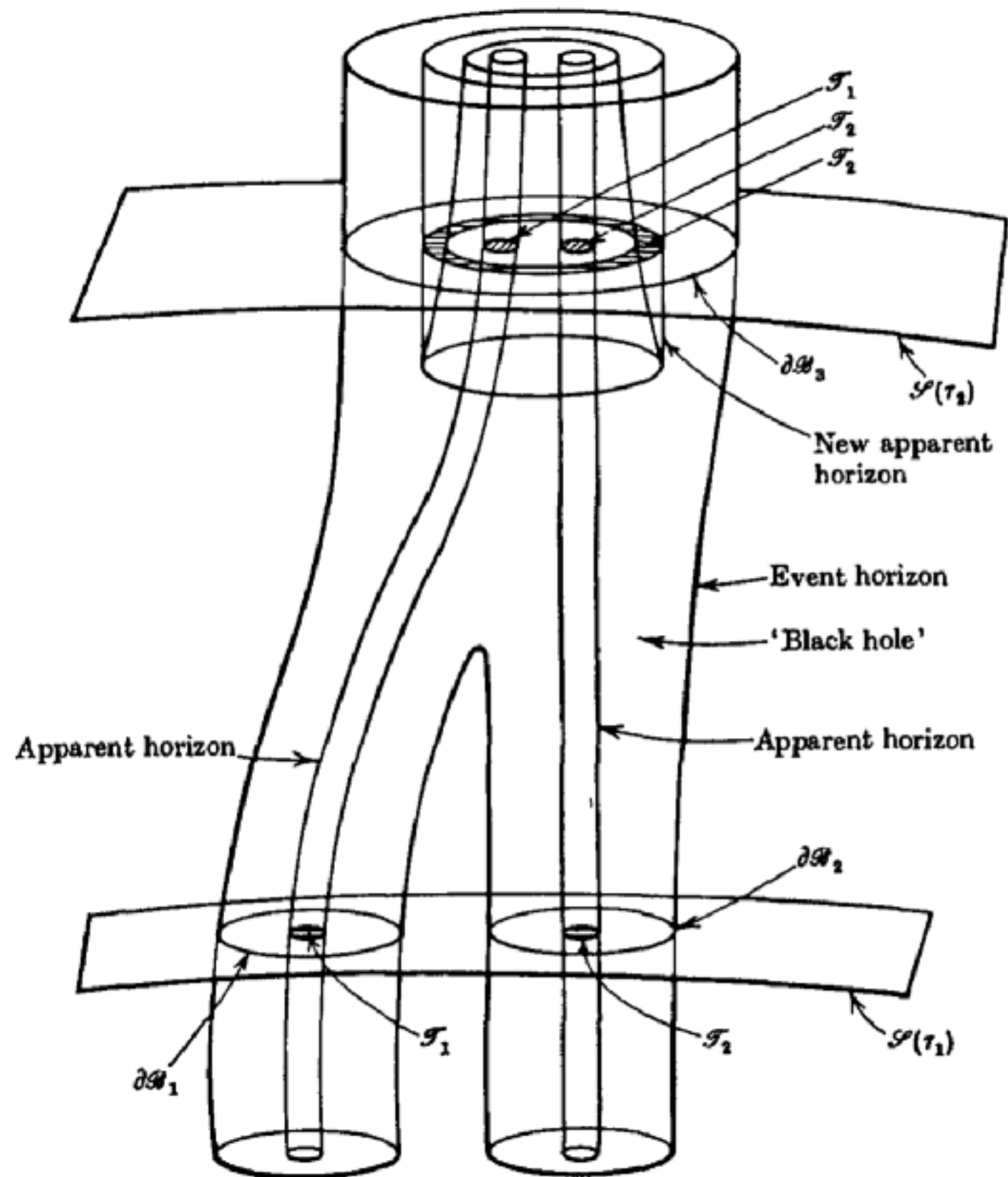
"Dissolved"

Black hole mergers and event horizons



Black hole mergers and event horizons

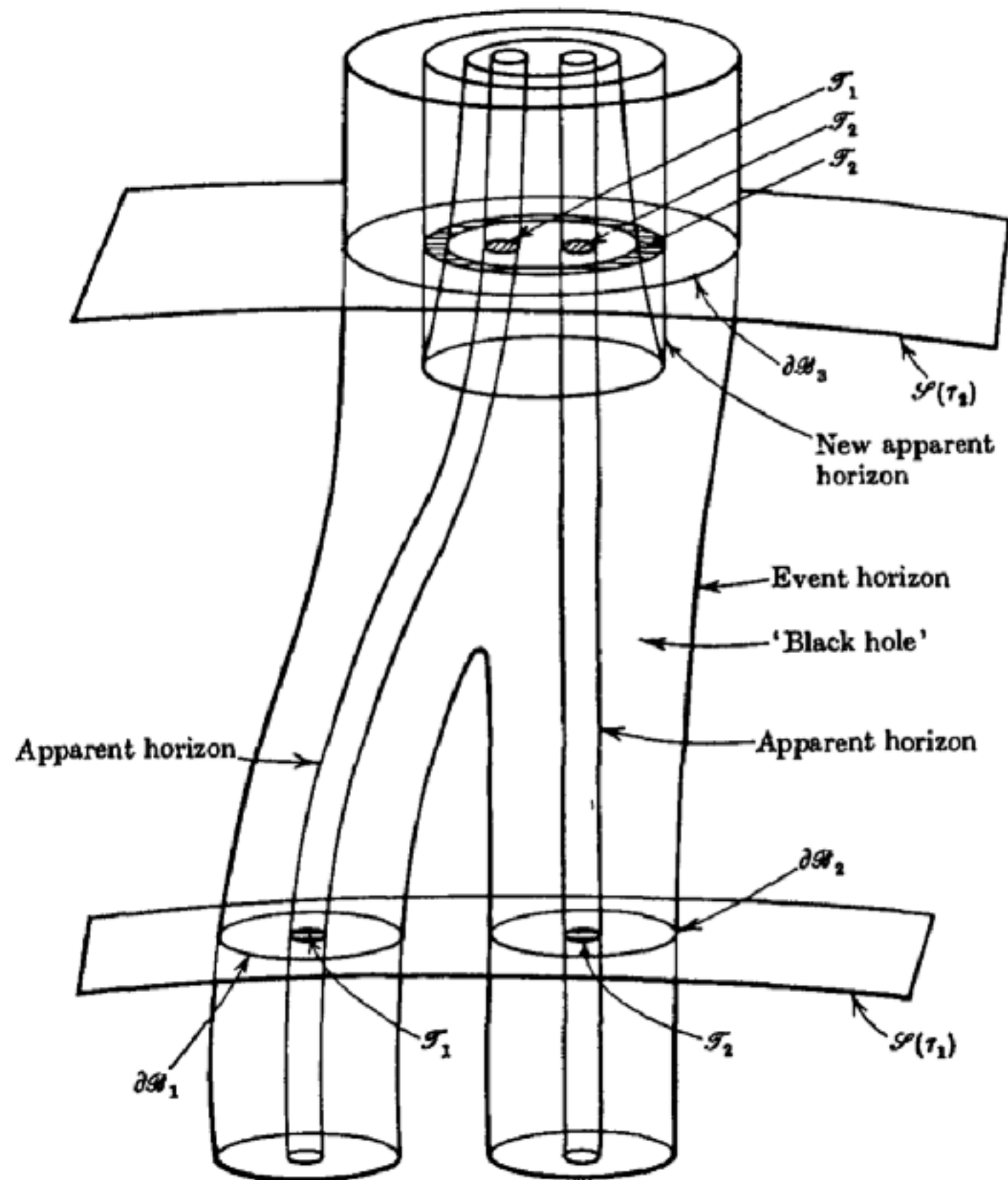
Causal black holes



Black hole mergers and event horizons

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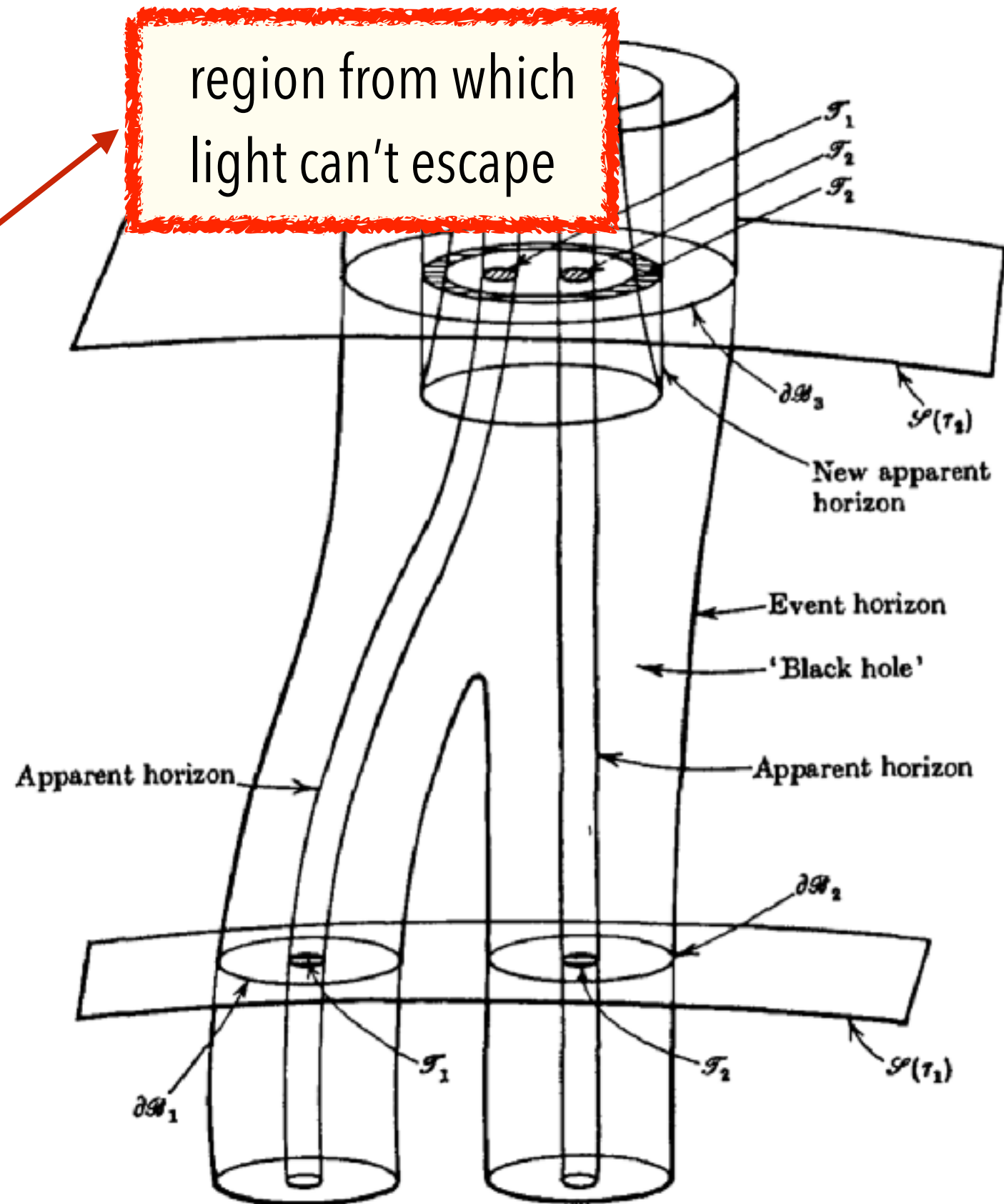
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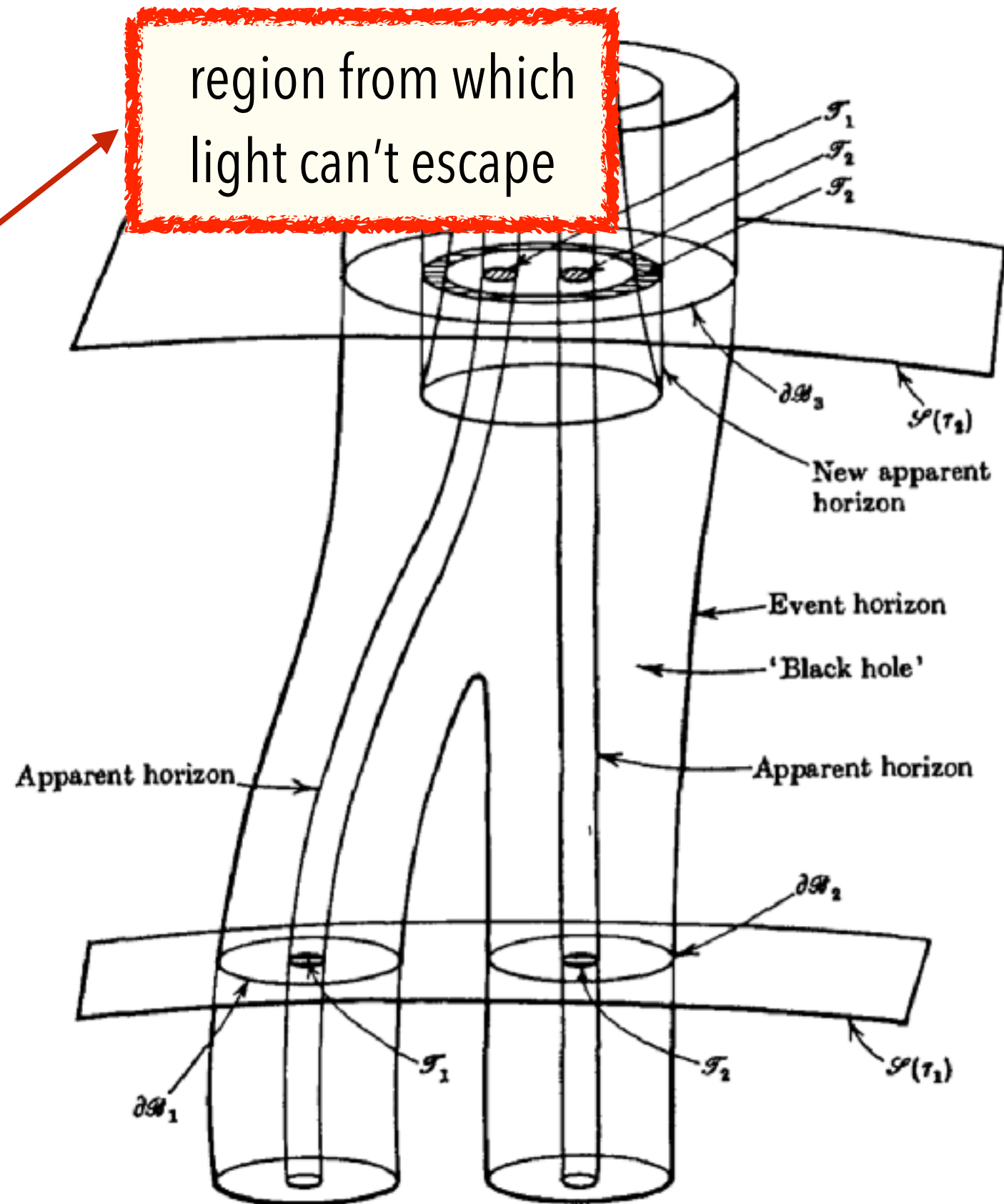
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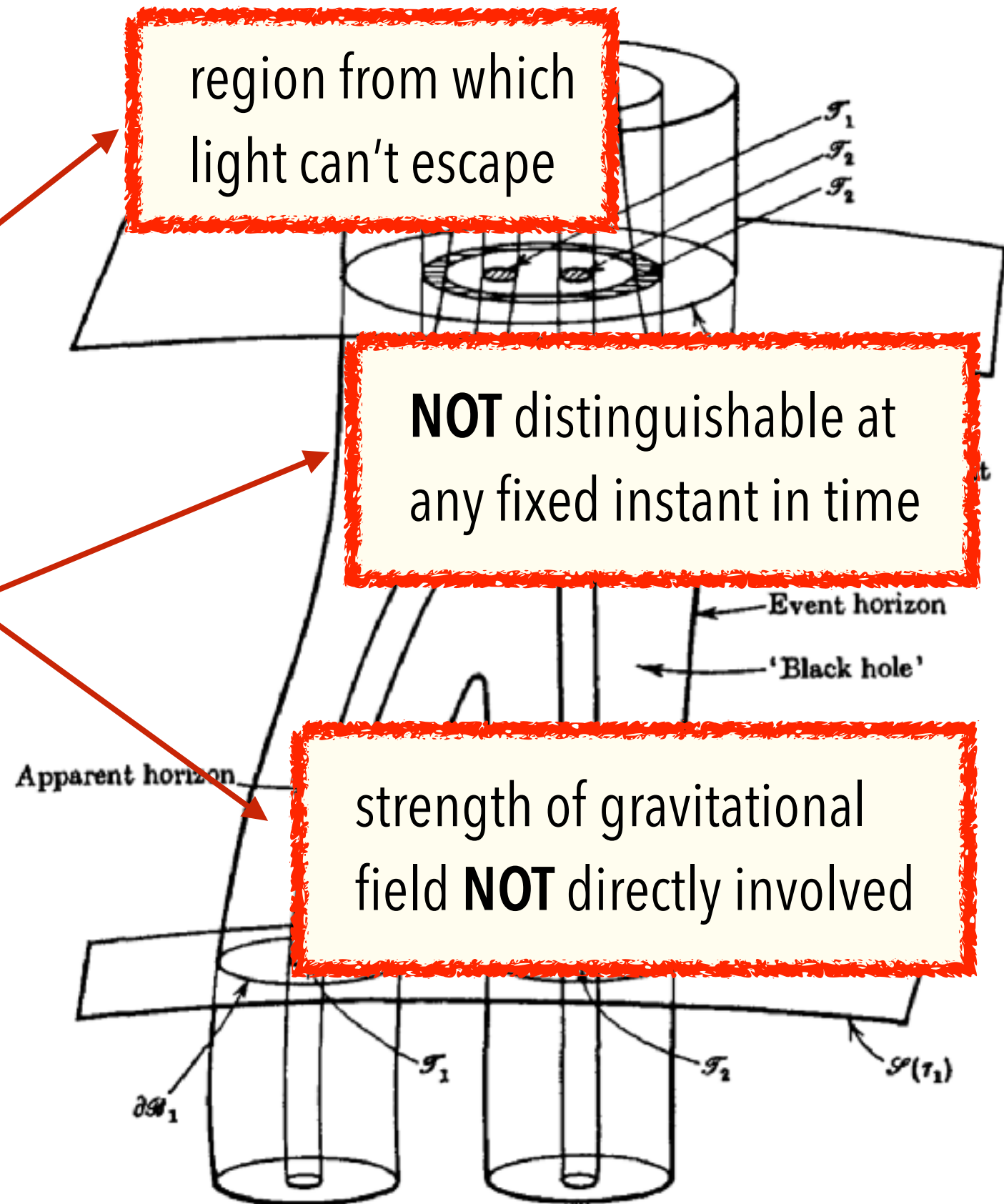
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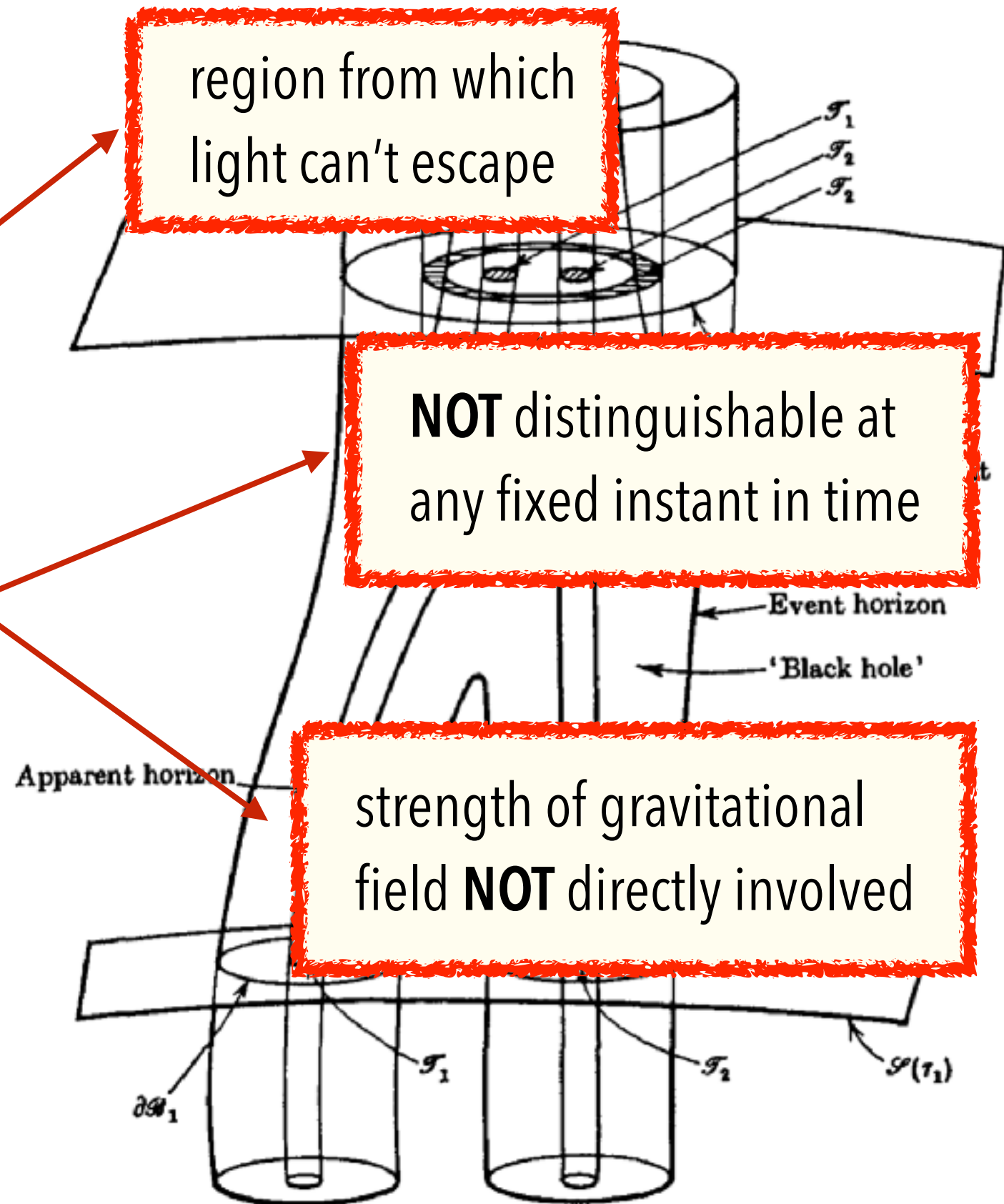
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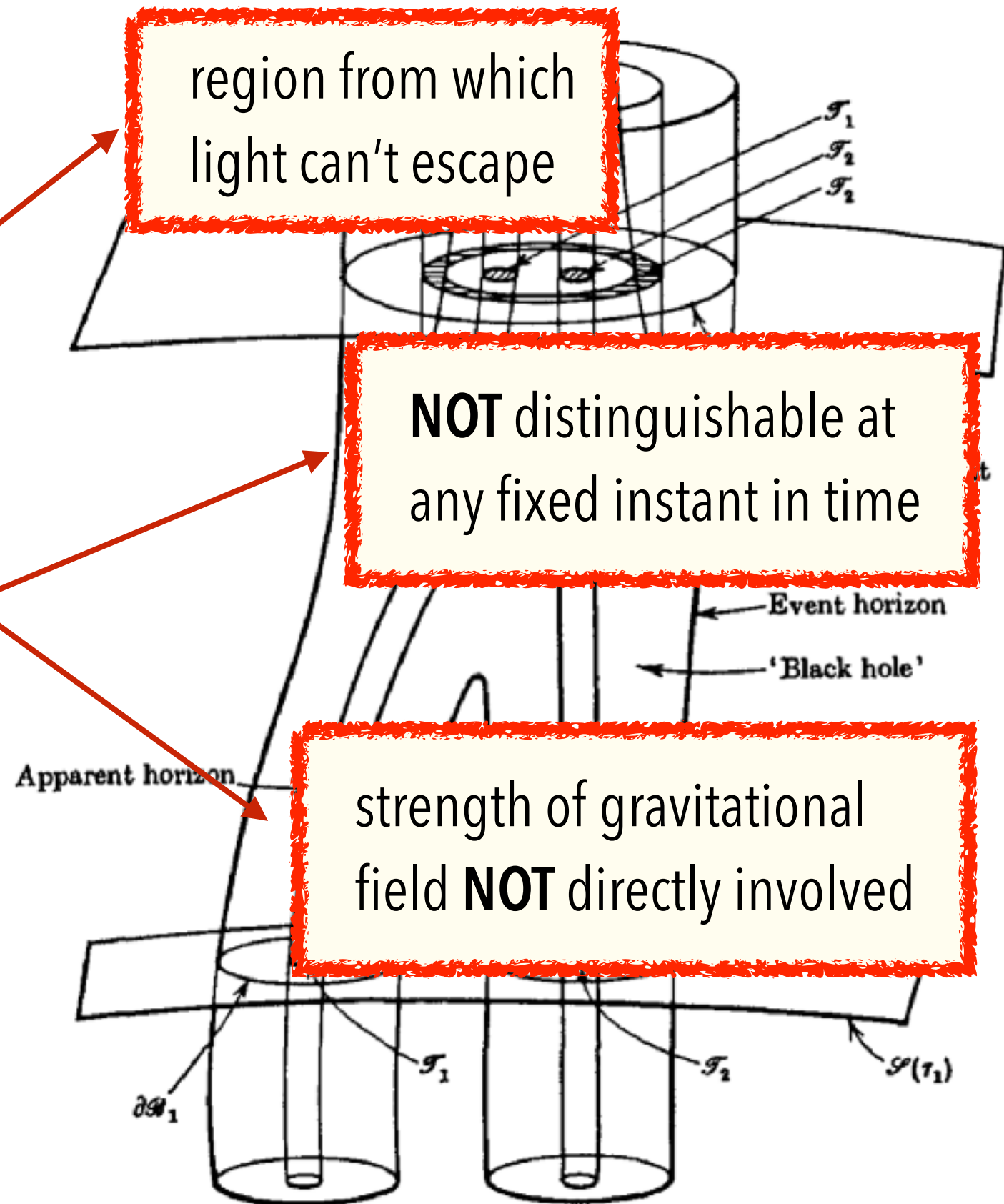
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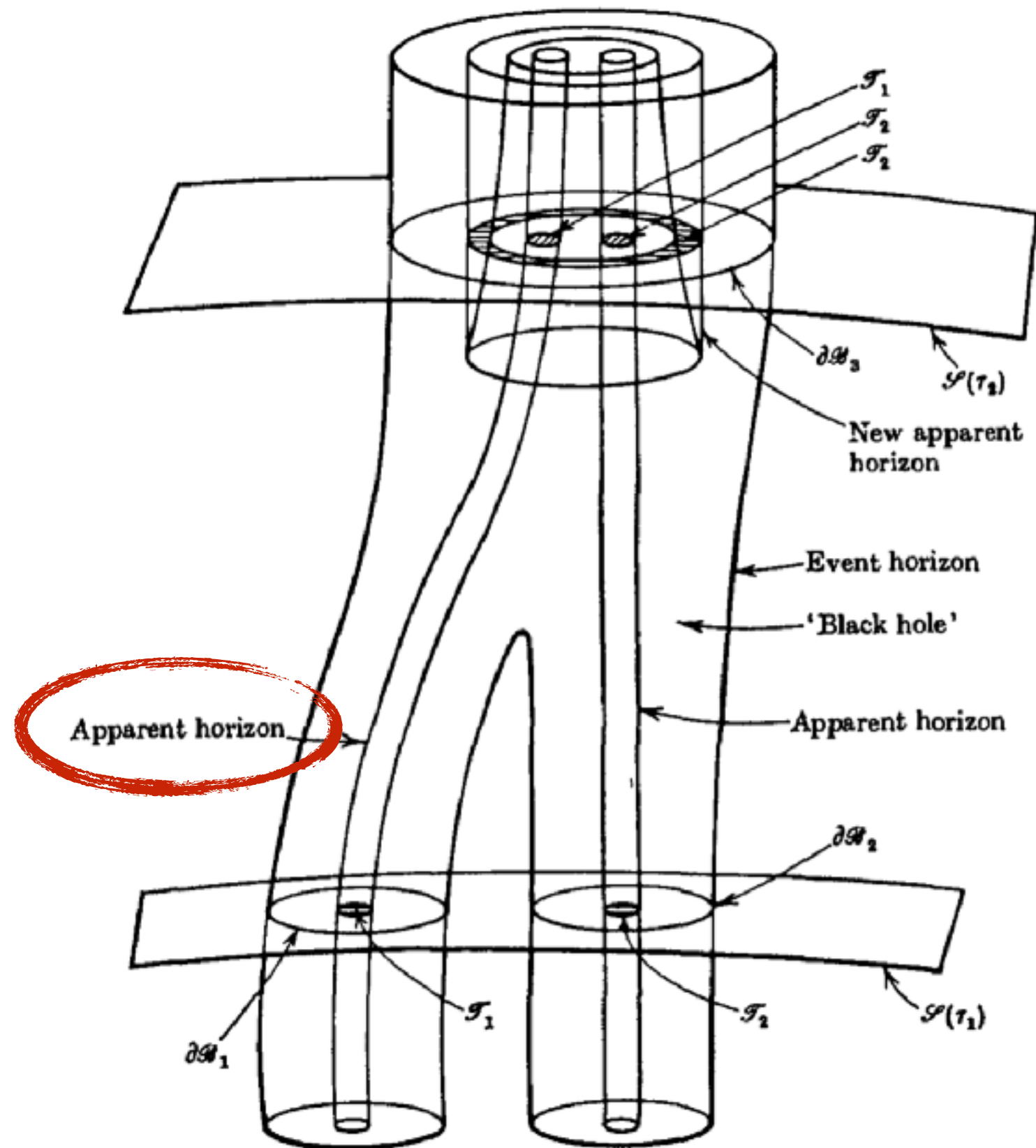
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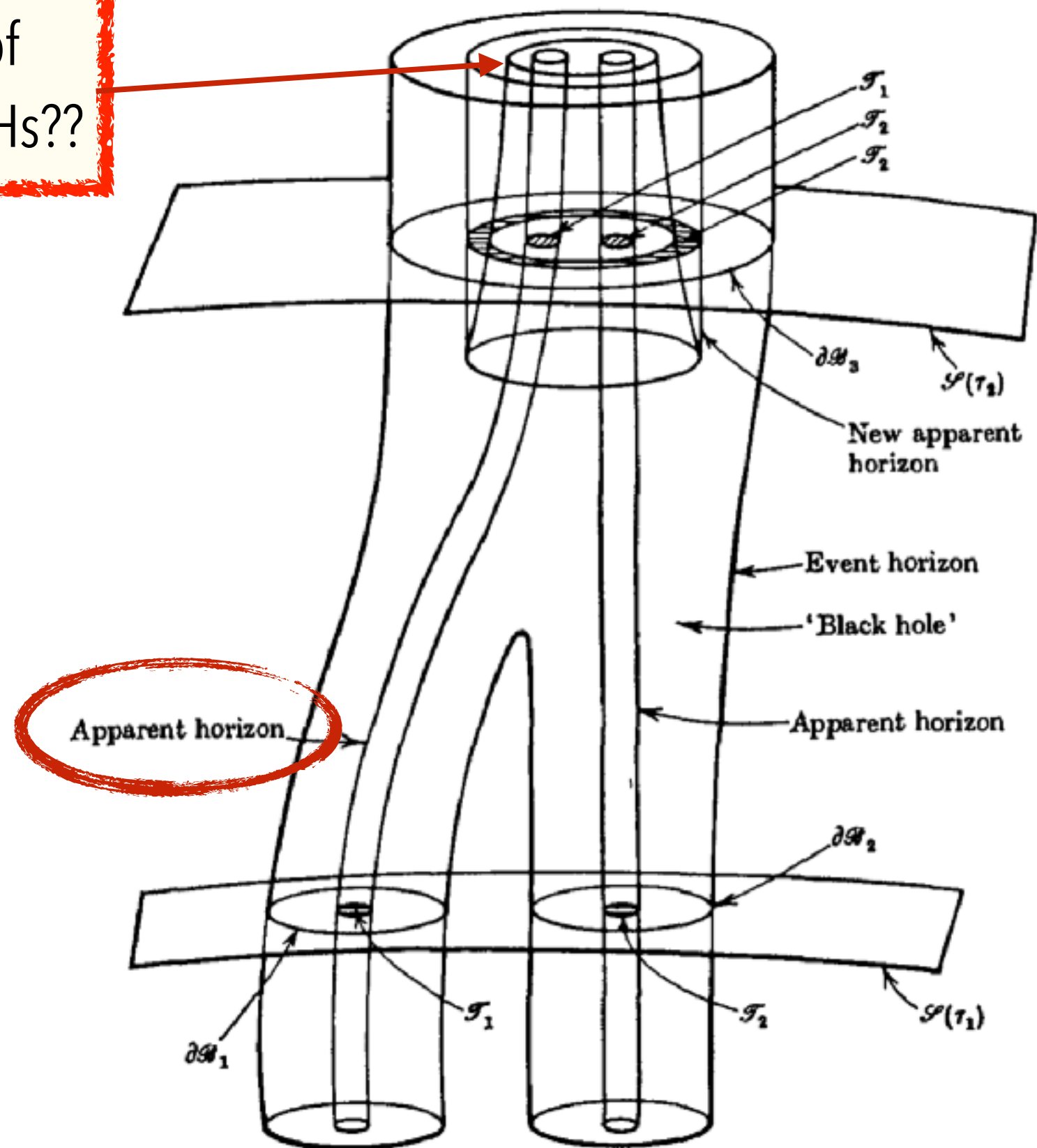


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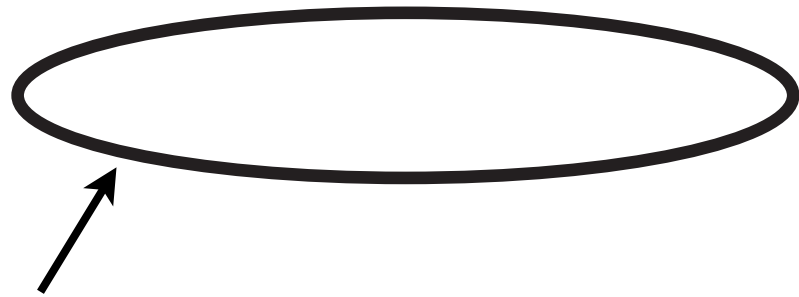
final fate of
original AHs??

Causal black holes

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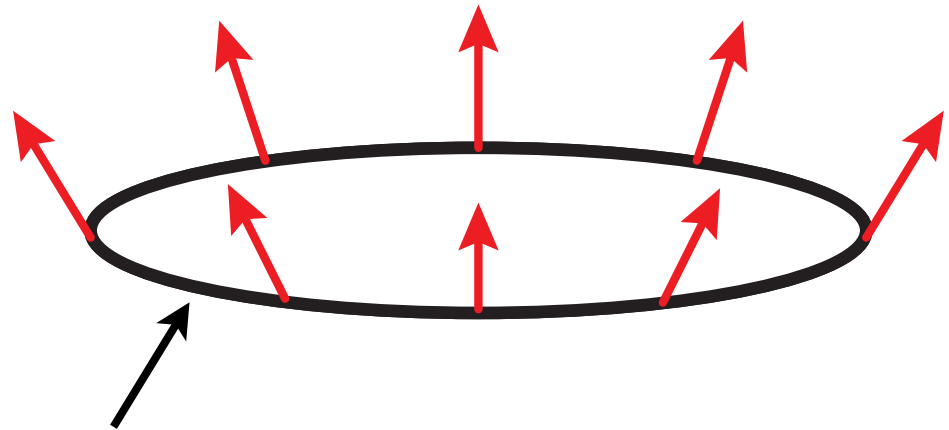


How do you know if you are inside a black hole?



S : spacelike two-surface bounding a three-dimensional region

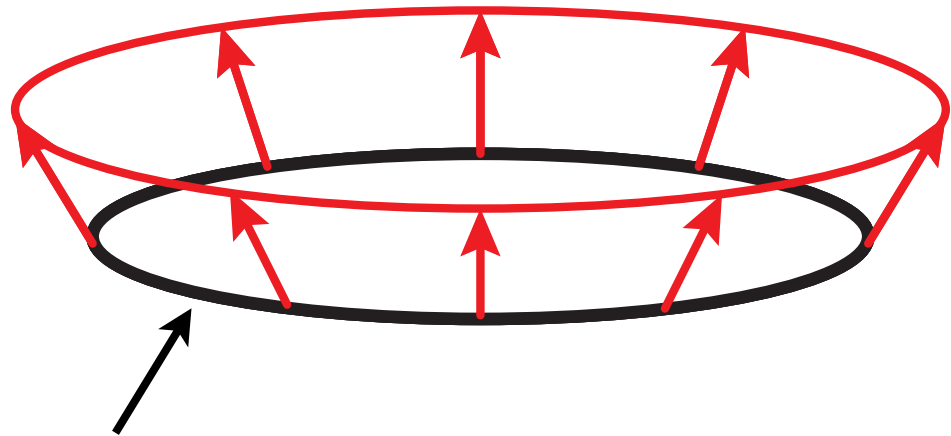
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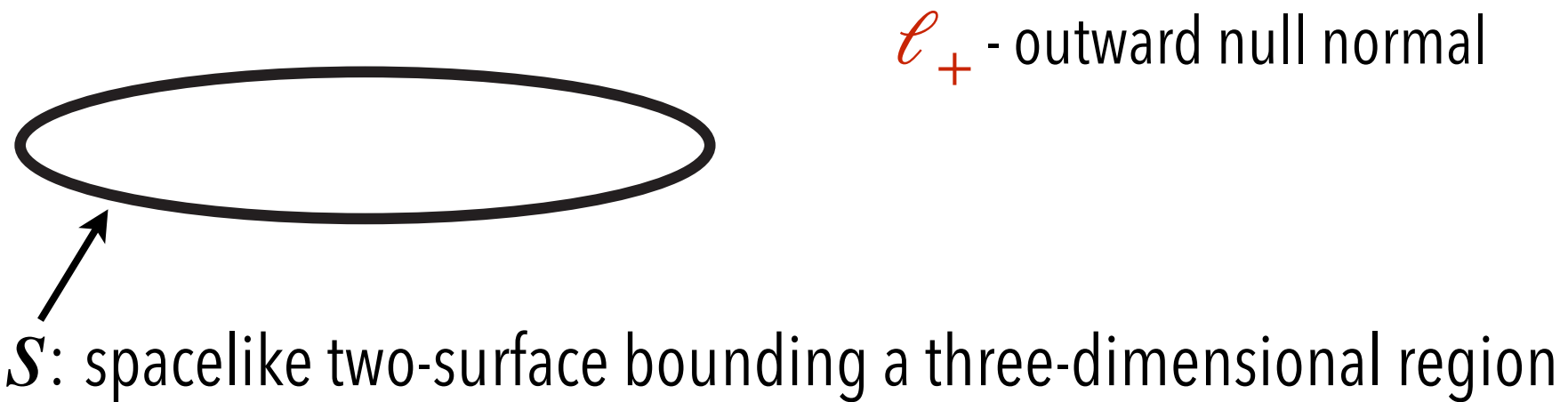


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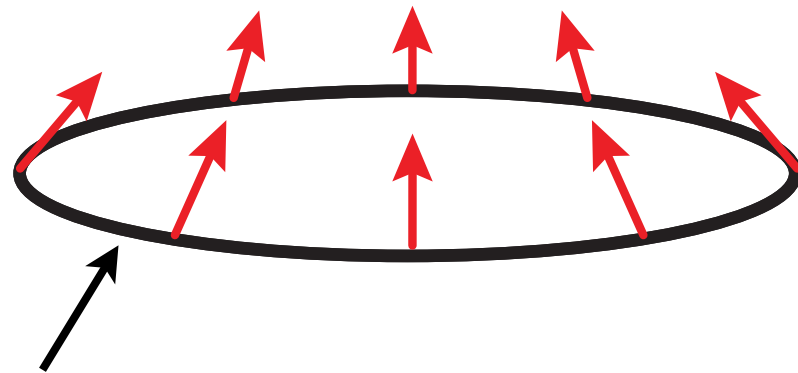
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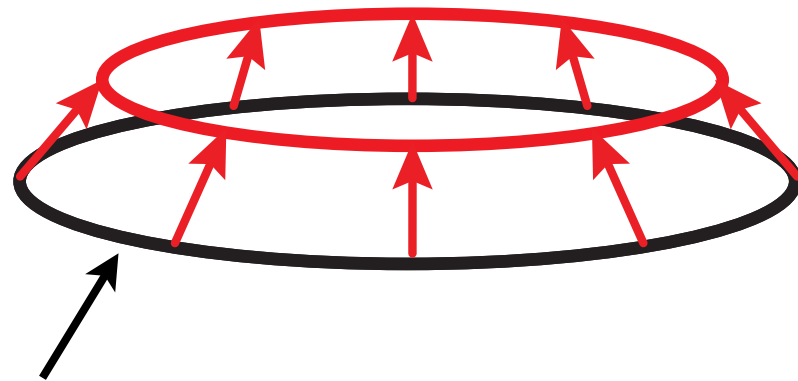


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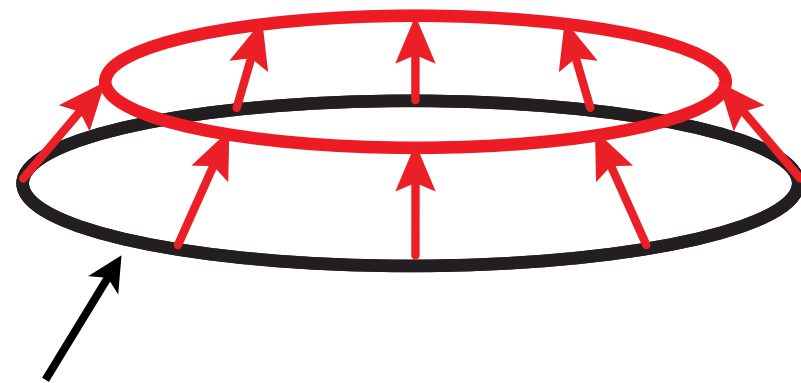
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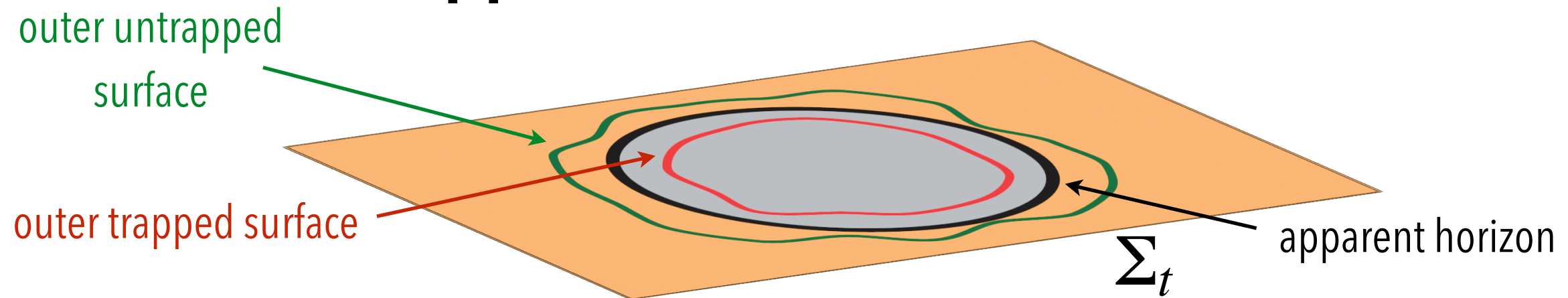
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- Outer trapped surfaces cannot send signals to infinity (Penrose PRL 65)

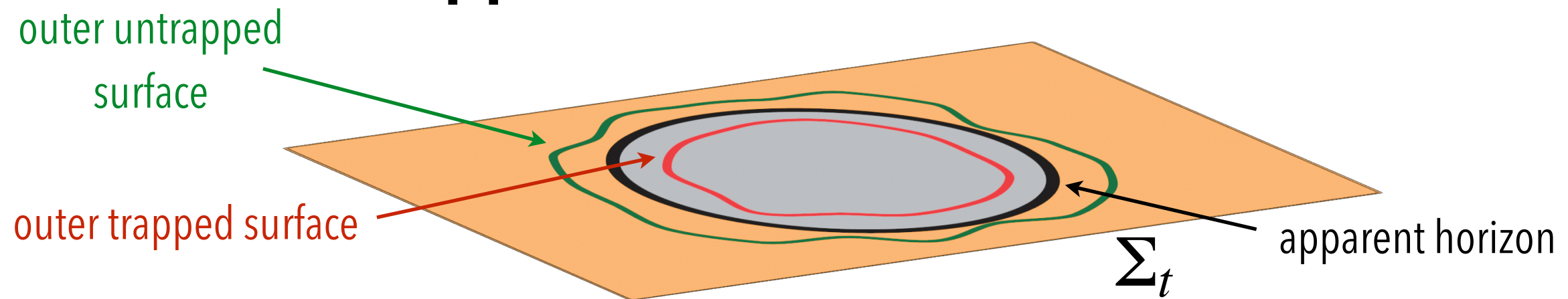
Light cannot escape from an outer trapped surface

Apparent horizons and MOTS

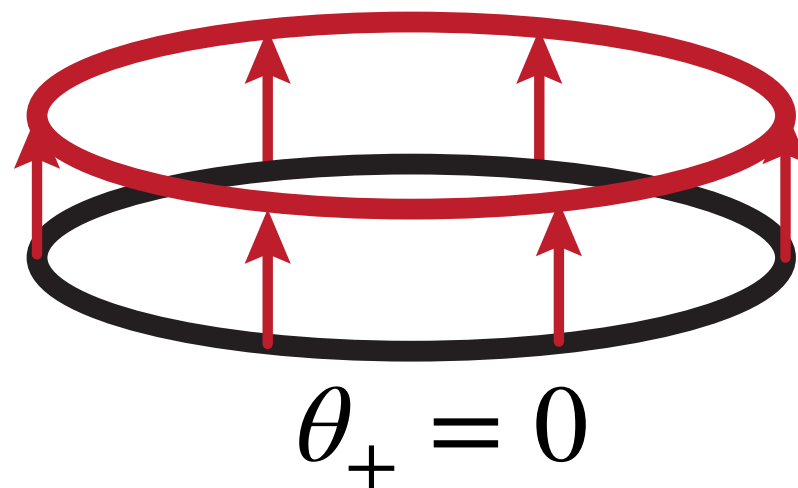


- The *apparent horizon* bounds the (outer) trapped region (outer trapped inside, outer untrapped outside)

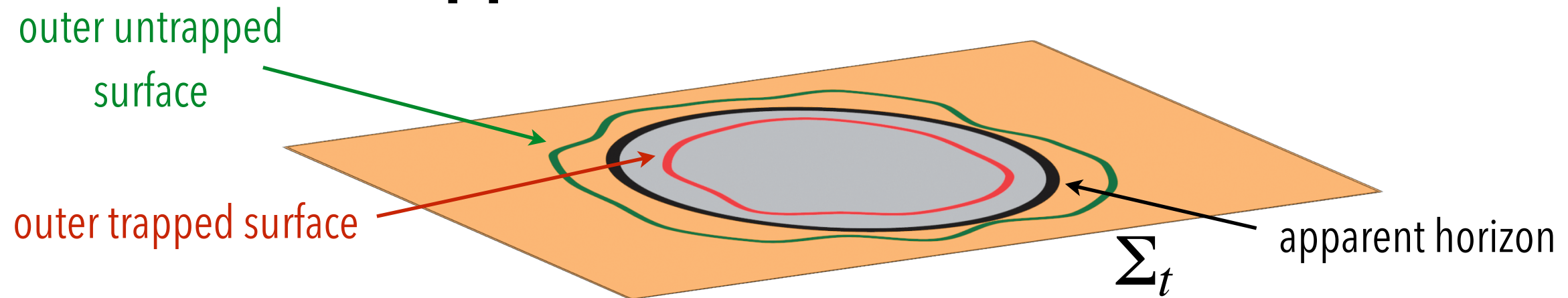
Apparent horizons and MOTS



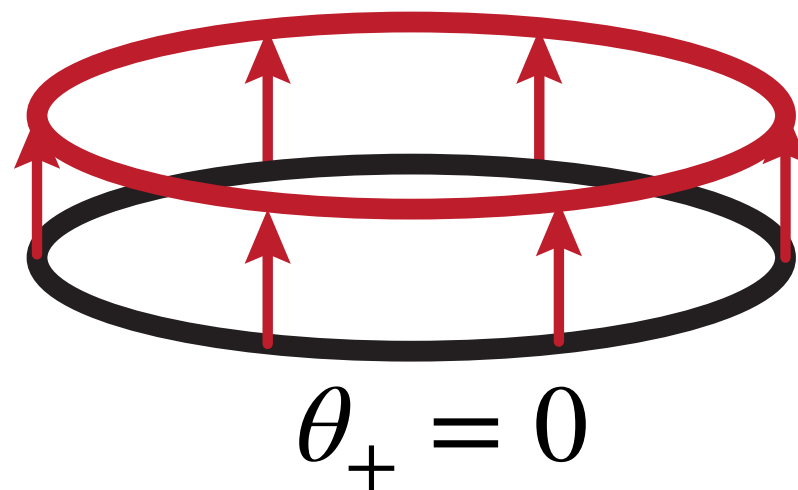
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Apparent horizons and MOTS

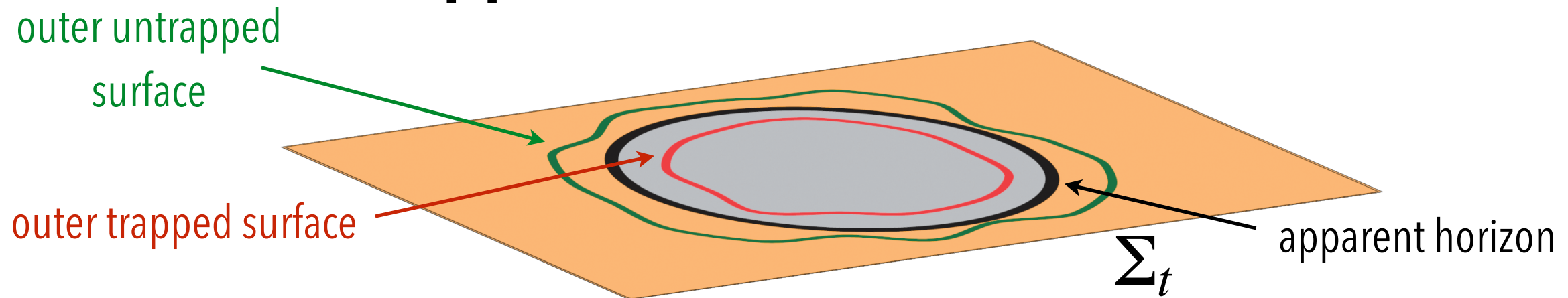


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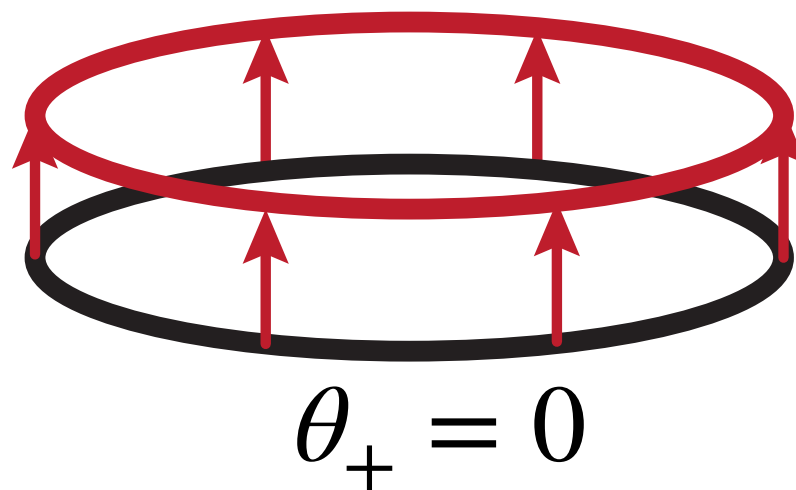


Schwarzschild, RN,
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Apparent horizons and MOTS



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Schwarzschild, RN, Kerr event horizons are MOTS and apparent horizons

RN and Kerr inner horizons as well as cosmo horizons are MOTS

A local characterization of apparent horizons

A MOTS S in a time slice Σ_t is a (local) boundary and *strictly stably outermost* if:

A local characterization of apparent horizons

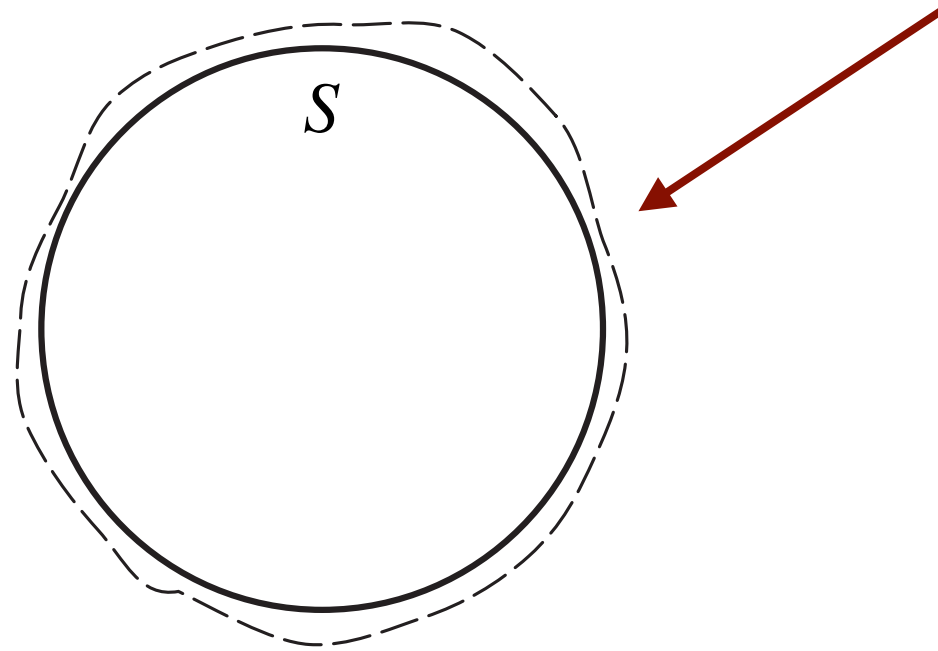
A MOTS S in a time slice Σ_t is a (local) boundary and *strictly stably outermost* if:

- 1) Small outward deformations become *outer untrapped*

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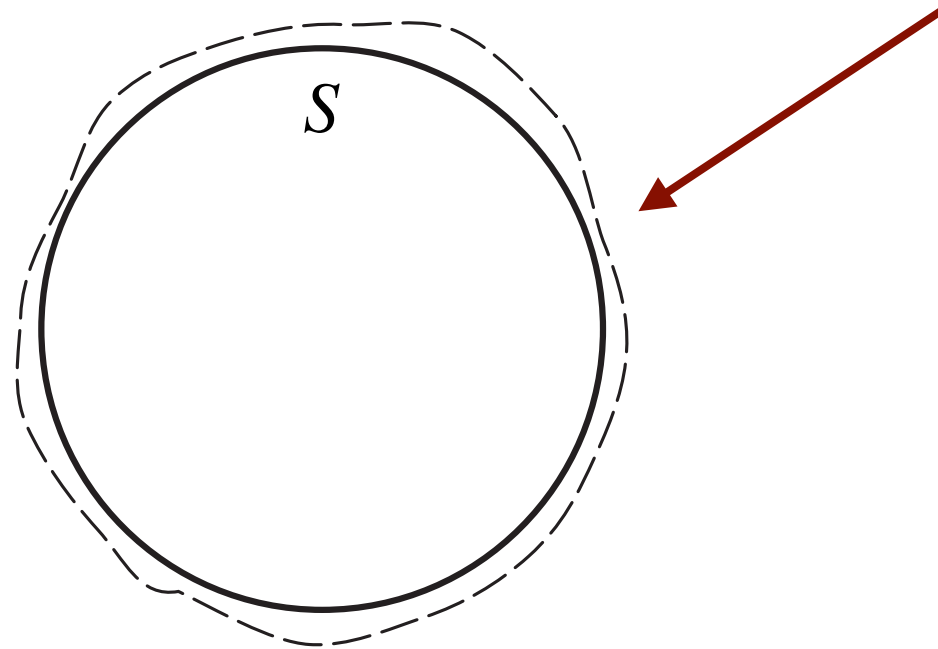
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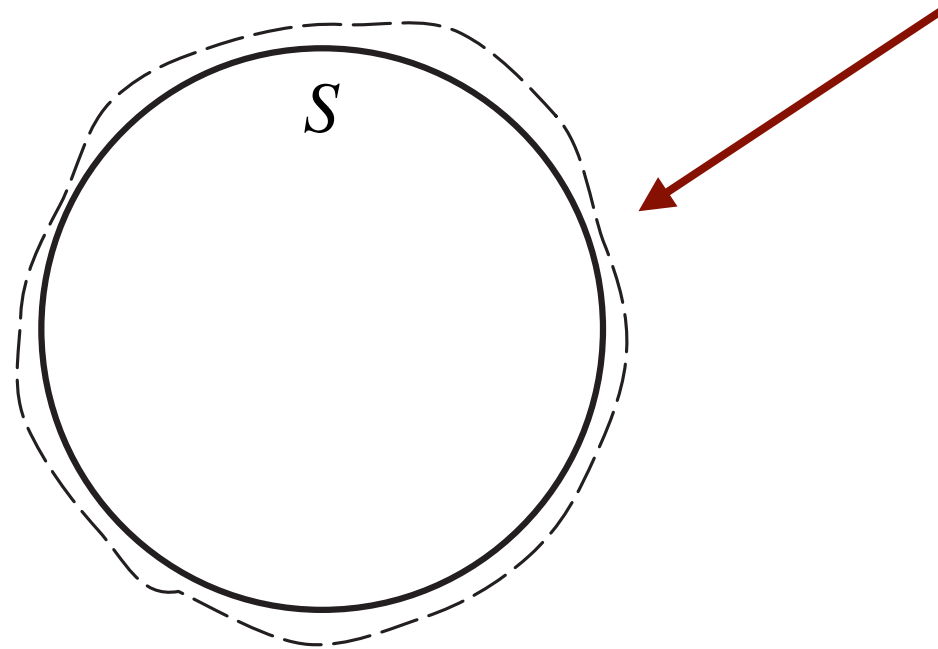


- 2) Small inward deformations become *outer trapped*

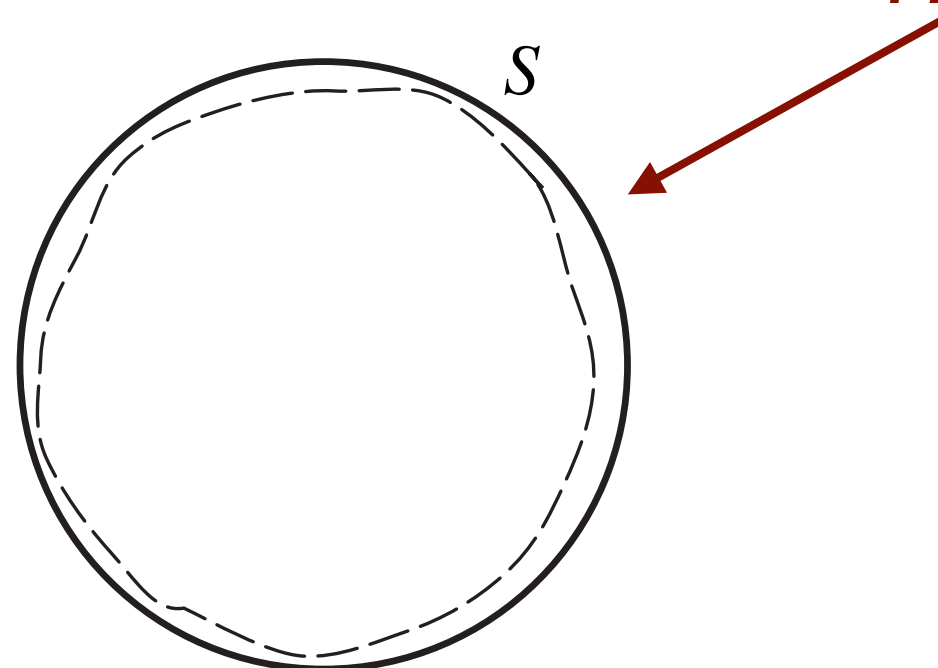
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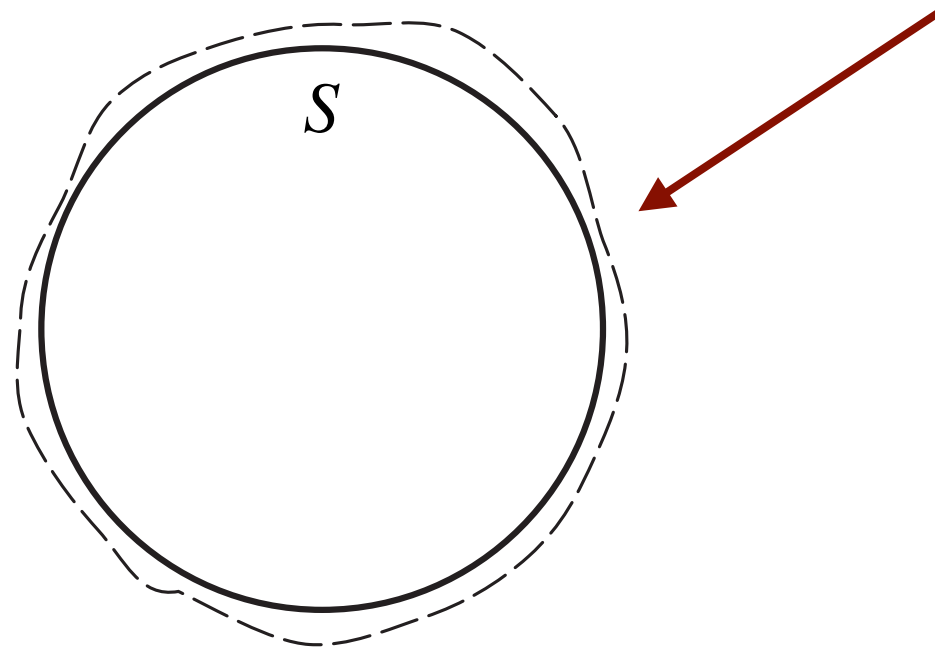
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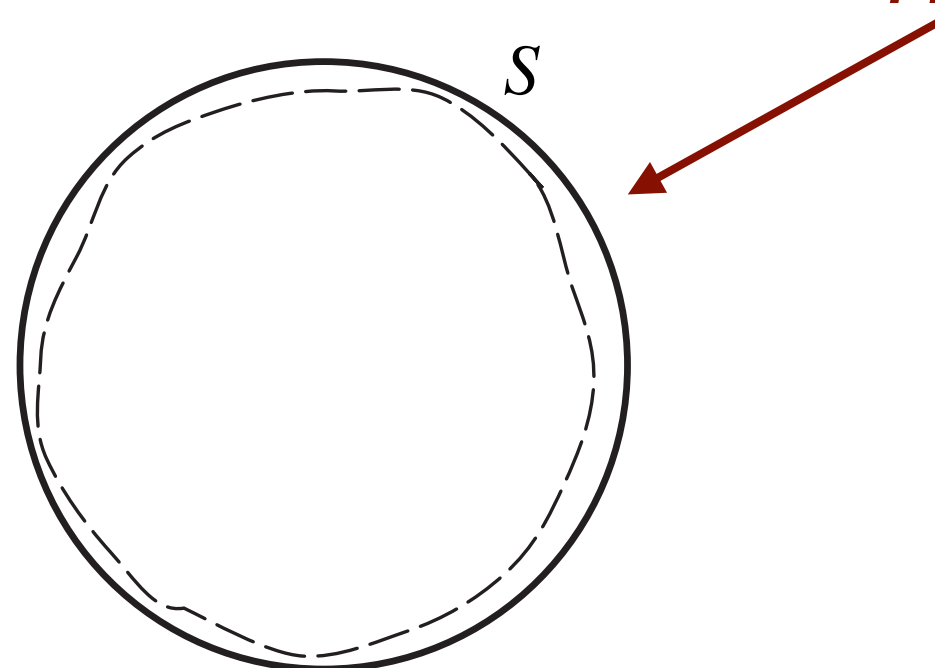
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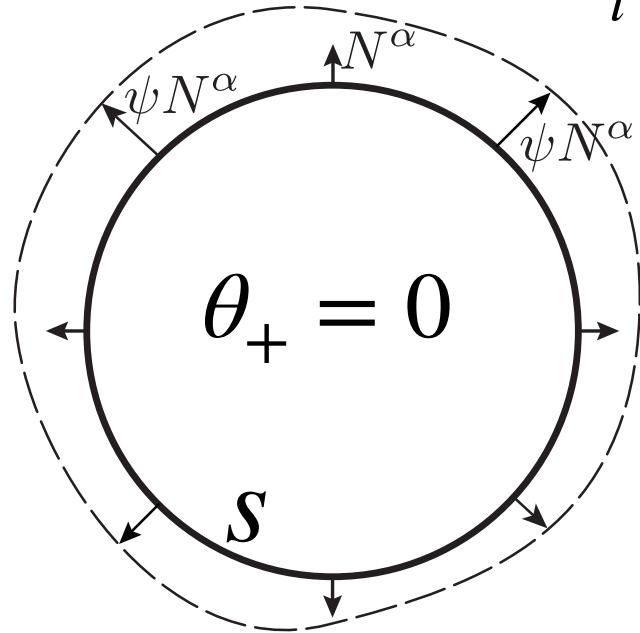


- 2) Small inward deformations become *outer trapped*



3D Stability Operator for (non-rotating) MOTS

- In a time slice Σ_t with N unit normal to S and future outward null $l_+ = u + N$:



variation of
expansion

stability
operator

2D surface
Laplacian

Gauss
curvature

square of
null shear

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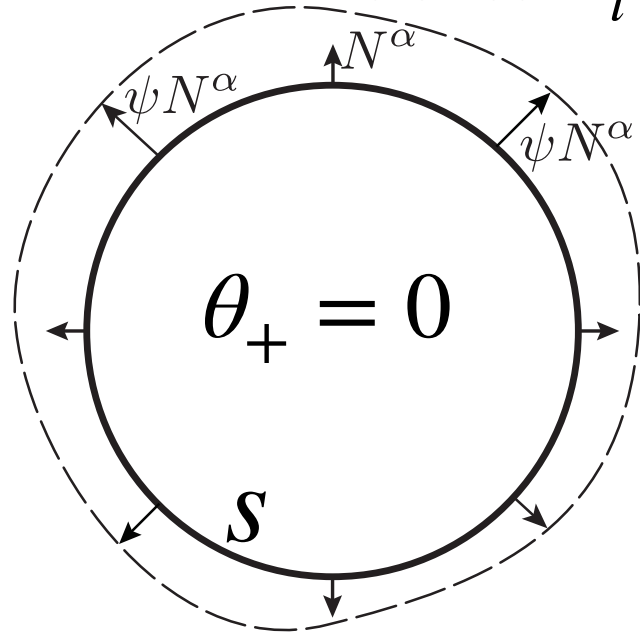
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(Andersson, Mars, Simon, 2005, PRL 111102)

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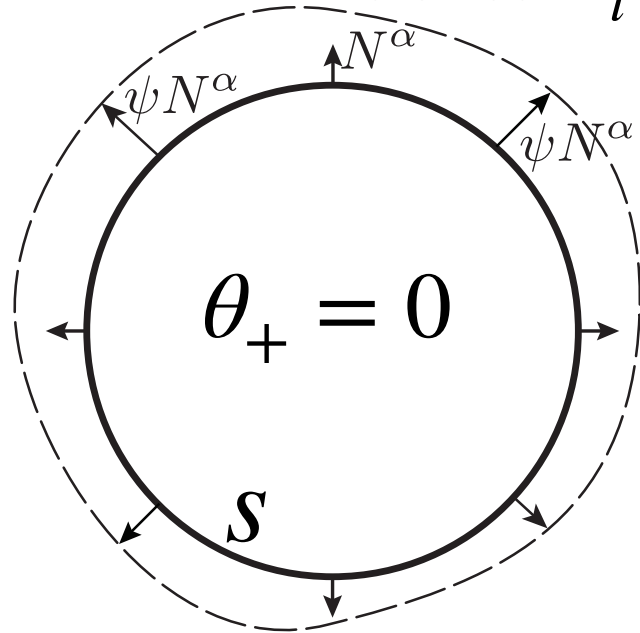
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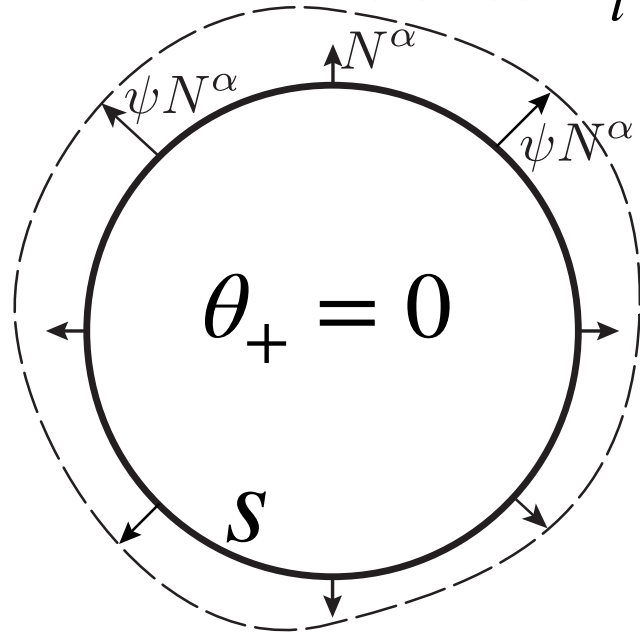
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variation of expansion stability operator 2D surface Laplacian Gauss curvature square of null shear matter term

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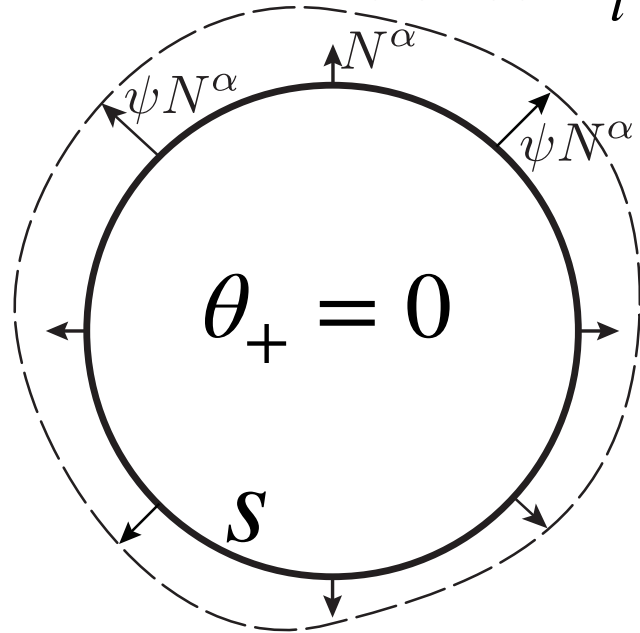
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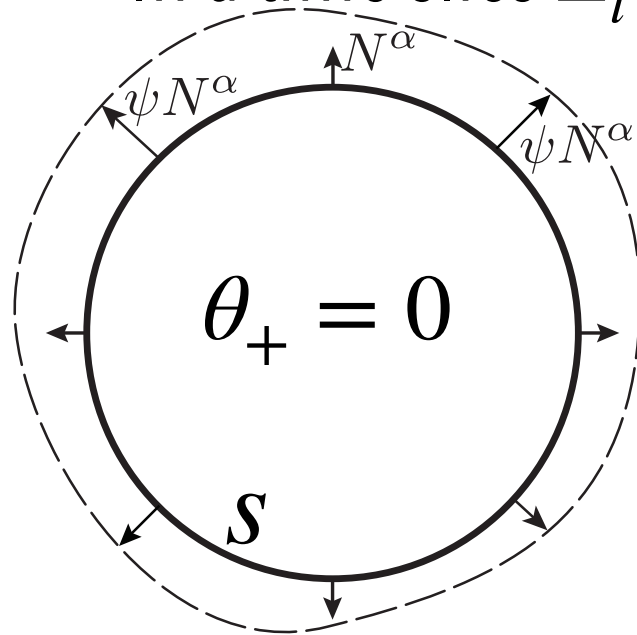
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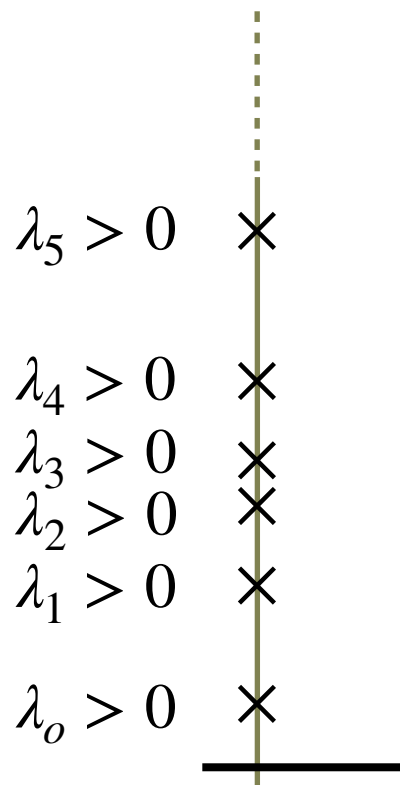
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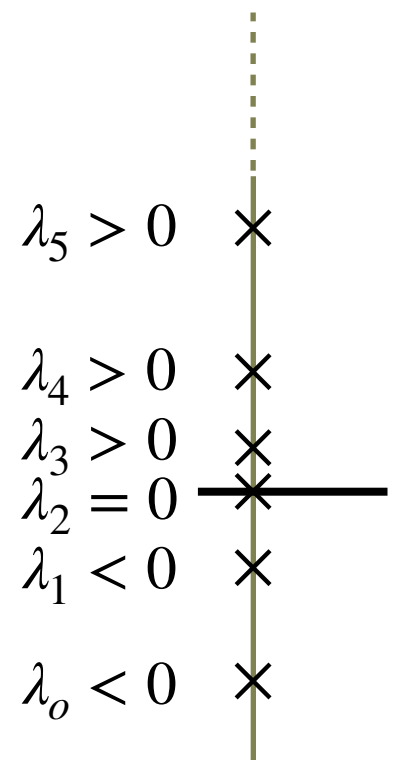
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- Strictly stable: all eigenvalues positive

Unstable: one or more negative eigenvalues

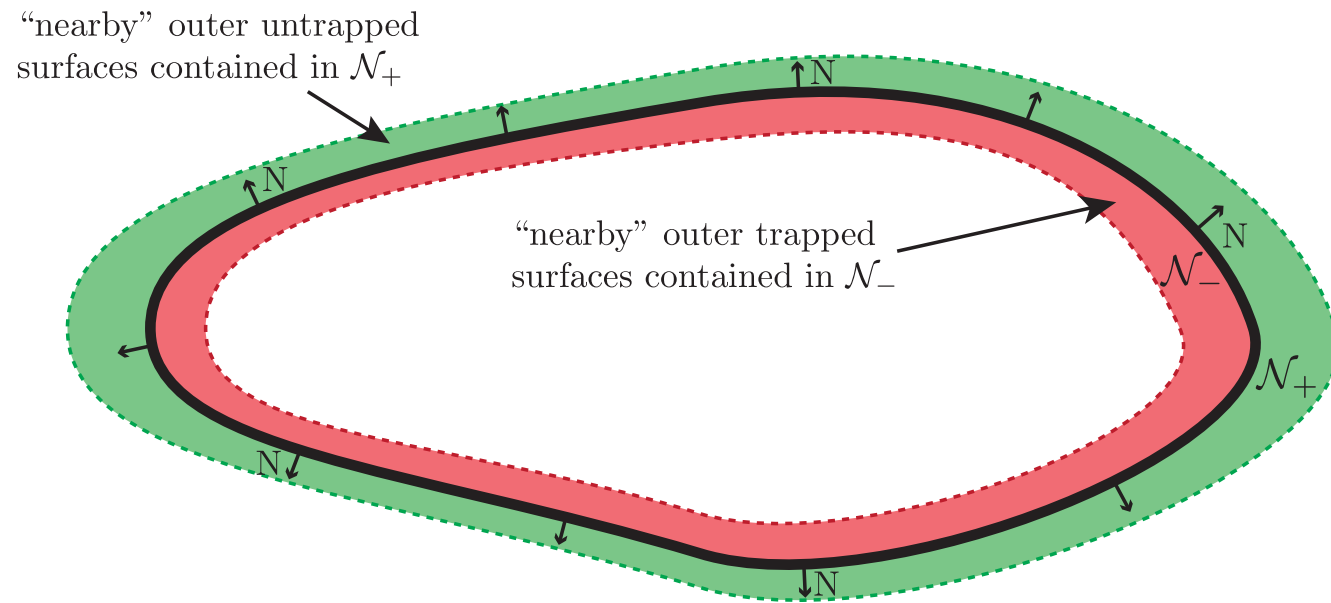


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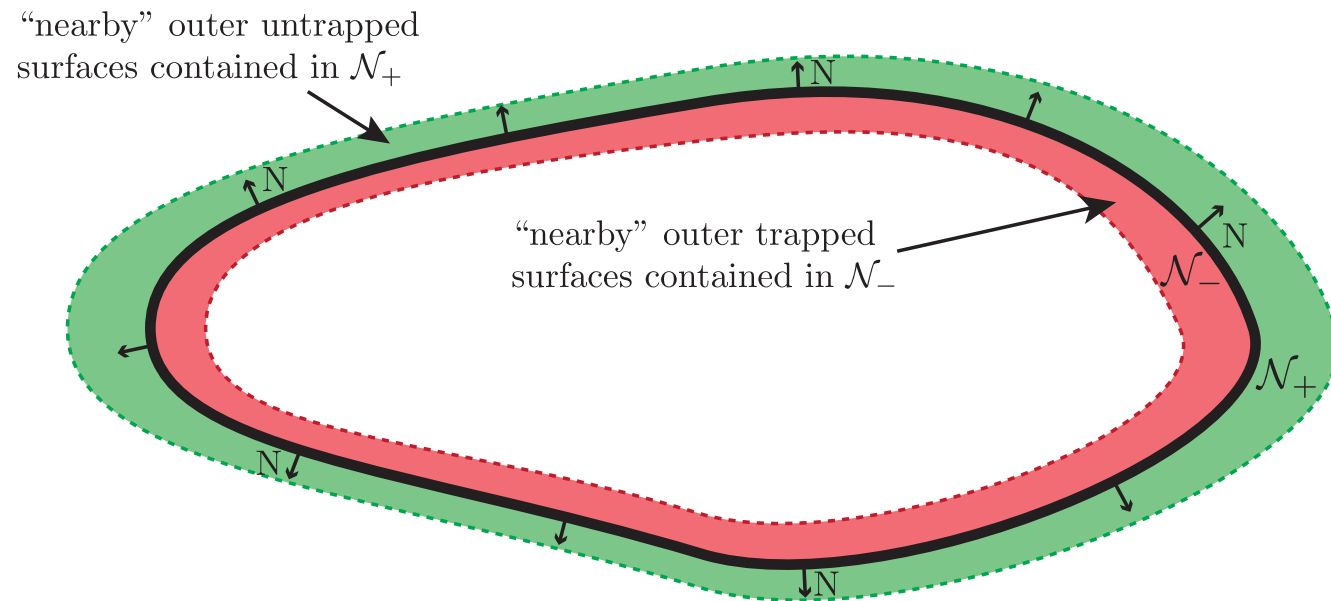
Unstable

Stability: MOTSs as local boundaries

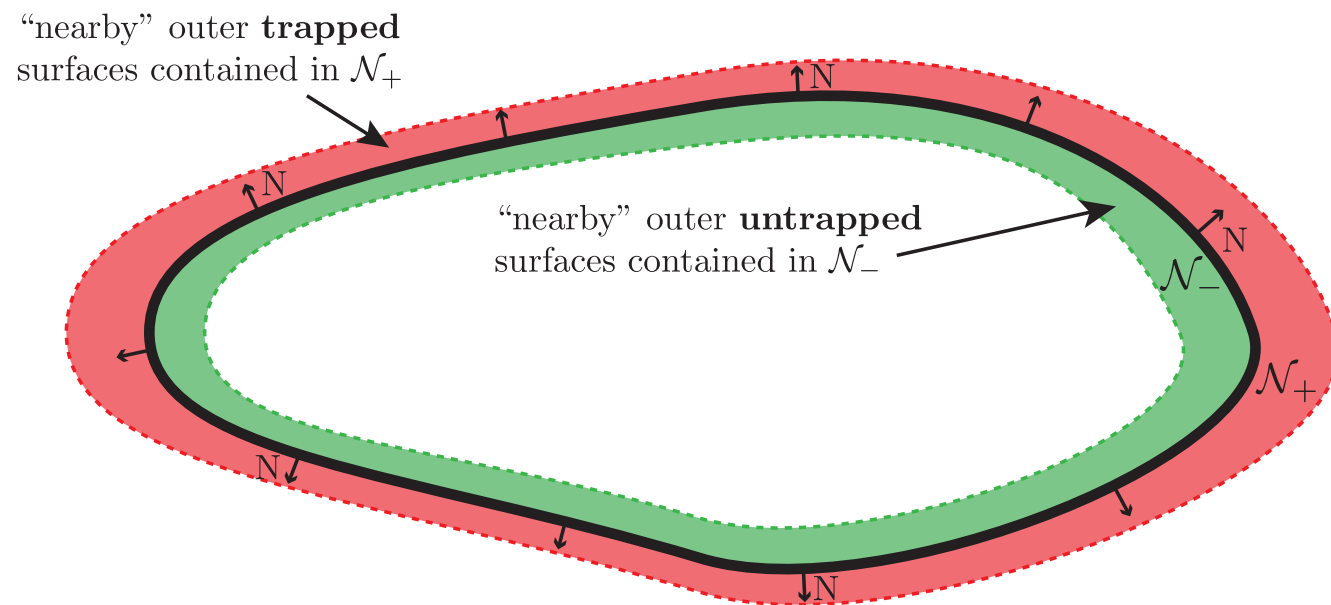


Strictly stable ($\lambda_o > 0$)
 $\Rightarrow$ outer untrapped outside,
outer trapped inside
Local apparent horizon

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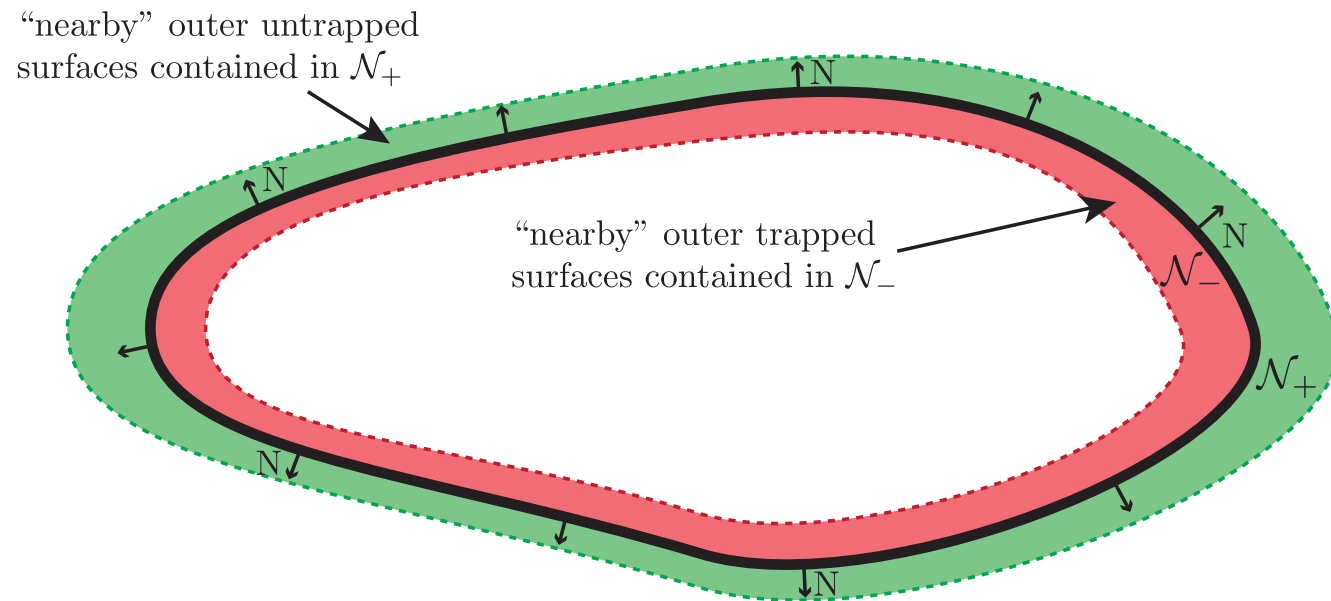
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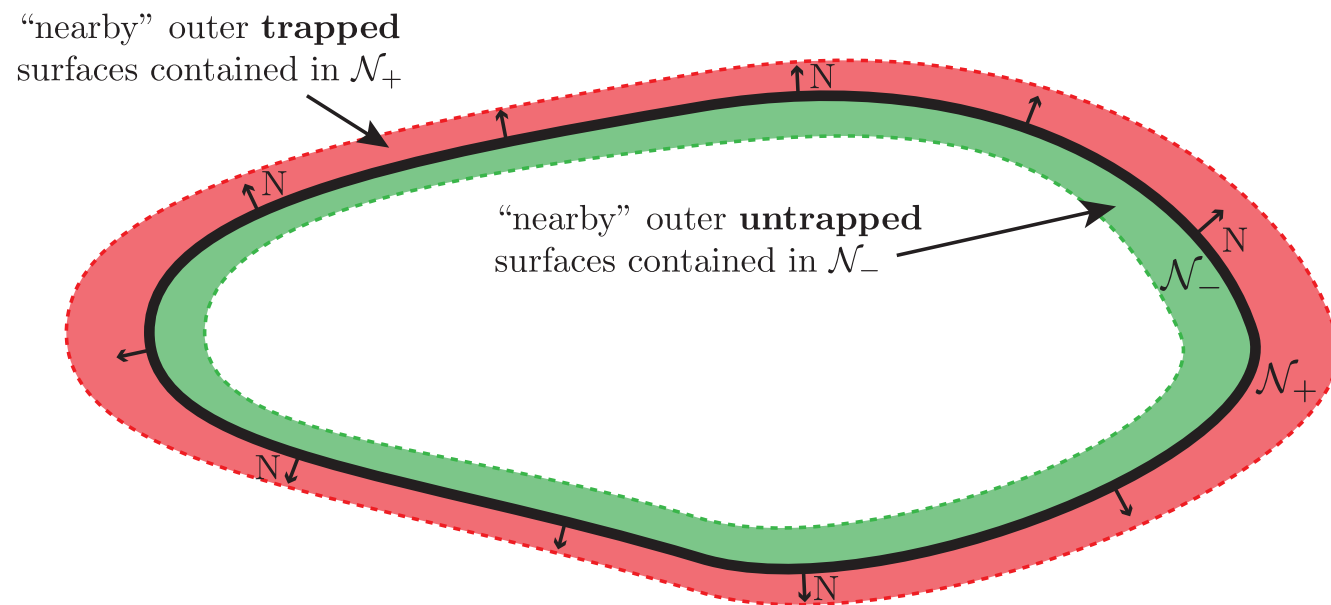
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Local inner horizon

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Strictly stable MOTS separates trapped from untrapped regions (distinguishable)

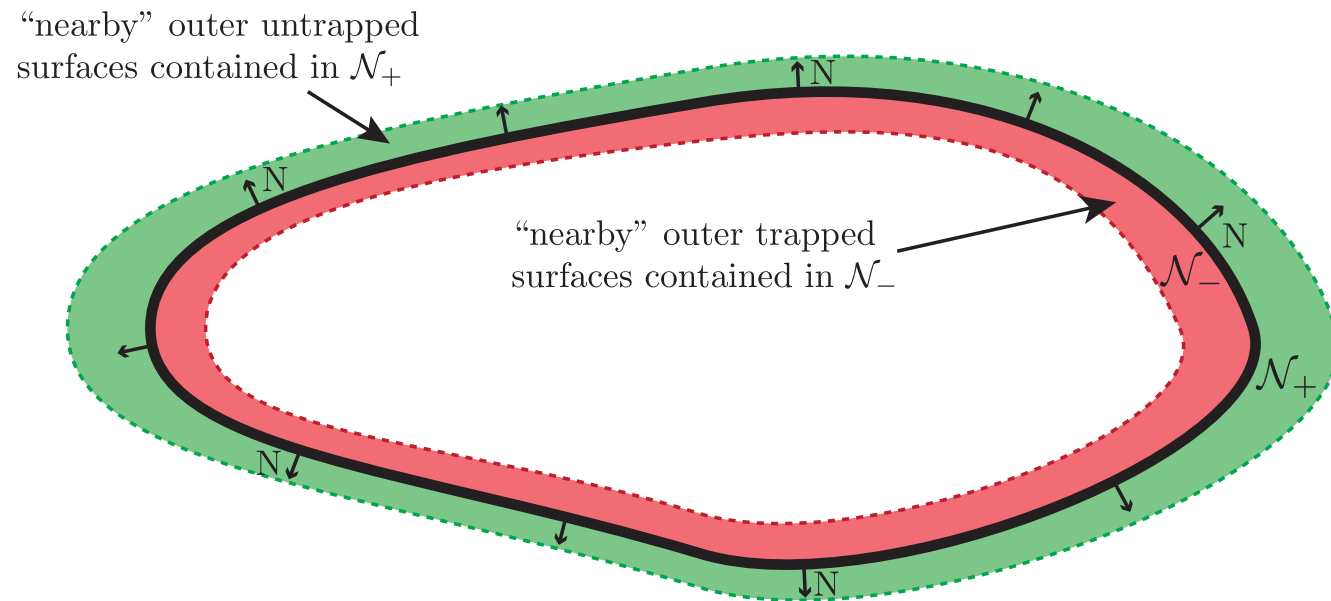


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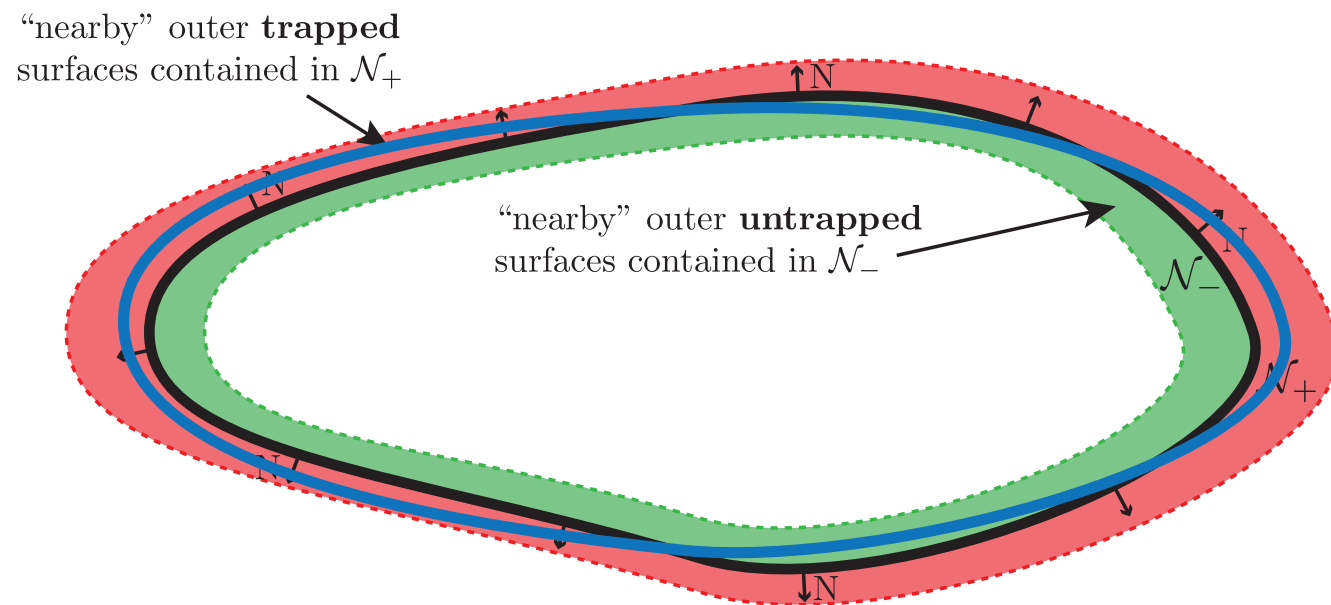
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Local inner horizon

Stability: MOTSs as local boundaries



Strictly stable MOTS separates trapped from untrapped regions (distinguishable)



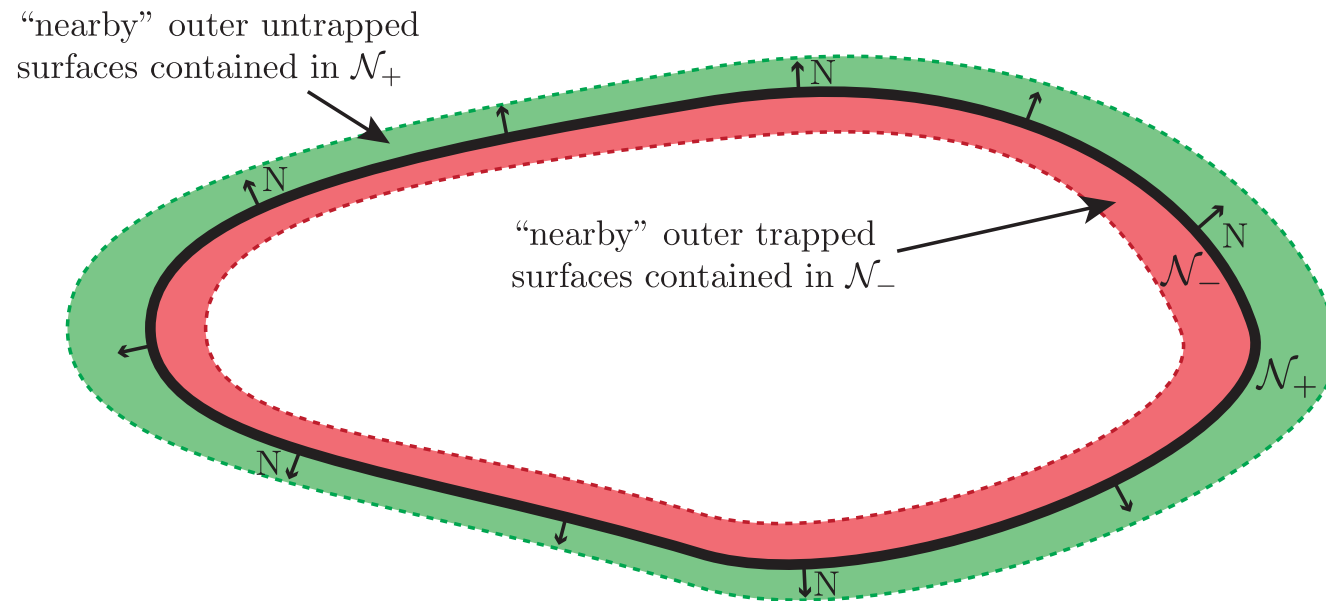
Strictly unstable ($\lambda_o < 0$)

$\Rightarrow$ outer trapped outside,
outer untrapped inside

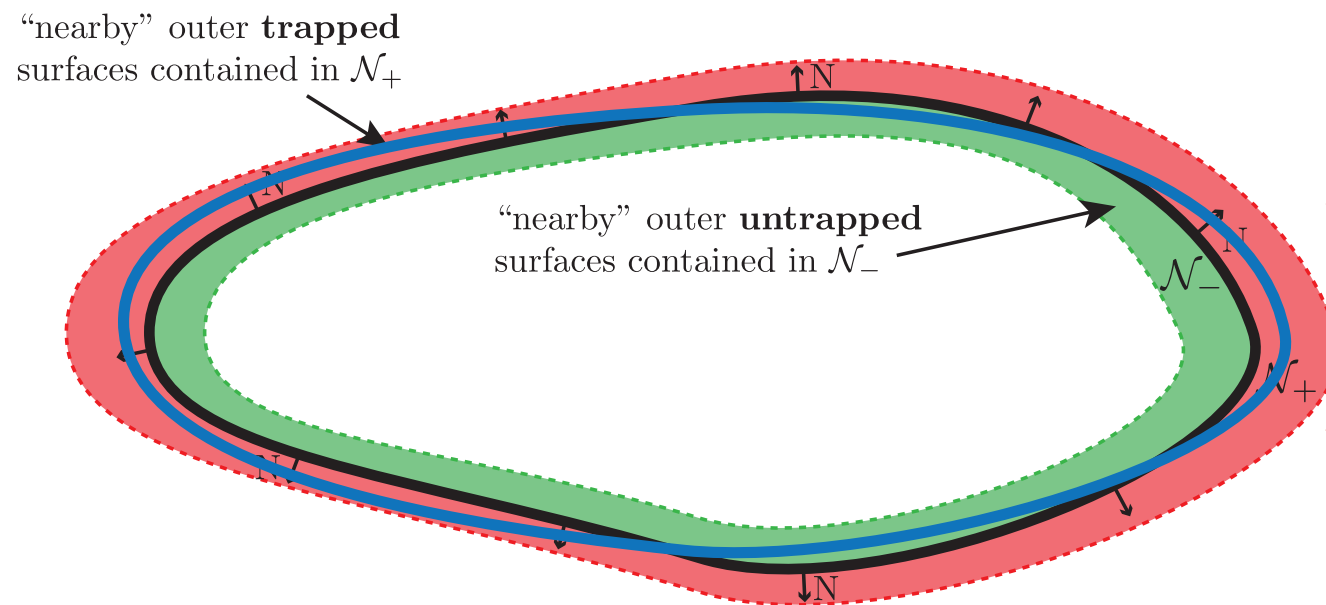
$\Rightarrow$ trapped and untrapped
can also **straddle** MOTS

Local inner horizon

Stability: MOTSs as local boundaries



Strictly stable MOTS separates trapped from untrapped regions (distinguishable)

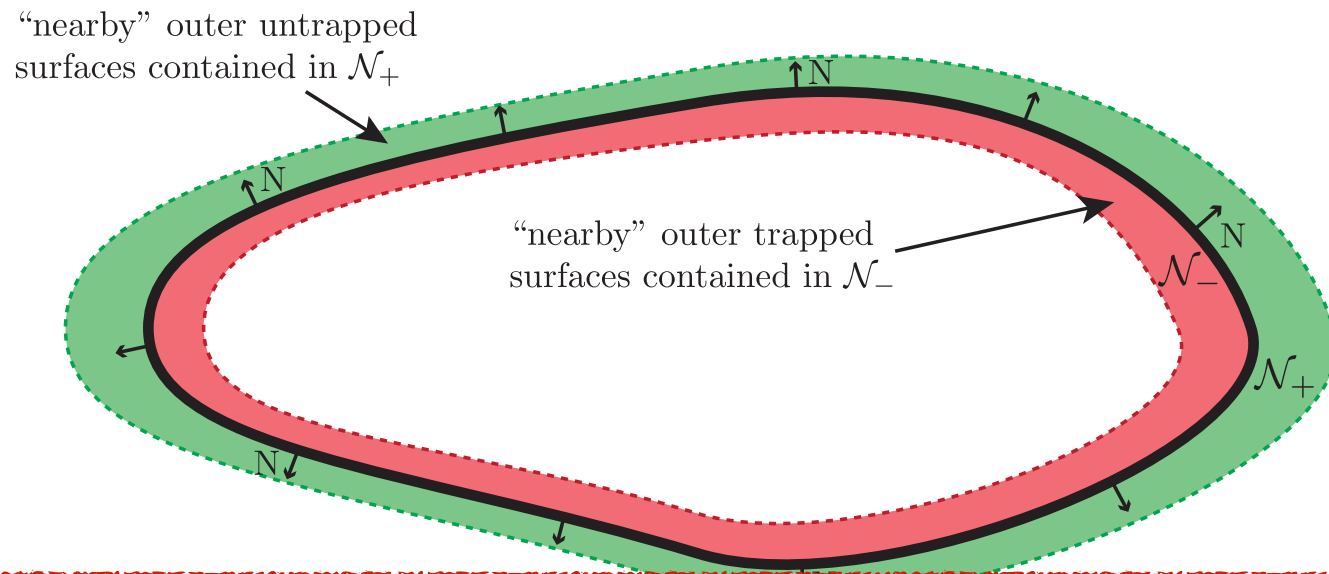


Strictly unstable ($\lambda_o < 0$)

$\Rightarrow$ outer trapped outside,

Unstable MOTS doesn't fully separate trapped from untrapped regions (distinguishable)

Stability: MOTSs as local boundaries



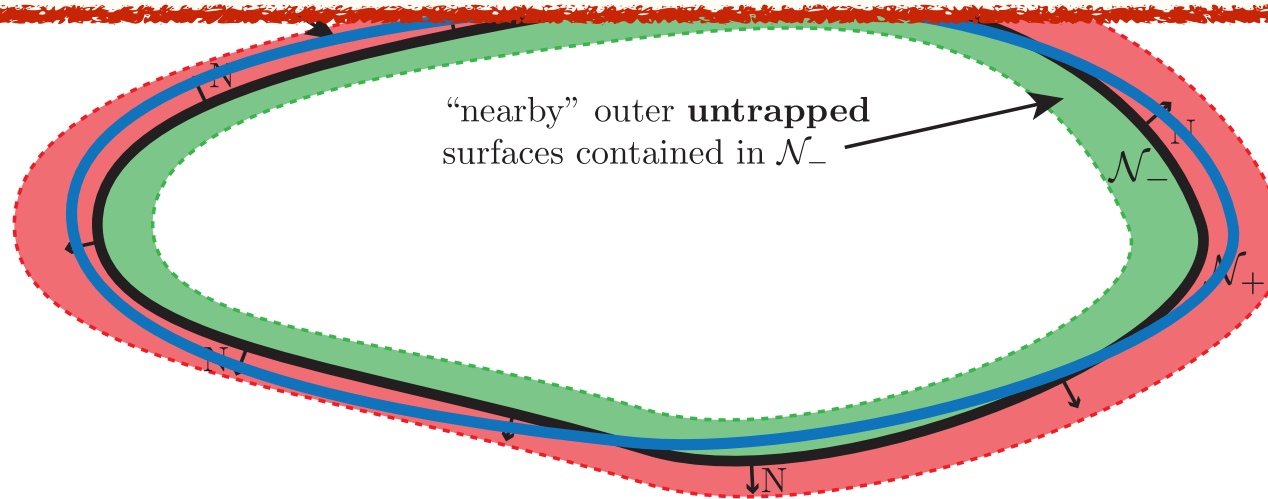
Strictly stable MOTS separates trapped from untrapped regions (distinguishable)

Canonical Example: Reissner-Nordström

Outer horizon $r_{\text{OH}} = m + \sqrt{m^2 - q^2}$: strictly stable

Inner horizon $r_{\text{IH}} = m - \sqrt{m^2 - q^2}$: strictly unstable stable ($\lambda_o < 0$)

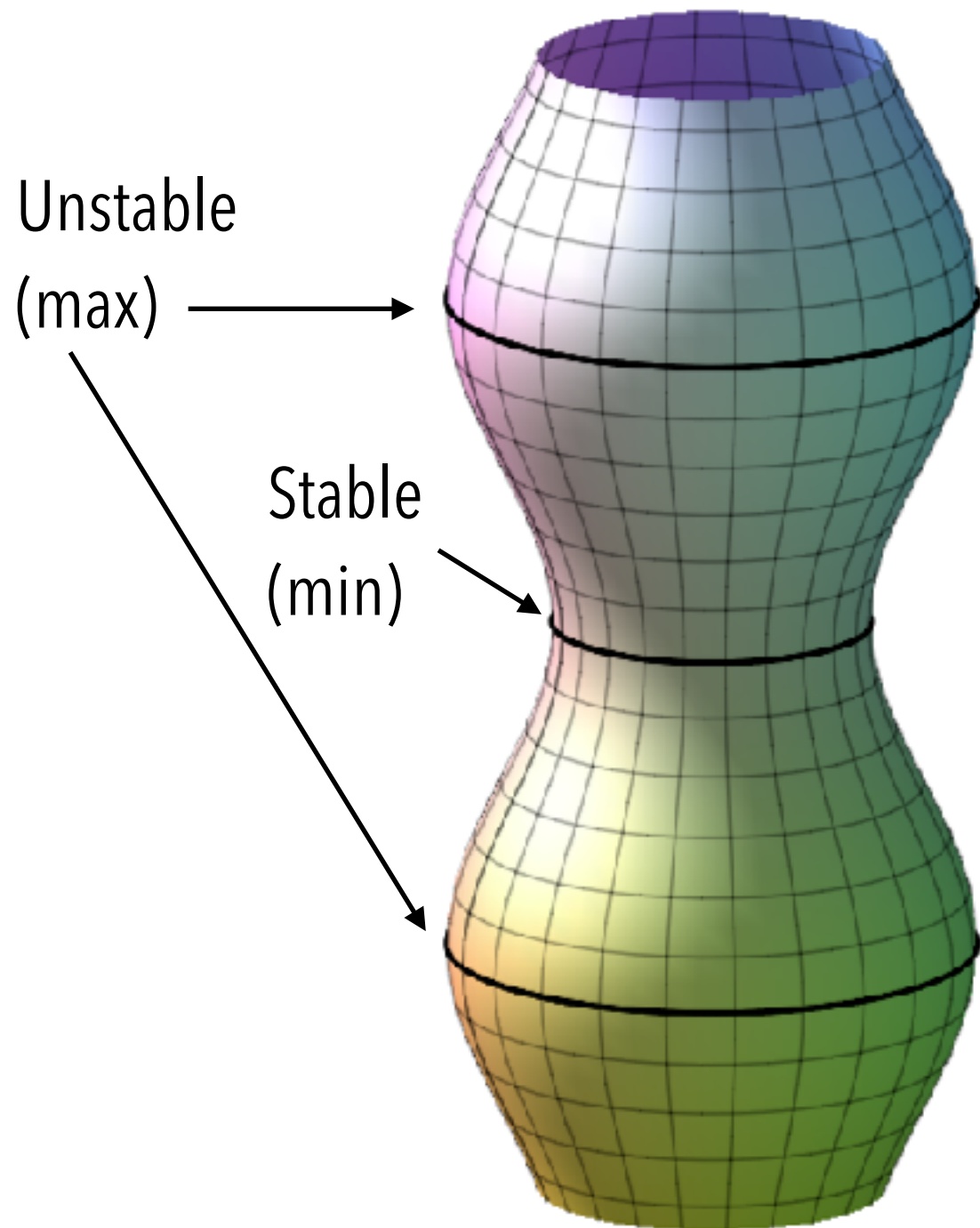
→ outer trapped outside,



Unstable MOTS doesn't fully separate trapped from untrapped regions(distinguishable)

An aside... What does "stable" mean?

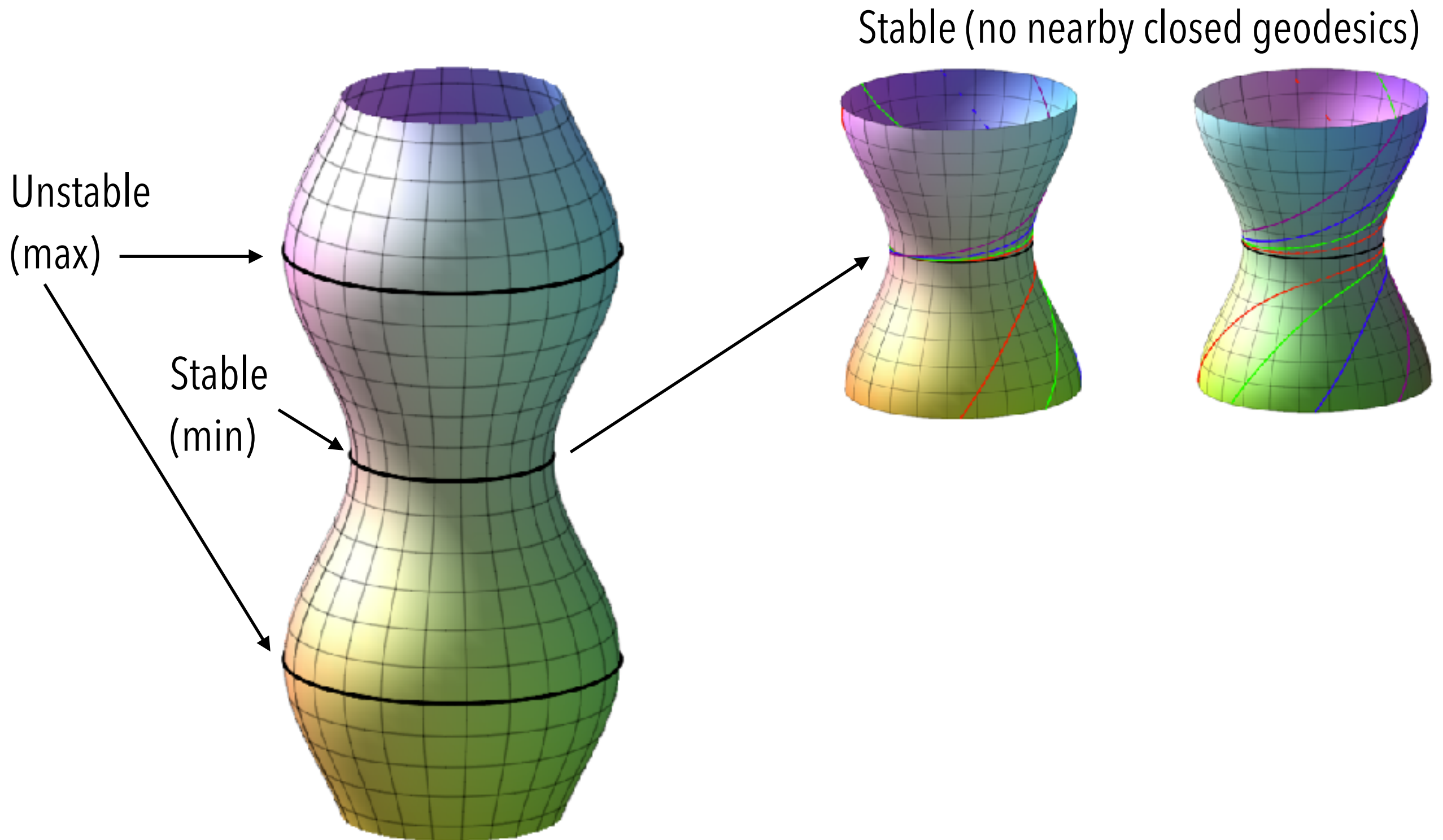
This is *geometric stability* in the sense of minimal surfaces/geodesics.



An aside...

What does "stable" mean?

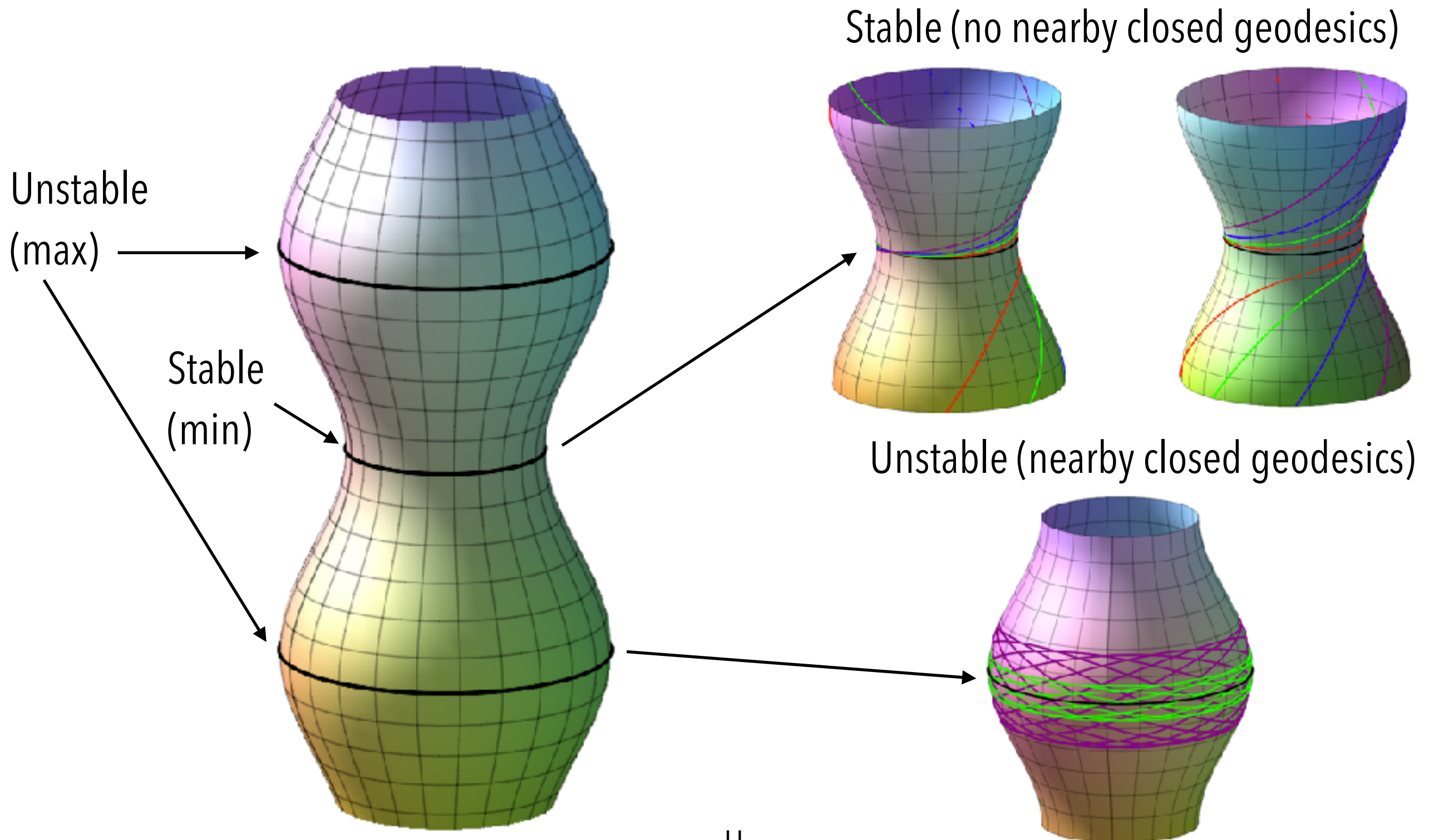
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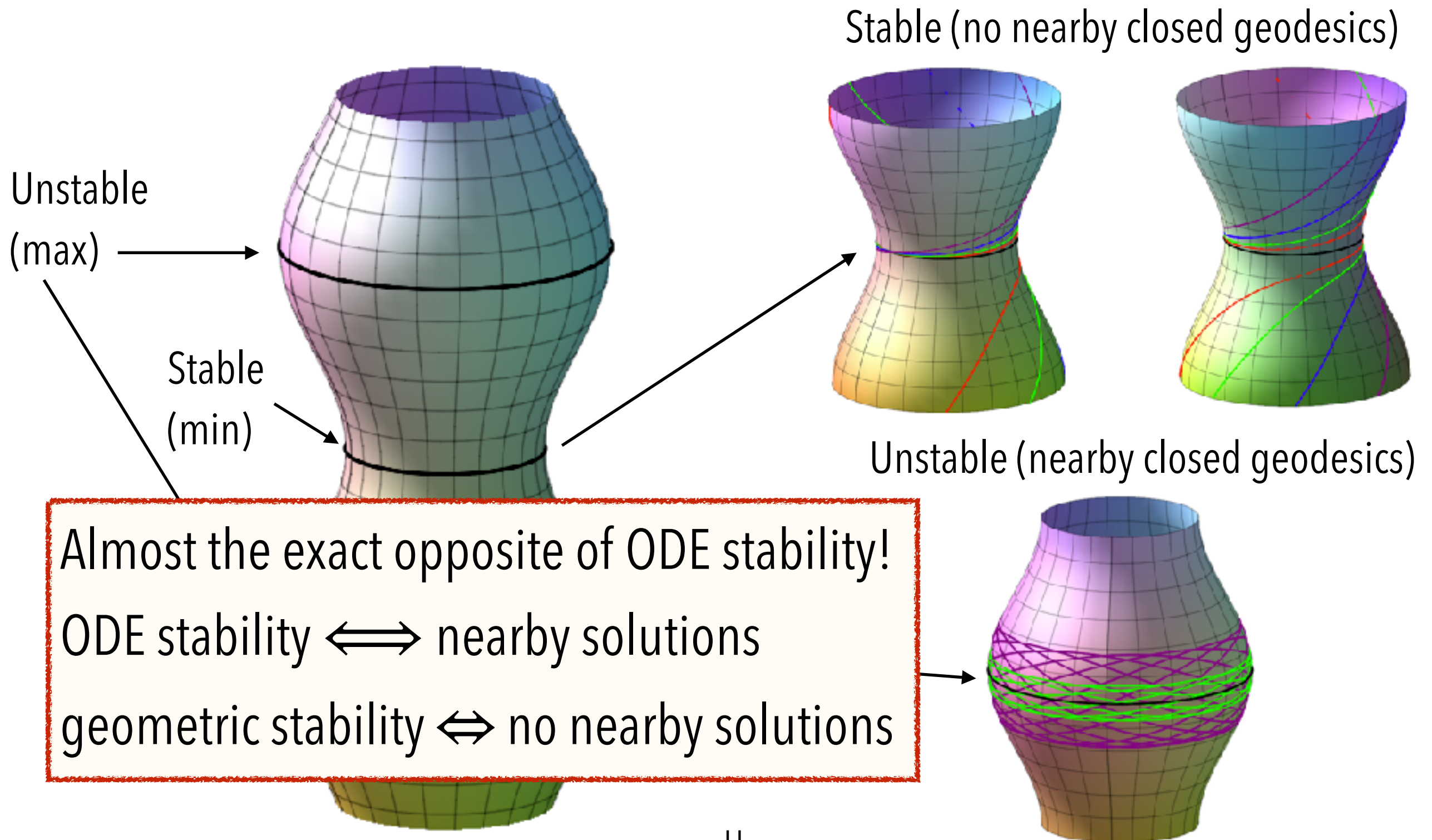
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An aside...

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This is *geometric stability* in the sense of minimal surfaces/geodesics.

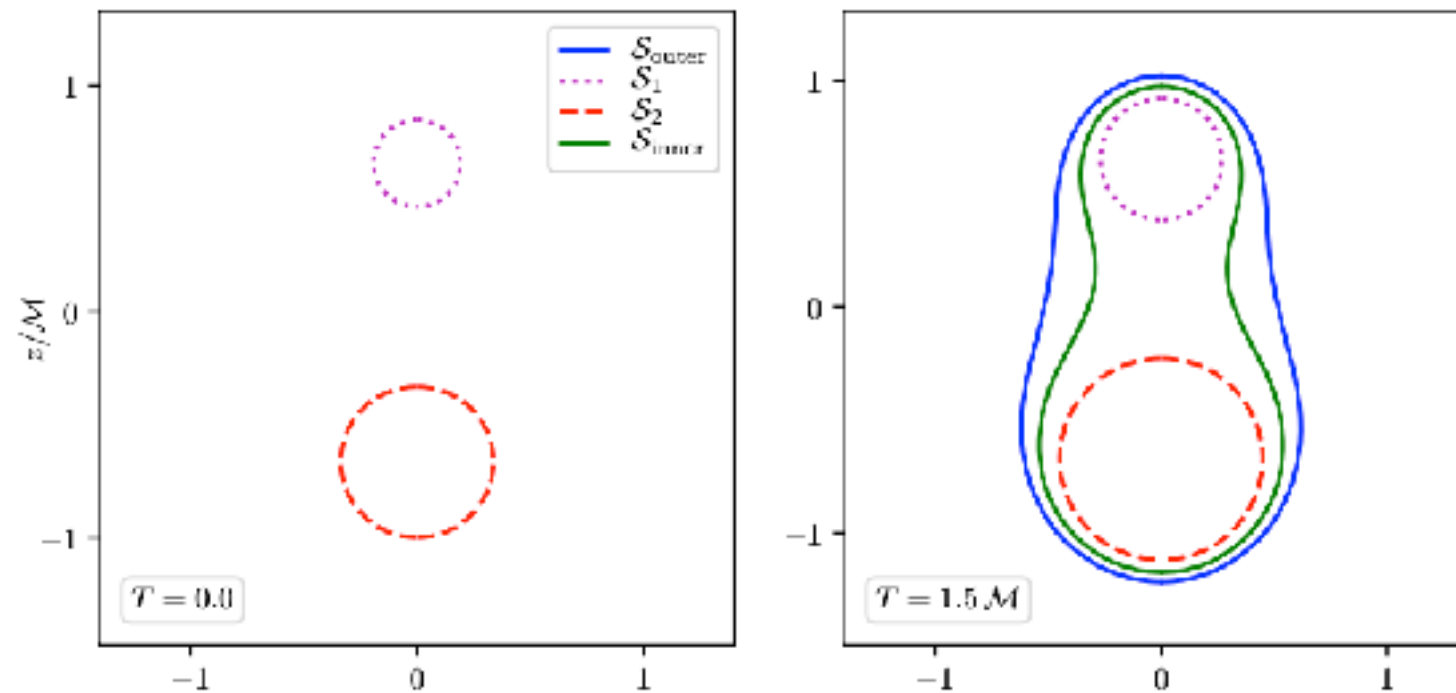


MOTSs can have "exotic" properties

Self-intersecting marginally outer trapped surfaces

Daniel Pook-Kolb,^{1,2} Ofek Birnholtz,³ Badri Krishnan,^{1,2} and Erik Schnetter^{4,5,6}

Phys. Rev. D 100, 084044 (2019)

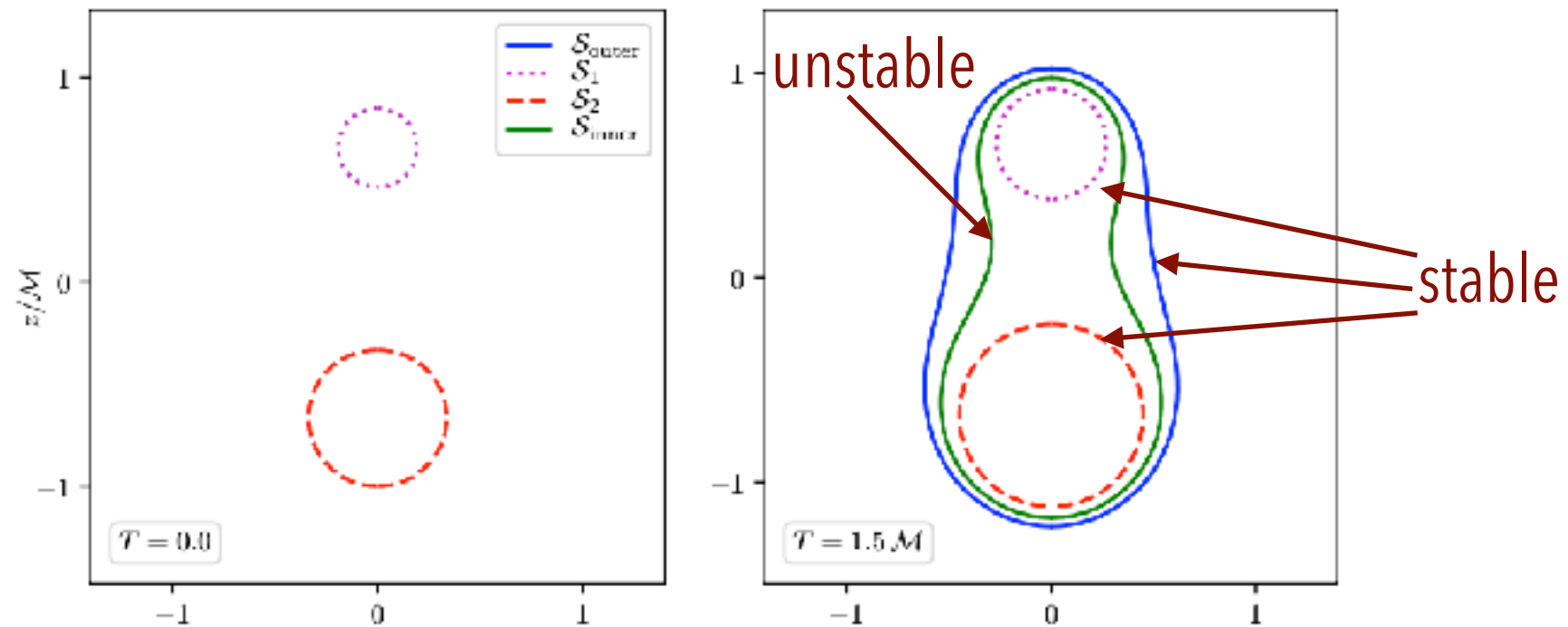


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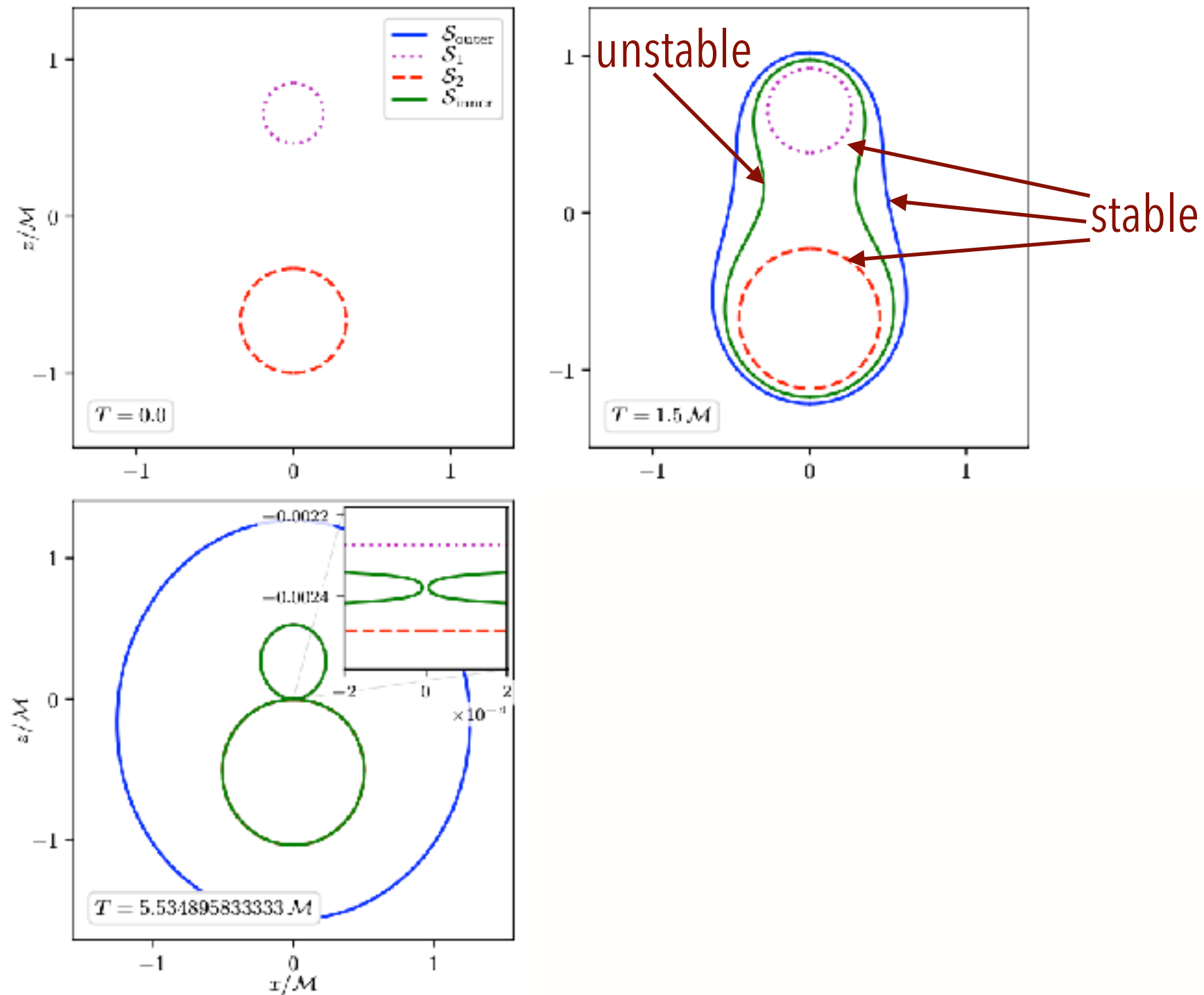


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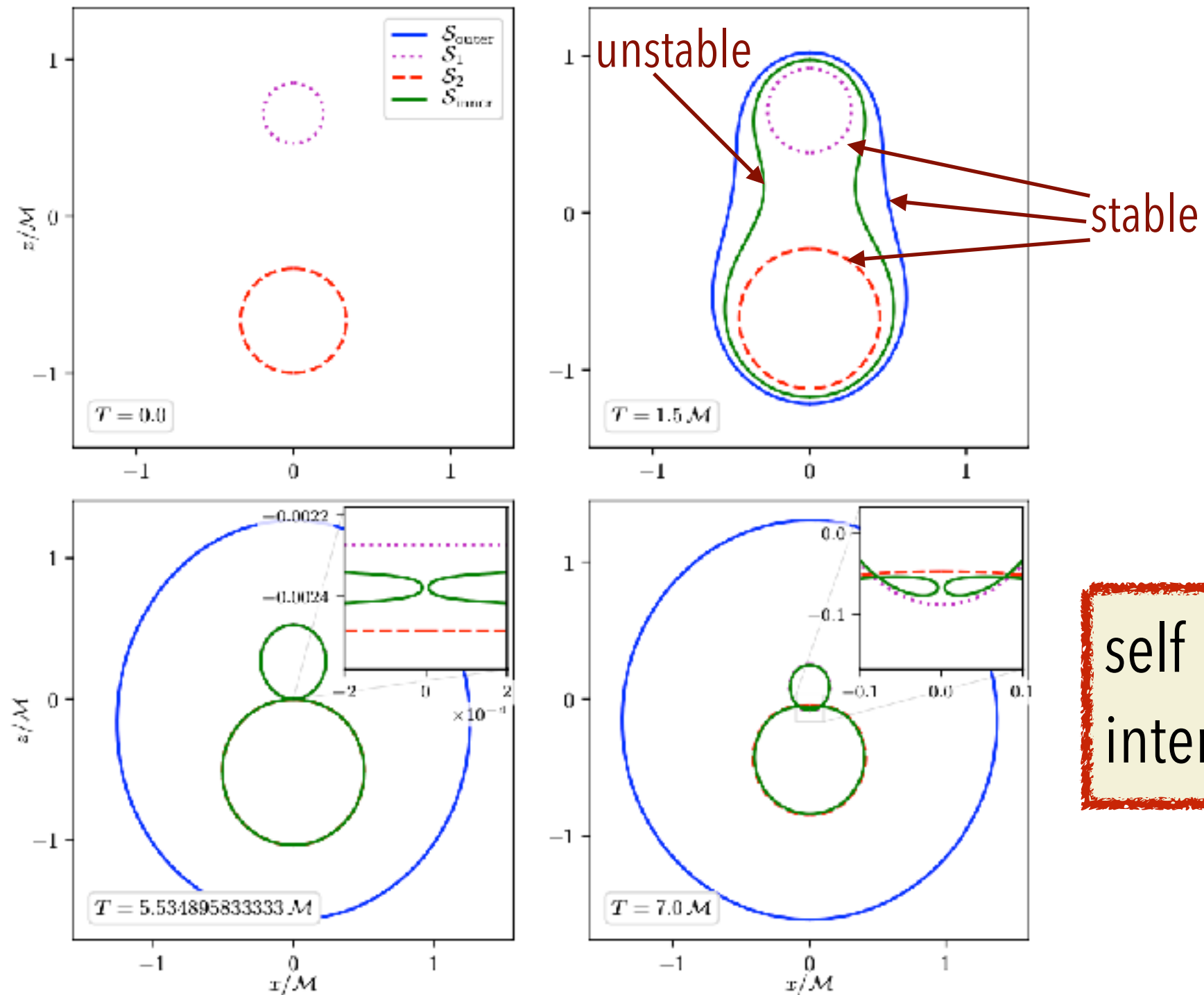


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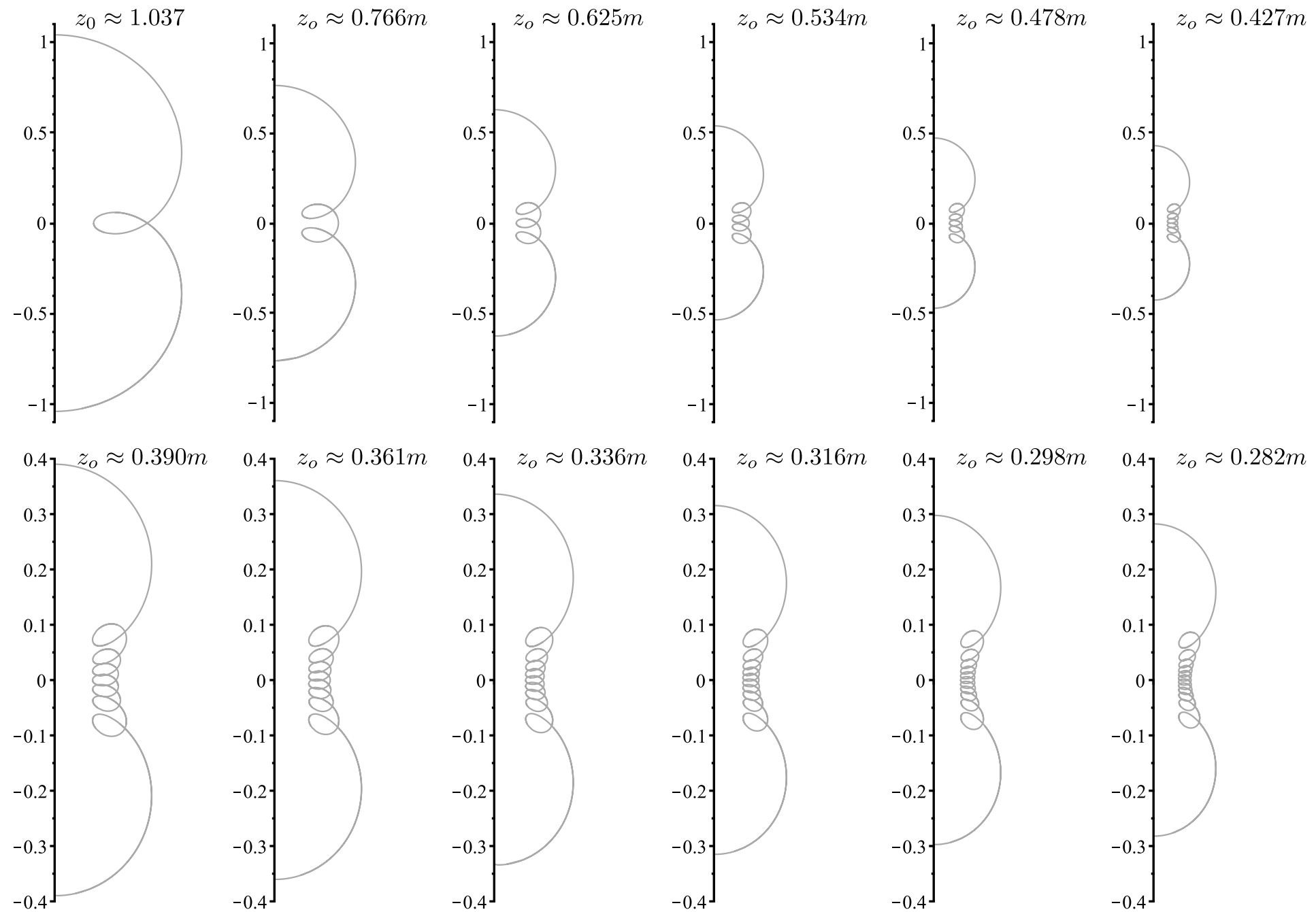
Phys. Rev. D 100, 084044 (2019)



self
intersections!

Most MOTS are not horizons/boundaries...

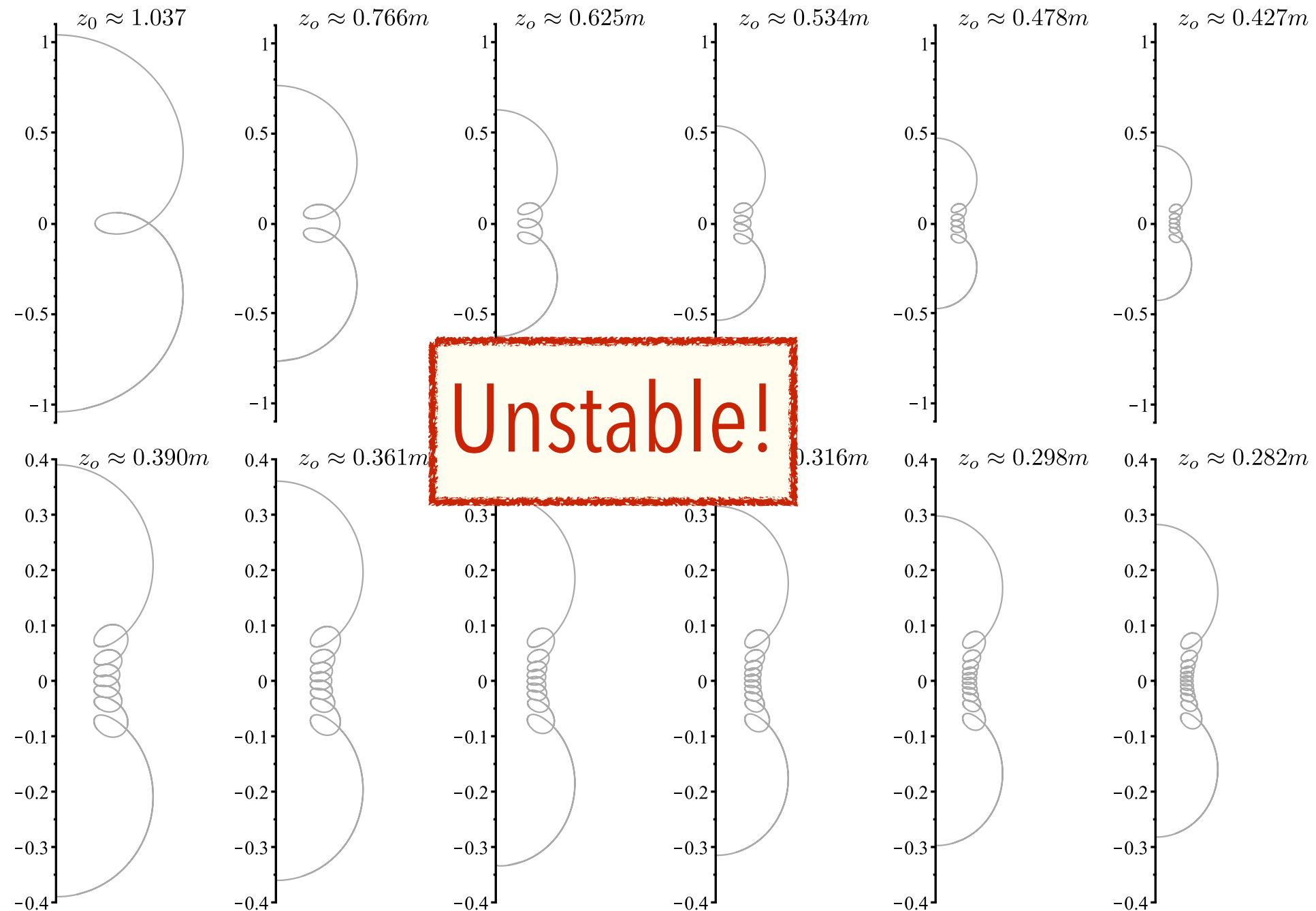
Schwarzschild



IB, R.Hennigar, S.Mondal (PRD 2020)

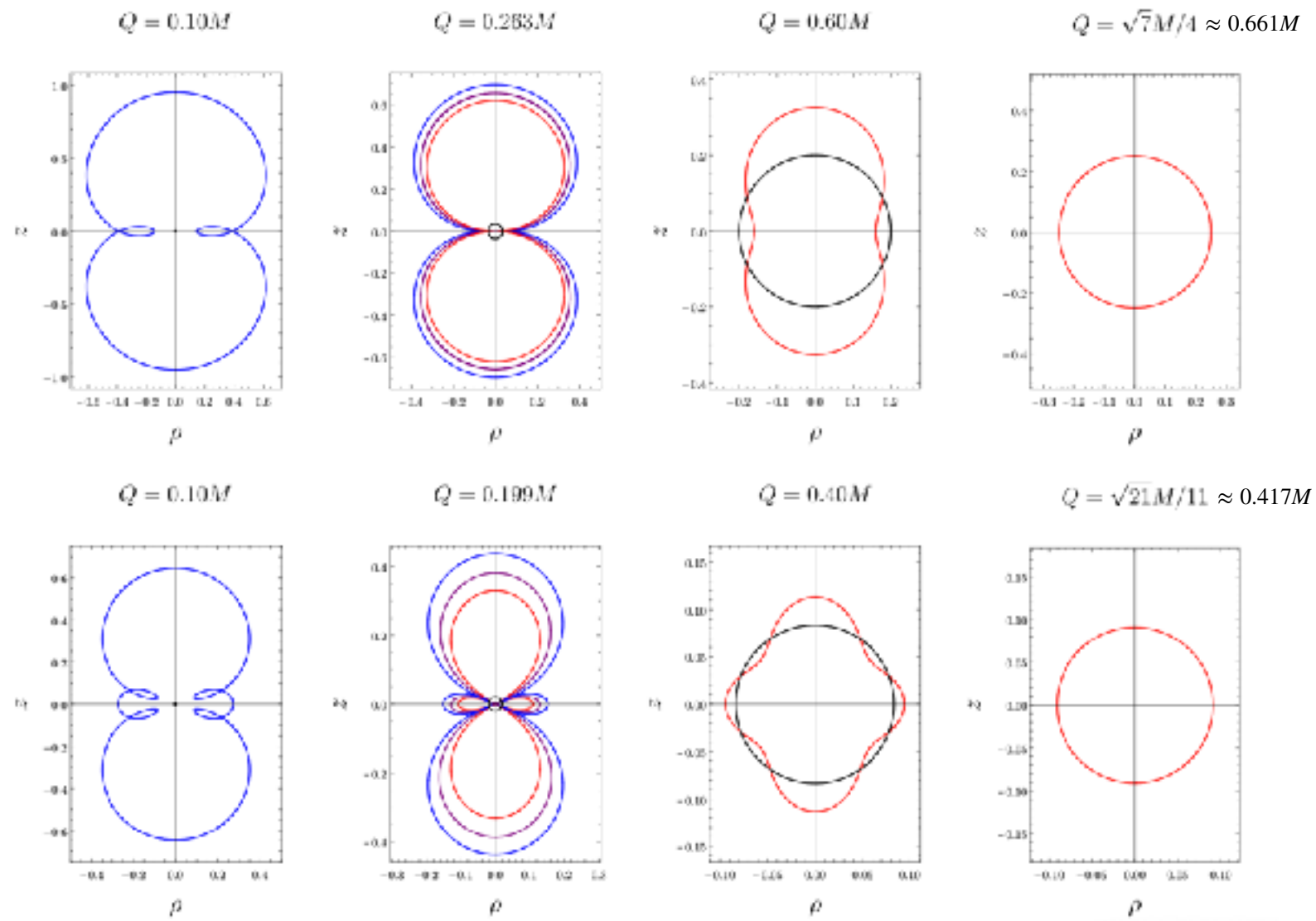
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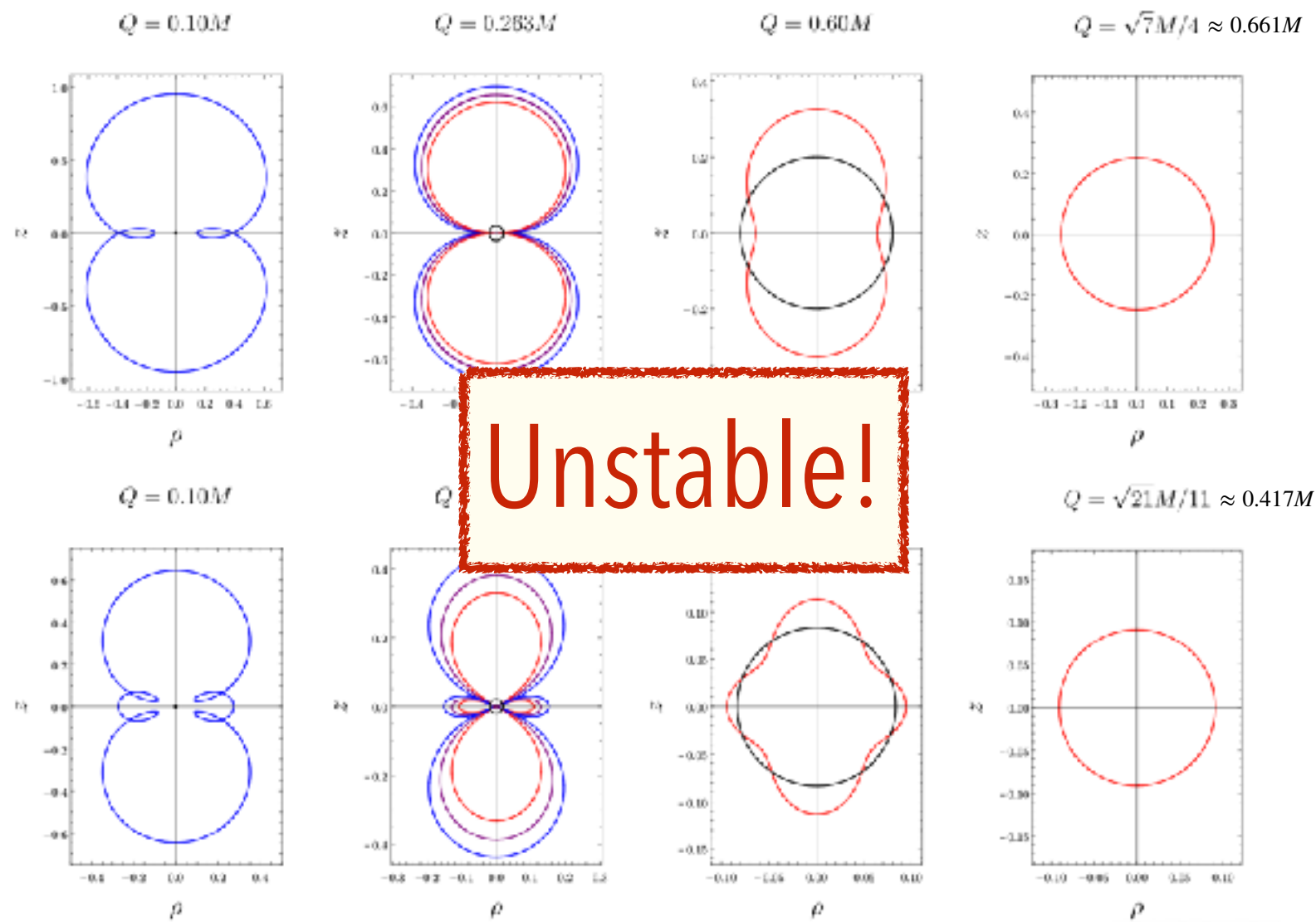
Reissner-Nordström (around inner horizon)



R.Hennigar, B.Chan/Sievers, L.Newhook, IB PRD 2022

Existence is robust across coordinate systems and solutions
(B.Sievers, R.Hennigar, H.Kunduri, S.Muth, L.Newhook, IB)

Reissner-Nordström (around inner horizon)



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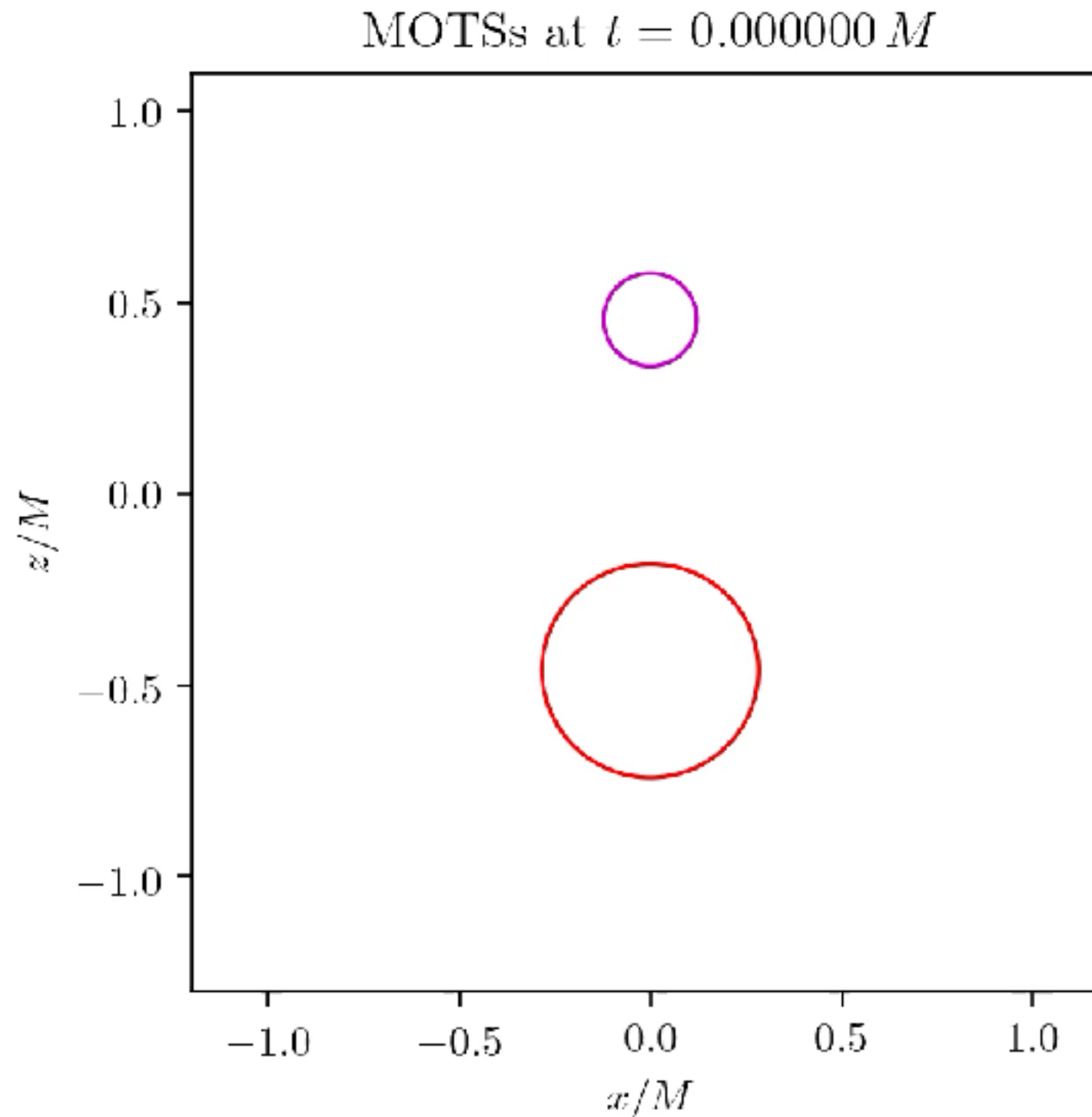
Existence is robust across coordinate systems and solutions
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Mergers are complicated...

Pook-Kolb, Hennigar, Booth PRL 2021 (Summary)

Pook-Kolb, Hennigar, Booth PRD 2021 (Theory)

Booth, Hennigar, Pook-Kolb PRD 2021 (Numerical Results)

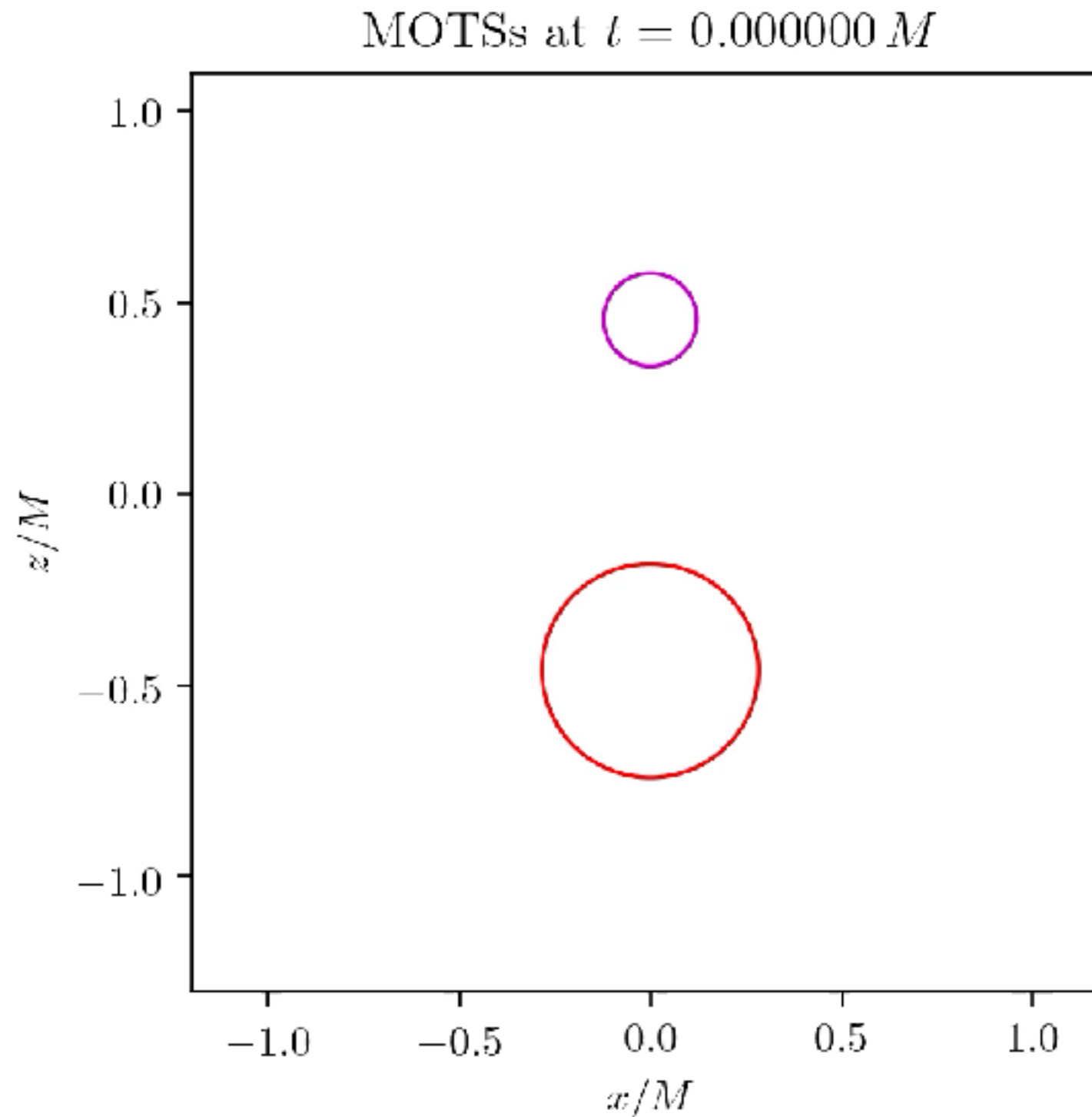


Mergers are complicated...

Pook-Kolb, Hennigar, Booth PRL 2021 (Summary)

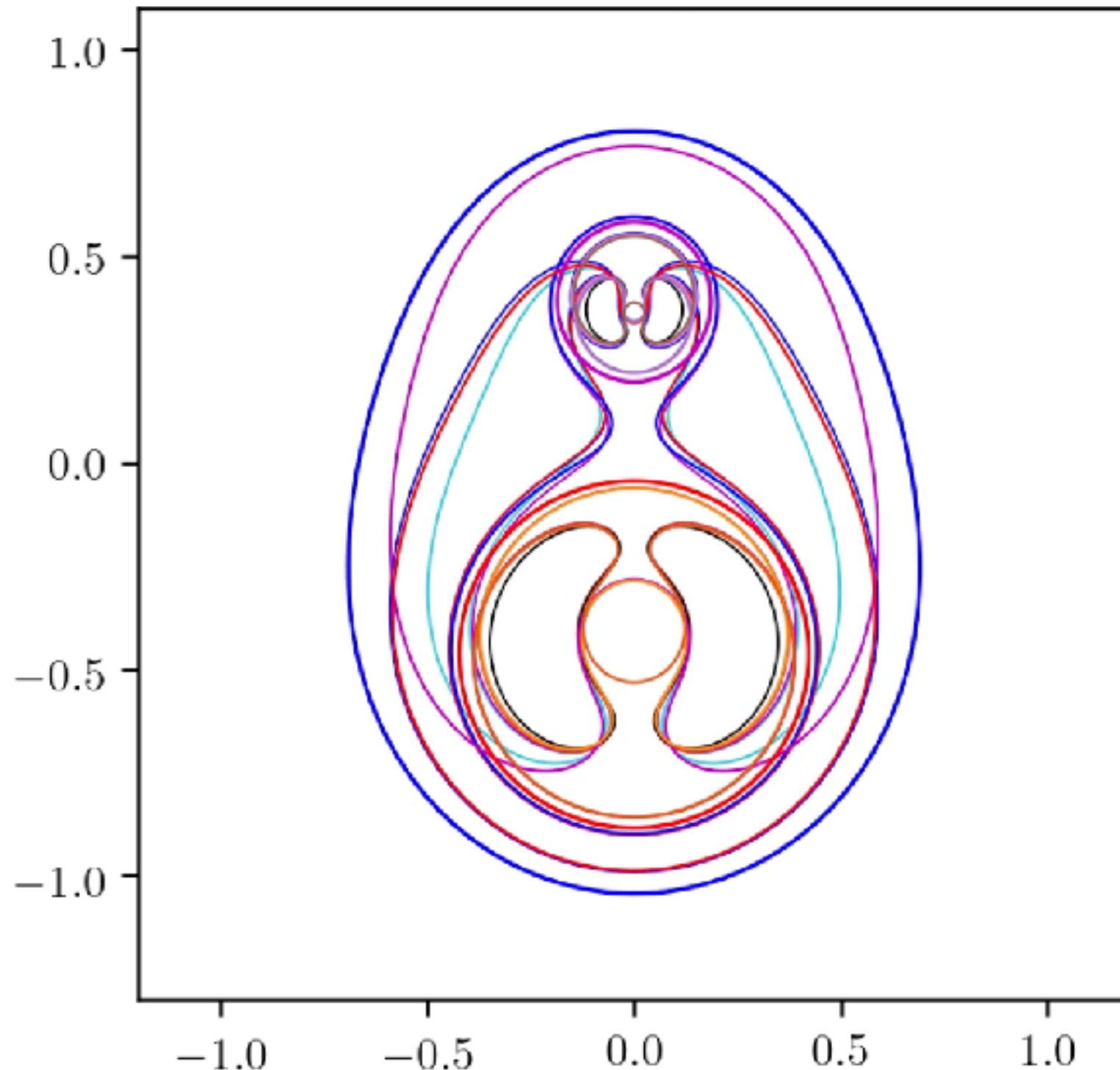
Pook-Kolb, Hennigar, Booth PRD 2021 (Theory)

Booth, Hennigar, Pook-Kolb PRD 2021 (Numerical Results)



During a merger

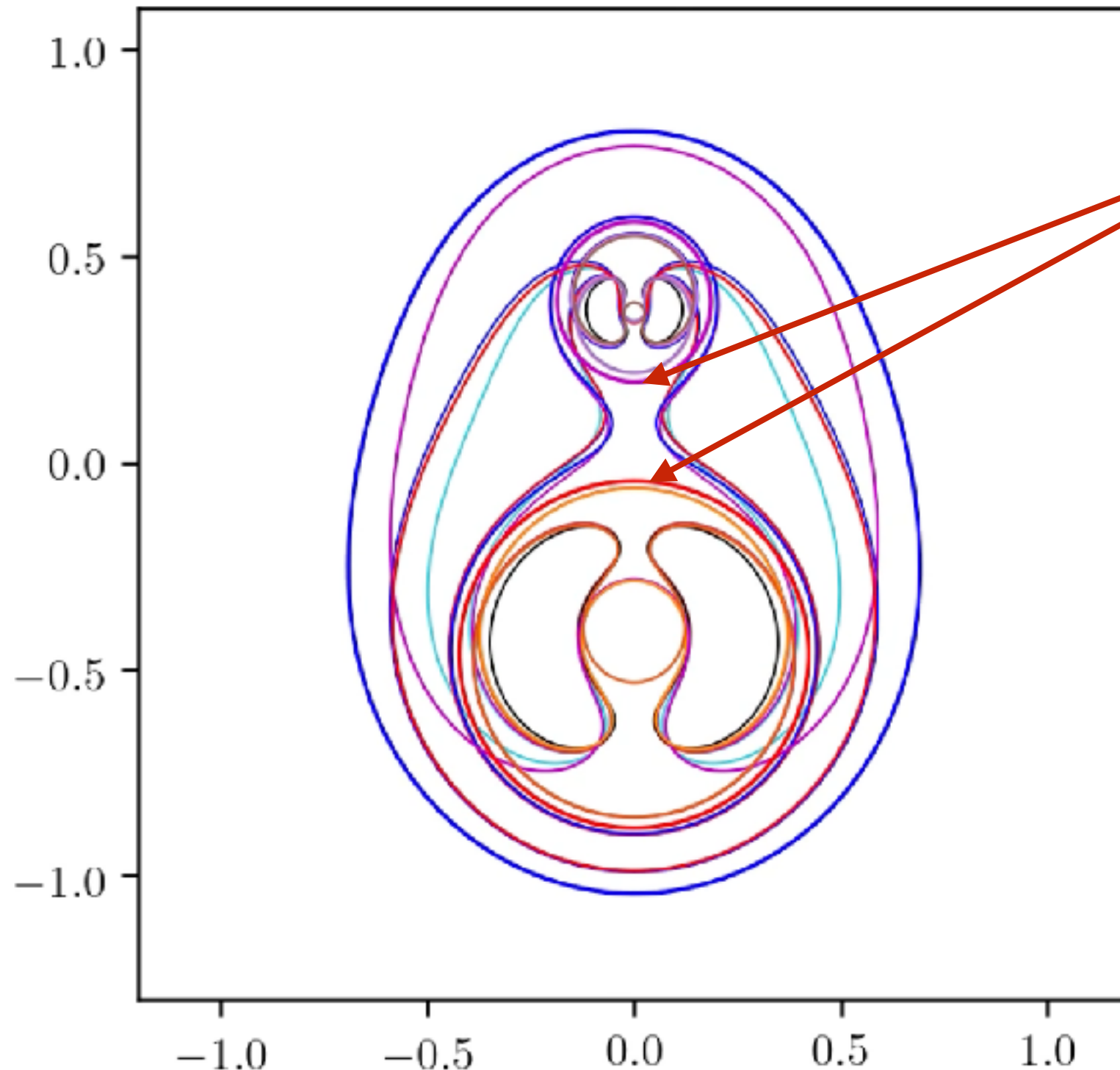
MOTSs at $t = 2.094256 M$



The original and final apparent horizons are stable.

During a merger

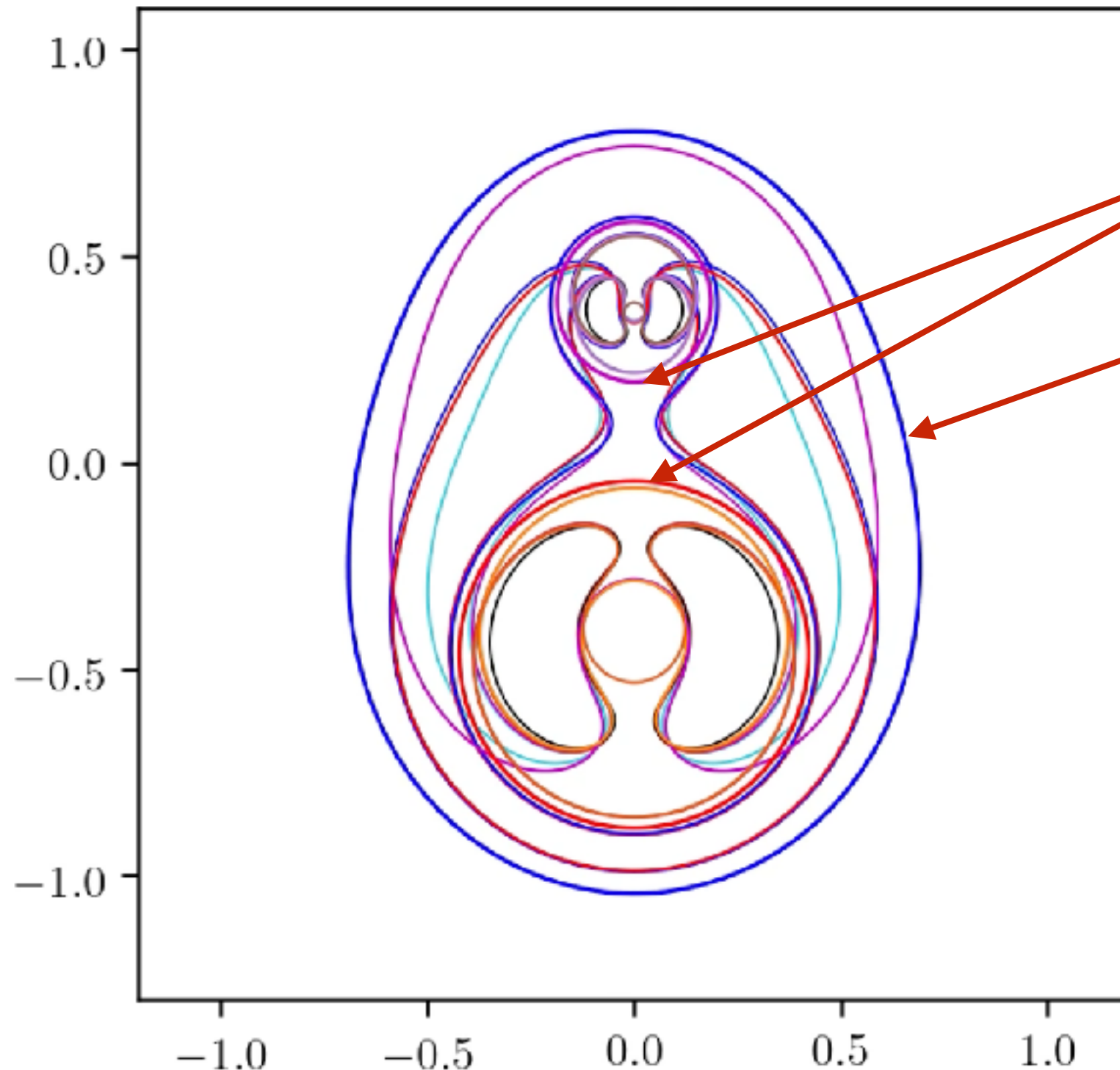
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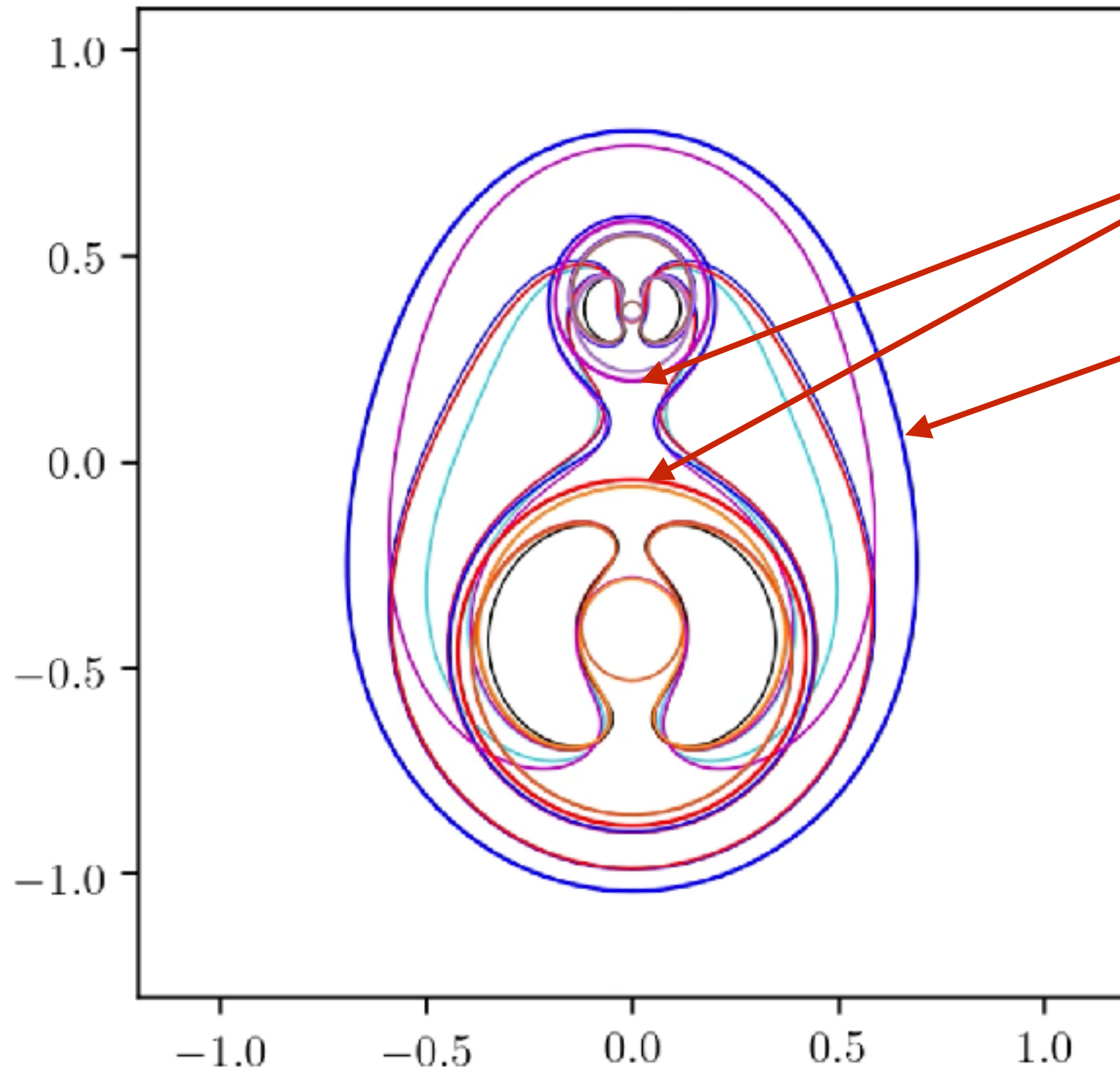
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MOTSs at $t = 2.094256 M$

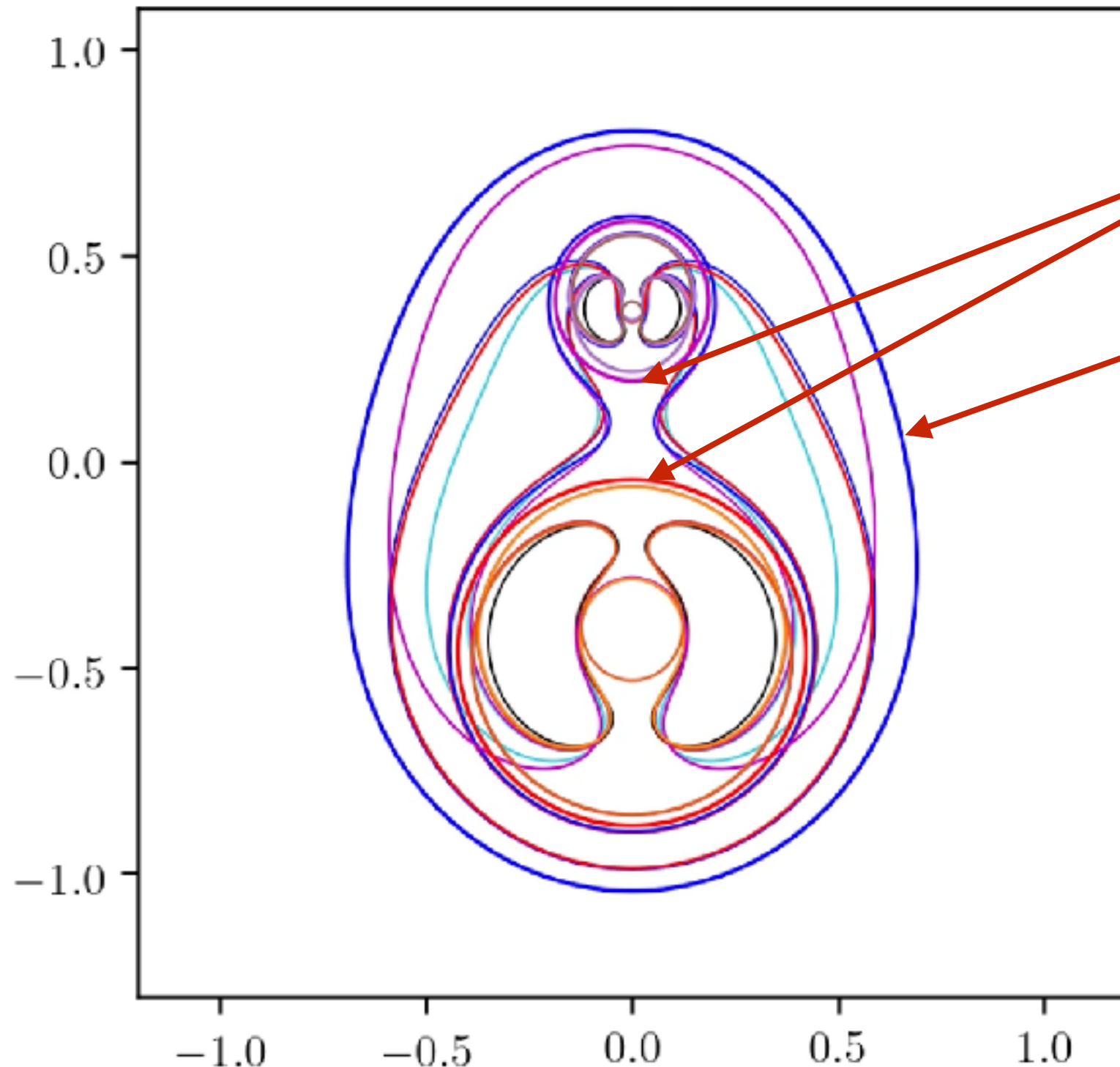


The original and final
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All other MOTS are
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During a merger

MOTSs at $t = 2.094256 M$



The original and final
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All other MOTS are
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Most MOTS do not
bound trapped regions

Stability Operator and Evolution/Deformation

Problem:

Stability Operator and Evolution/Deformation

Problem: δ_α = one-parameter deformation of the geometry (h_{ij}, K_{ij}) of a slice Σ_t

Second application of stability operator

Stability Operator and Evolution/Deformation

examples: time evolution, q in RN, Λ is dS, anything else

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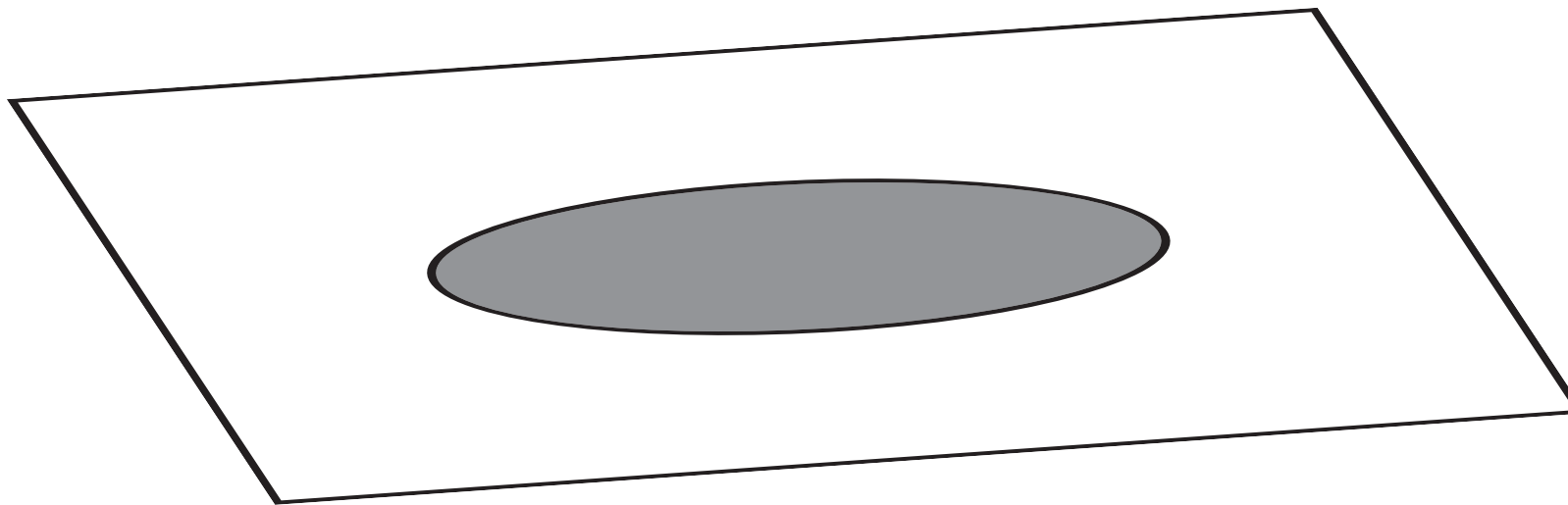
Can we perturb S in Σ_t so that it remains a MOTS?

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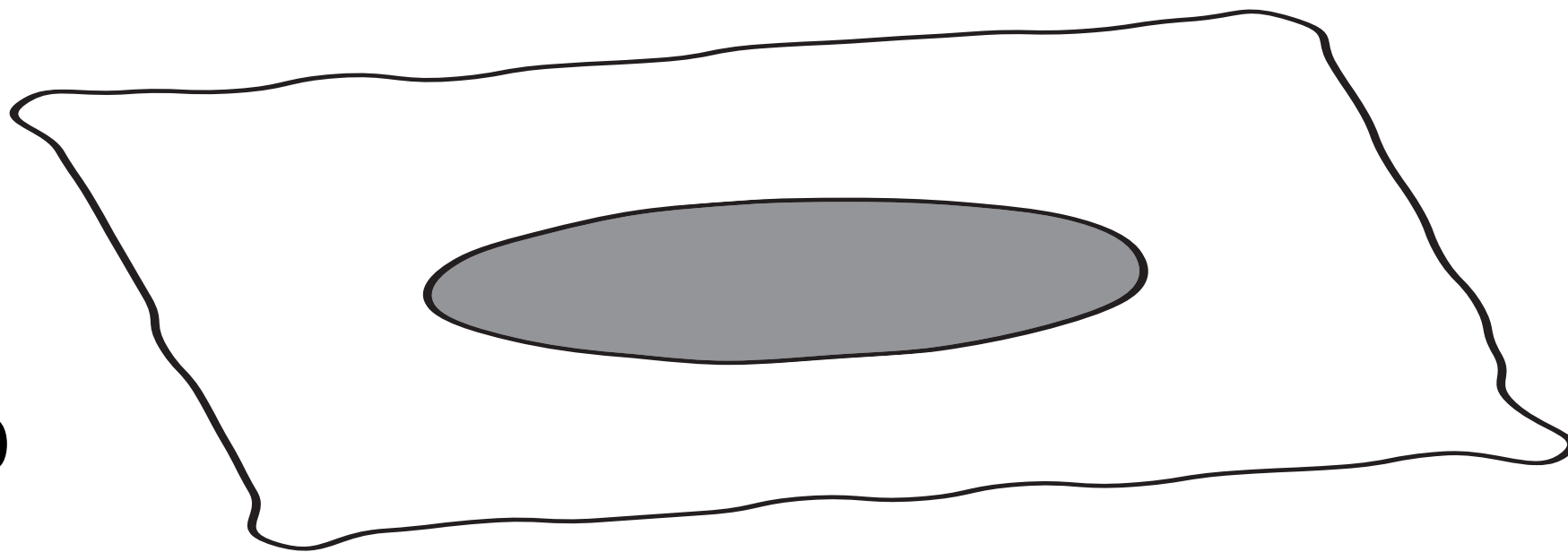
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Can we perturb S in Σ_t so that it remains a MOTS?

distorted
 (h_{ij}, K_{ij})
 $\theta_+|_S \neq 0$

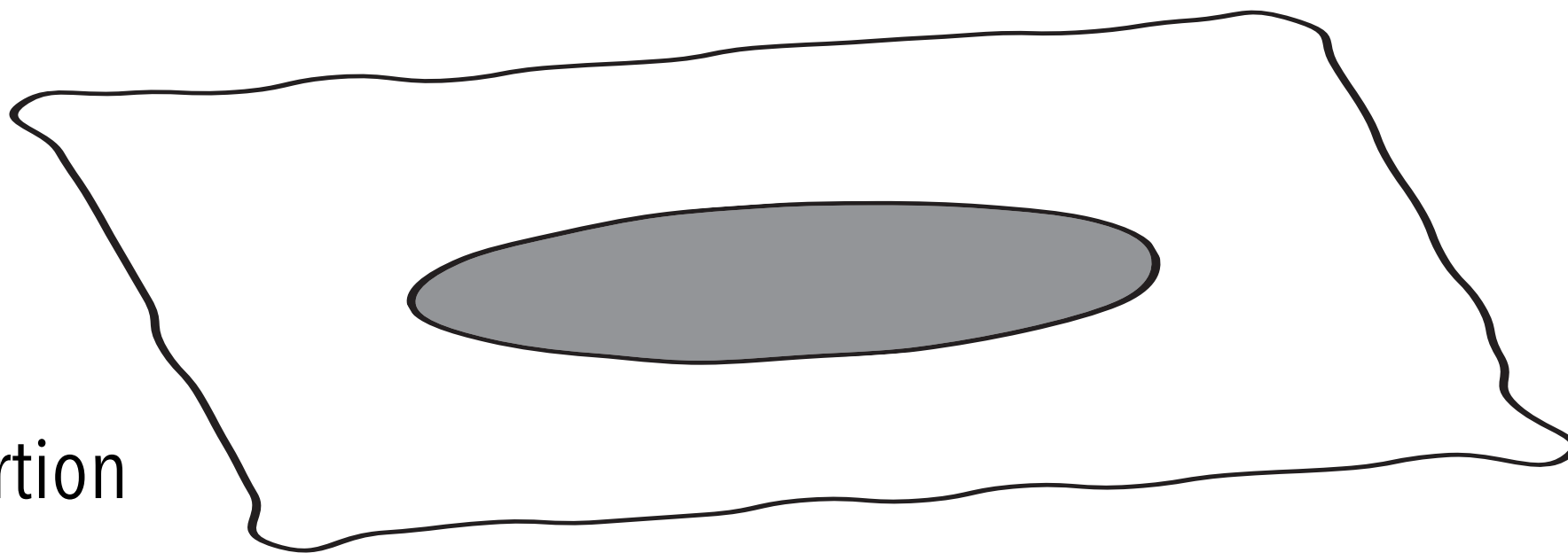


Stability Operator and Evolution/Deformation

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small distortion
of $S \rightarrow \theta_+ = 0$

Second application of stability operator

Stability Operator and Evolution/Deformation

examples: time evolution, q in RN, Λ is dS, anything else

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total change in expansion

change due to (h, K) deformation

Solution: Look for a ψ for which: $0 = \delta\theta_+ = \delta_\alpha\theta_+ + \delta_{\psi N}\theta_+$

change from S perturbation

Second application of stability operator

Stability Operator and Evolution/Deformation

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change from S
perturbation

$$\iff 0 = \delta_\alpha\theta_+ + L_S\psi$$

Second application of stability operator

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ψ is unique if L_S is invertible $\iff L_S$ has no vanishing eigenvalues

Second application of stability operator

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Strict stability ($\lambda_o > 0$) is sufficient but not necessary for uniqueness

$\lambda_5 > 0$	×
$\lambda_4 > 0$	×
$\lambda_3 > 0$	×
$\lambda_2 > 0$	×
$\lambda_1 > 0$	×
$\lambda_o > 0$	×

Second application of stability operator

Stability Operator and Evolution/Deformation

examples: time evolution, q in RN, Λ is dS, anything else

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Strict stability ($\lambda_o > 0$) is sufficient but not necessary for uniqueness

Non-uniqueness: Possible when an eigenvalue vanishes.

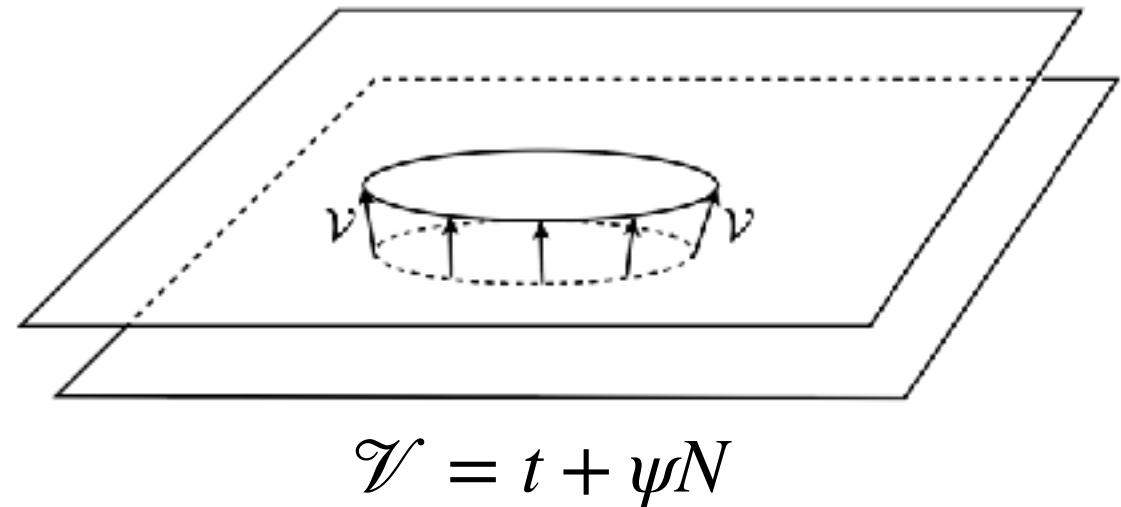
$\lambda_5 > 0$	×
$\lambda_4 > 0$	×
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$\lambda_2 > 0$	×
$\lambda_1 > 0$	×
$\lambda_o > 0$	×

Example: time evolution

- Time evolution of a MOTS:

$$0 = \delta_t \theta_+ + \delta_{\psi N} \theta_+$$

$$\iff \psi = -L^{-1}(l_+, N)[\delta_t \theta_+]$$

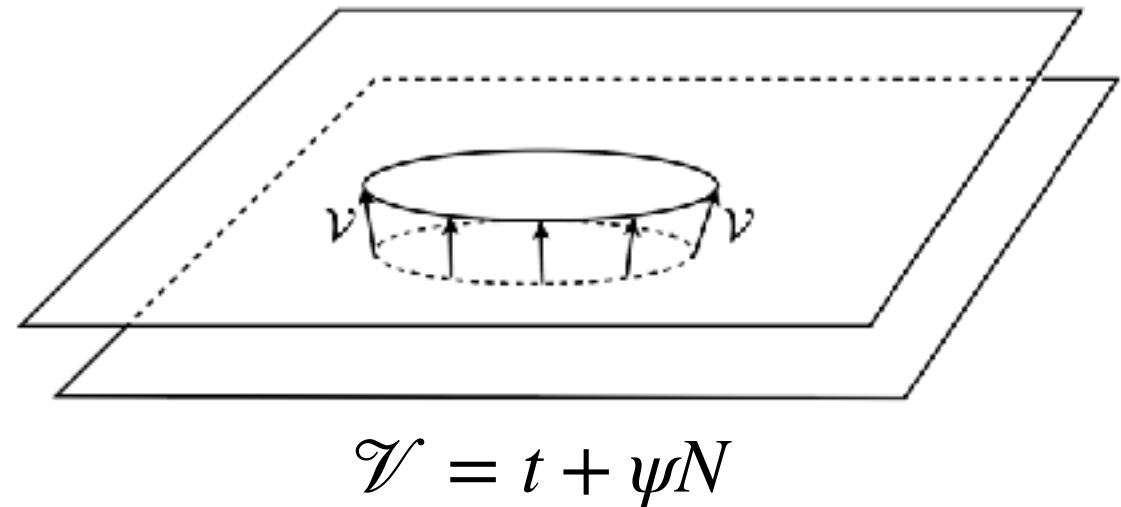


Example: time evolution

- Time evolution of a MOTS:

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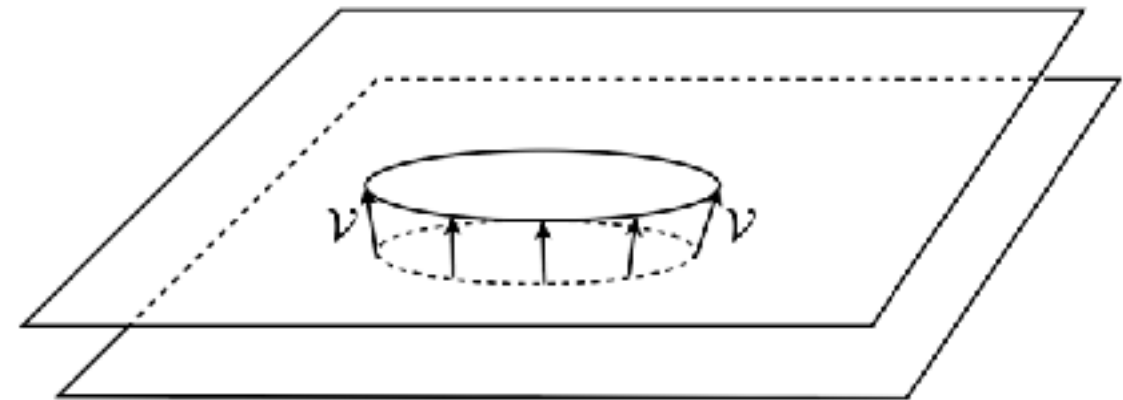
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Example: time evolution

- Time evolution of a MOTS:

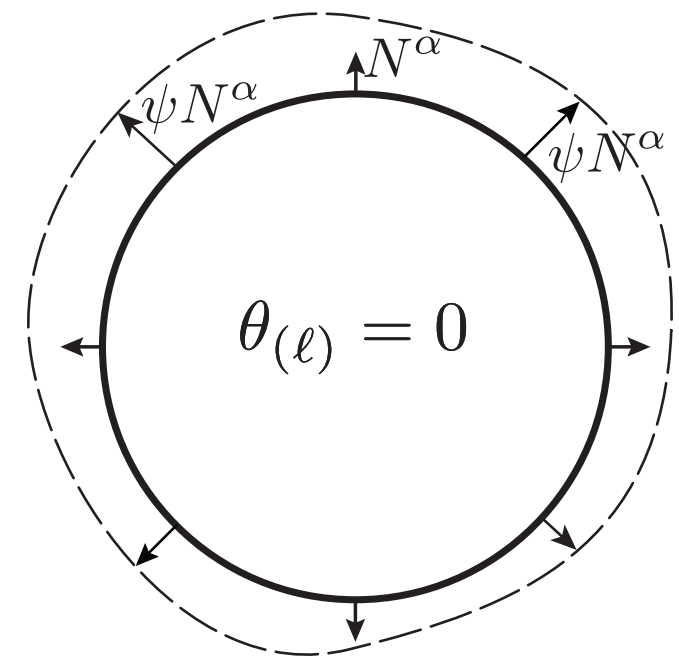
$$0 = \delta_t \theta_+ + \delta_{\psi N} \theta_+$$

$$\iff \psi = -L^{-1}(l_+, N)[\delta_t \theta_+]$$



$$\mathcal{V} = t + \psi N$$

- Unique if there are no vanishing eigenvalues
- If the MOTS is **marginally stable** then there exists a function ψ_0 such that: $\delta_{\psi_0 N} \theta_+ = L_{\Sigma} \psi_0 = 0$

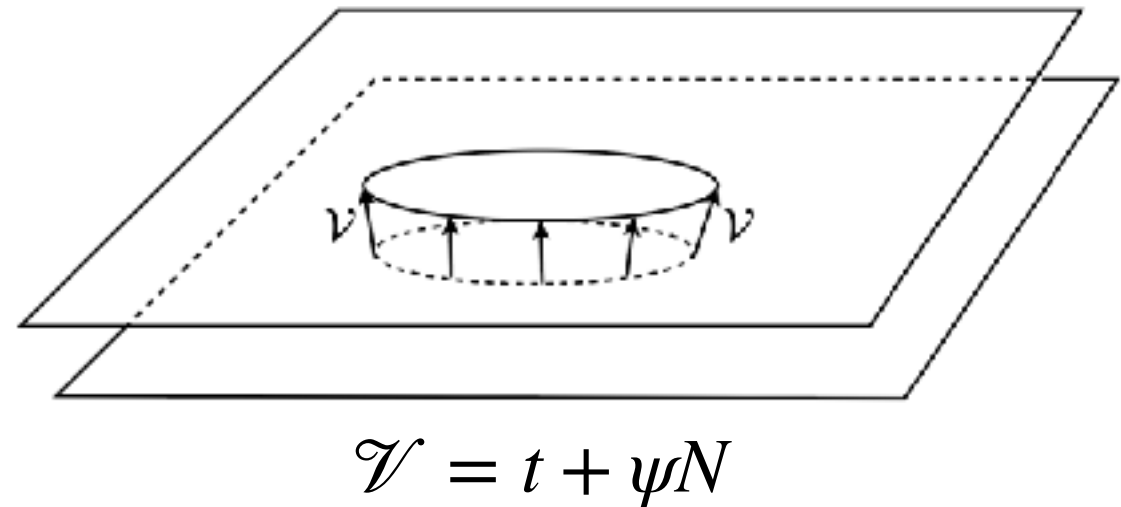


Example: time evolution

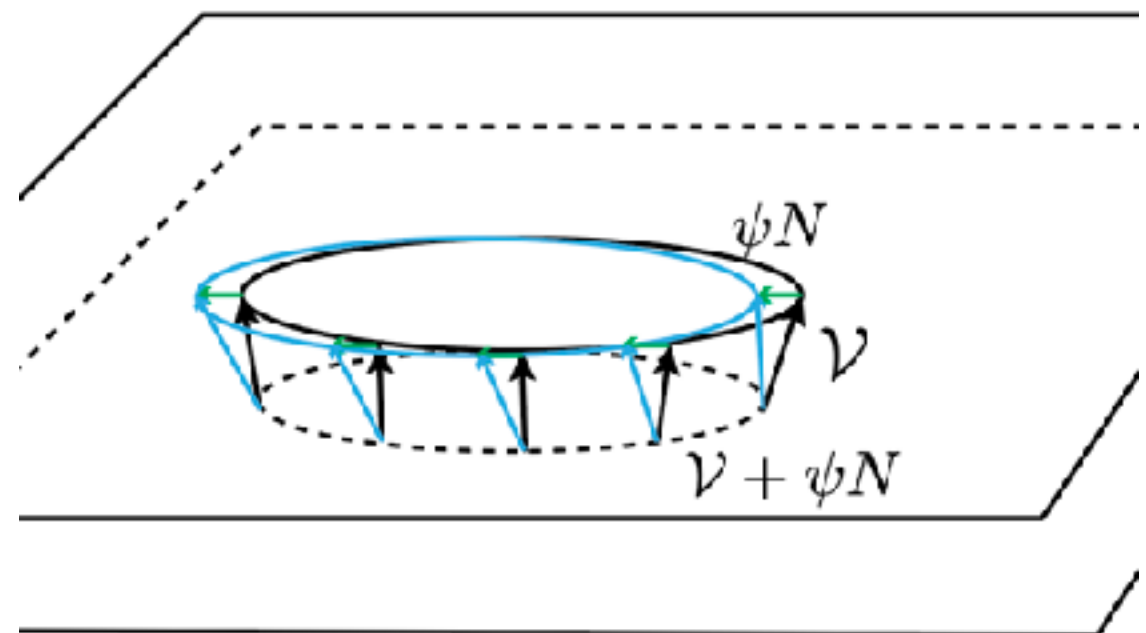
- Time evolution of a MOTS:

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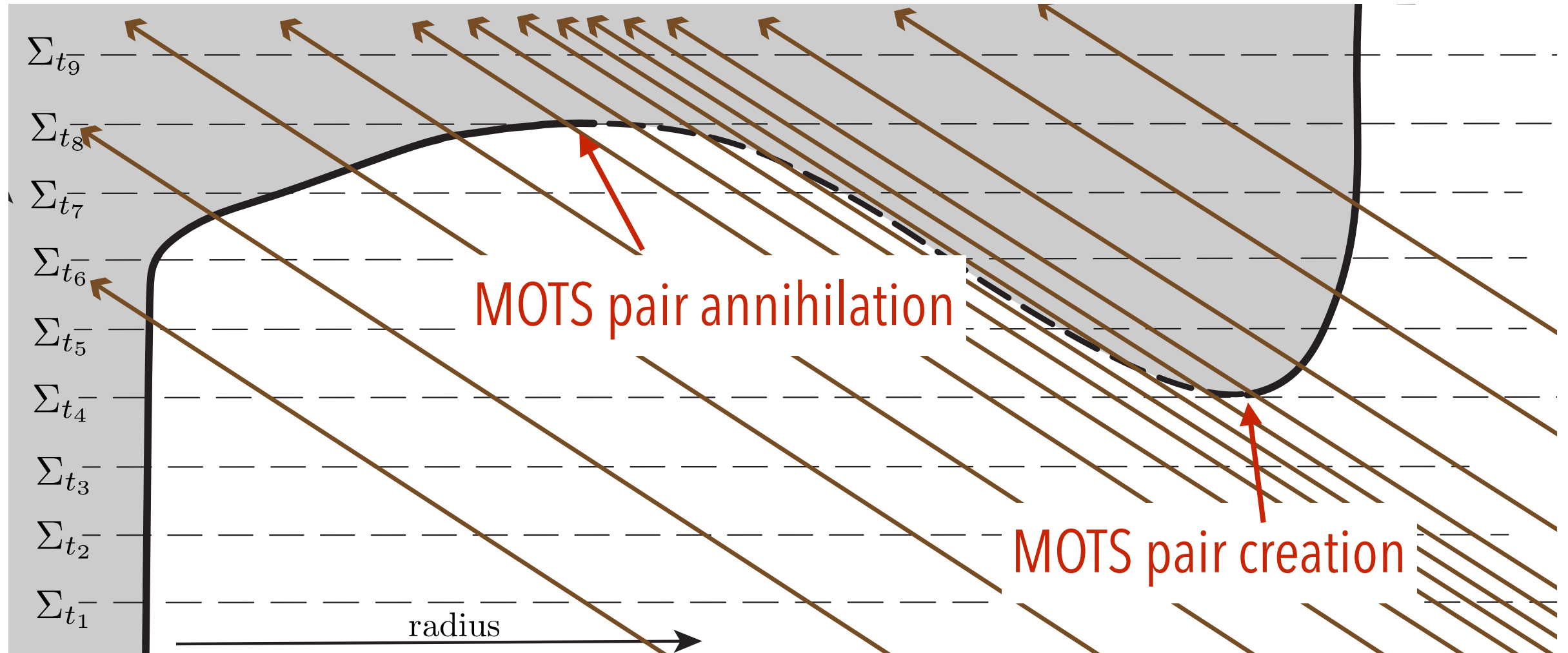
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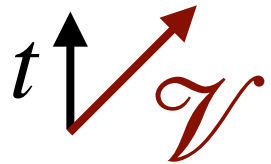
- Unique if there are no vanishing eigenvalues
- If the MOTS is **marginally stable** then there exists a function ψ_0 such that: $\delta_{\psi_0 N} \theta_+ = L_\Sigma \psi_0 = 0$
- Then: $\delta_{(\mathcal{V} + \psi_0 N)} \theta_+ = 0$ so:
 $\mathcal{V} + \psi_0 N$ is an equally good
 "time-evolution" vector



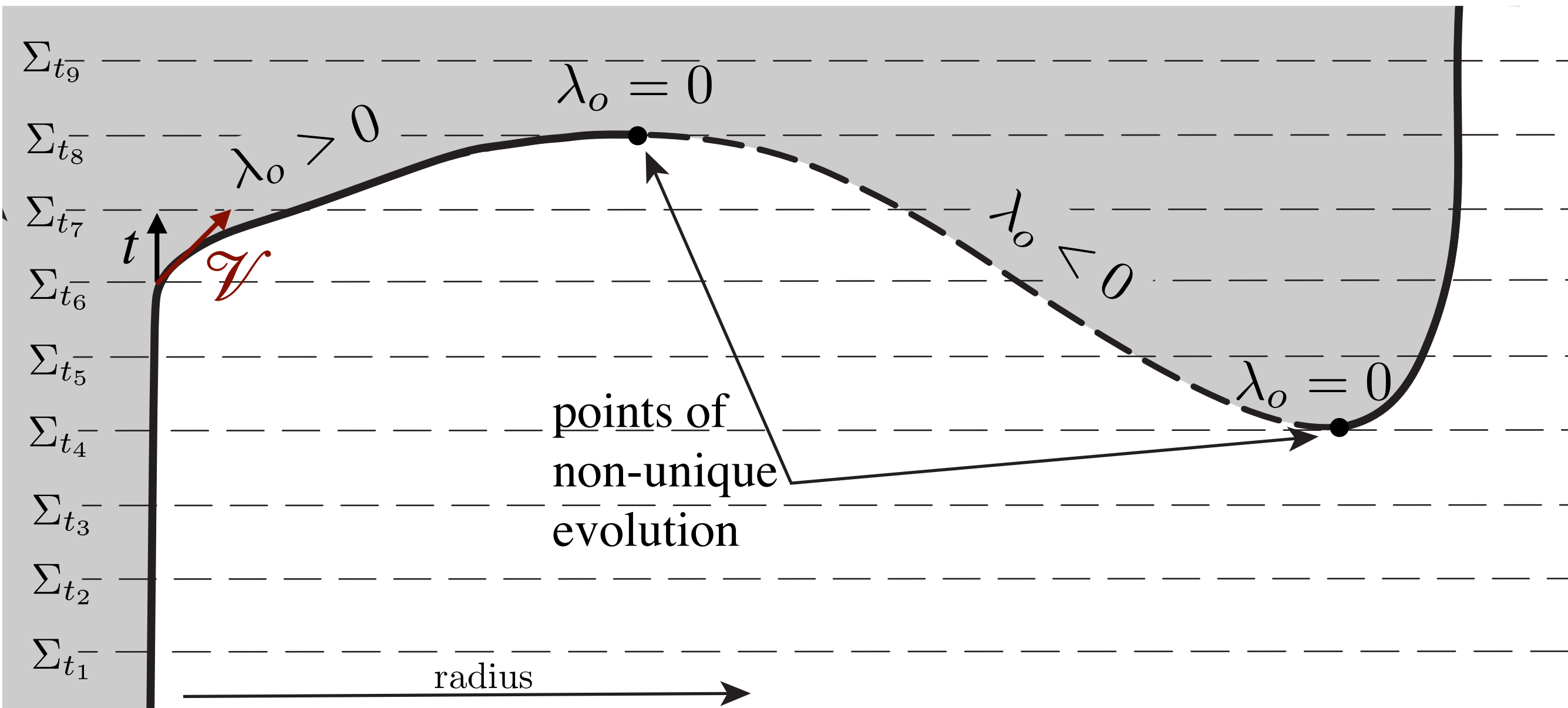
MOTS time evolution - an example



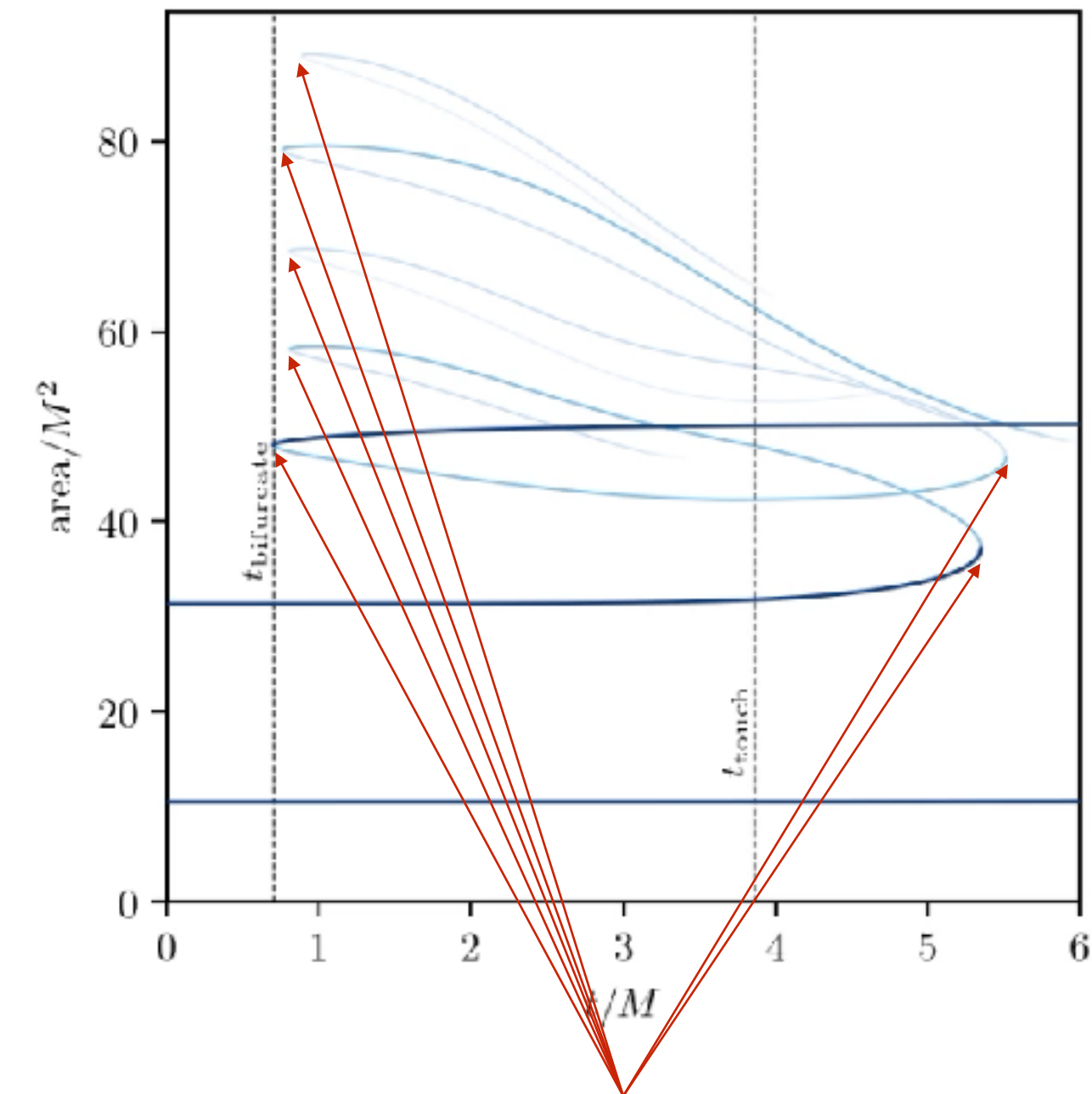
MOTS evolution and the stability operator



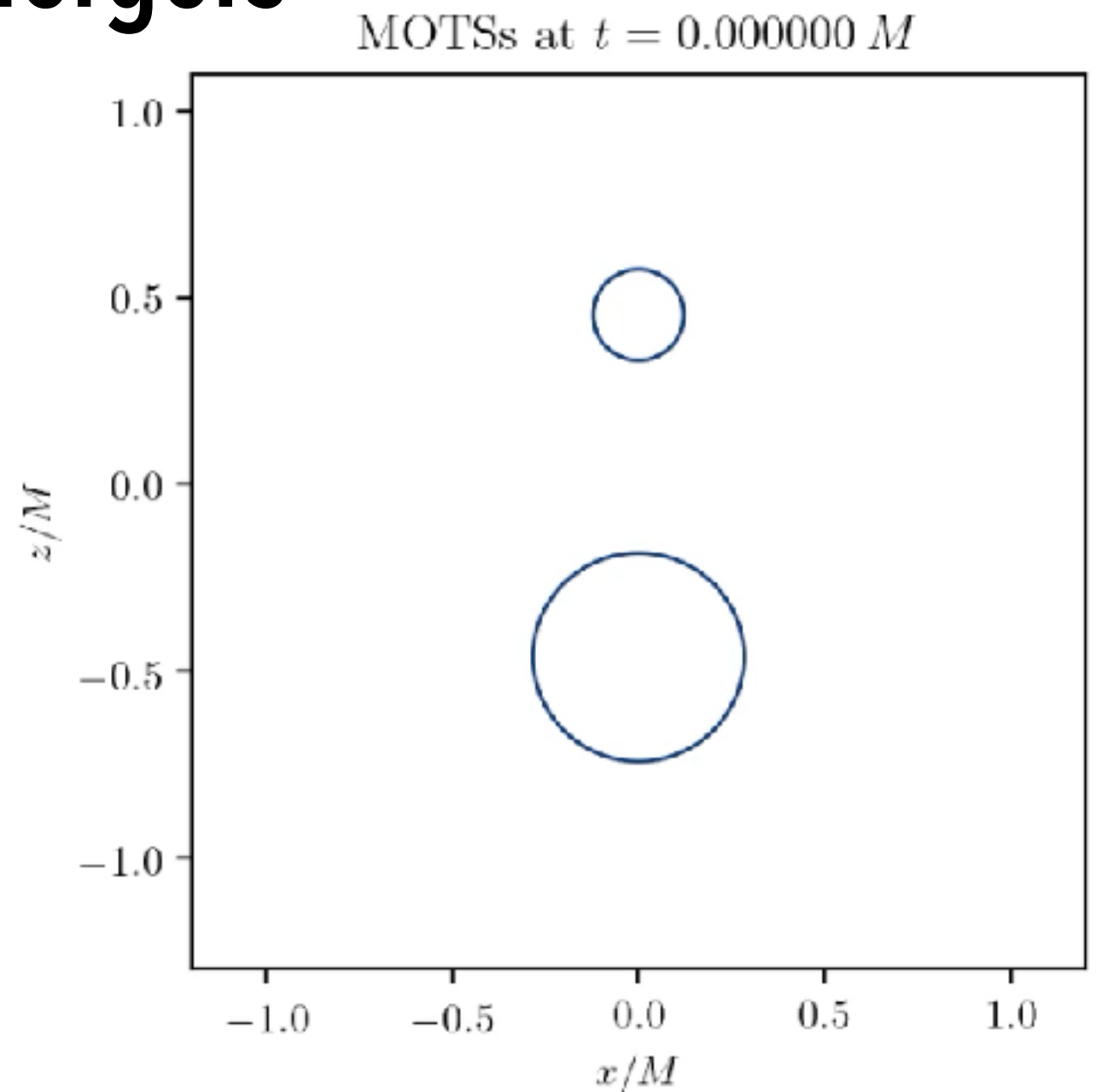
MOTS evolution and the stability operator



MOTS during black hole mergers



L_Σ has a vanishing eigenvalue at
creation and annihilation points

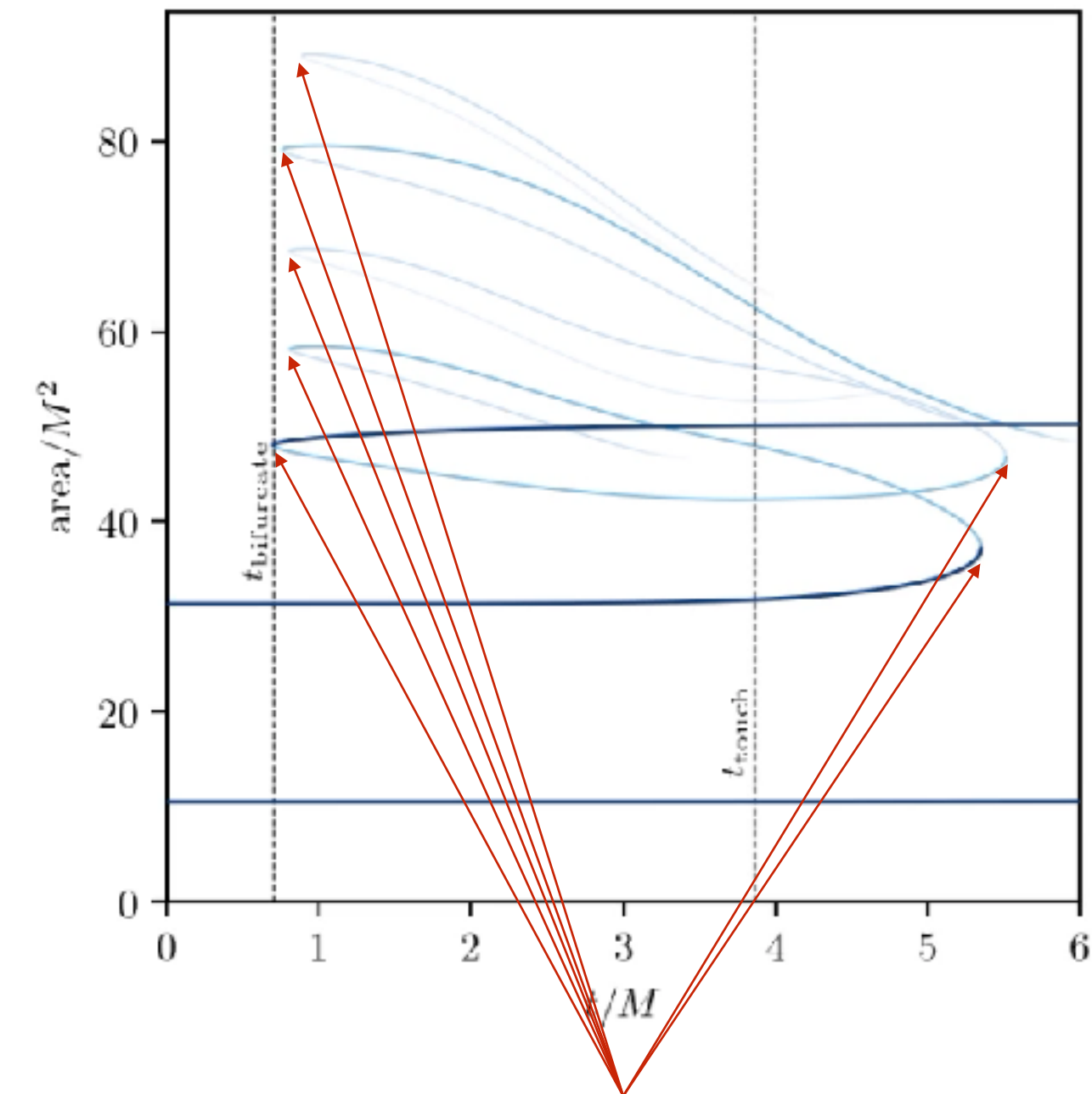


Black = stable MOTS = apparent horizons

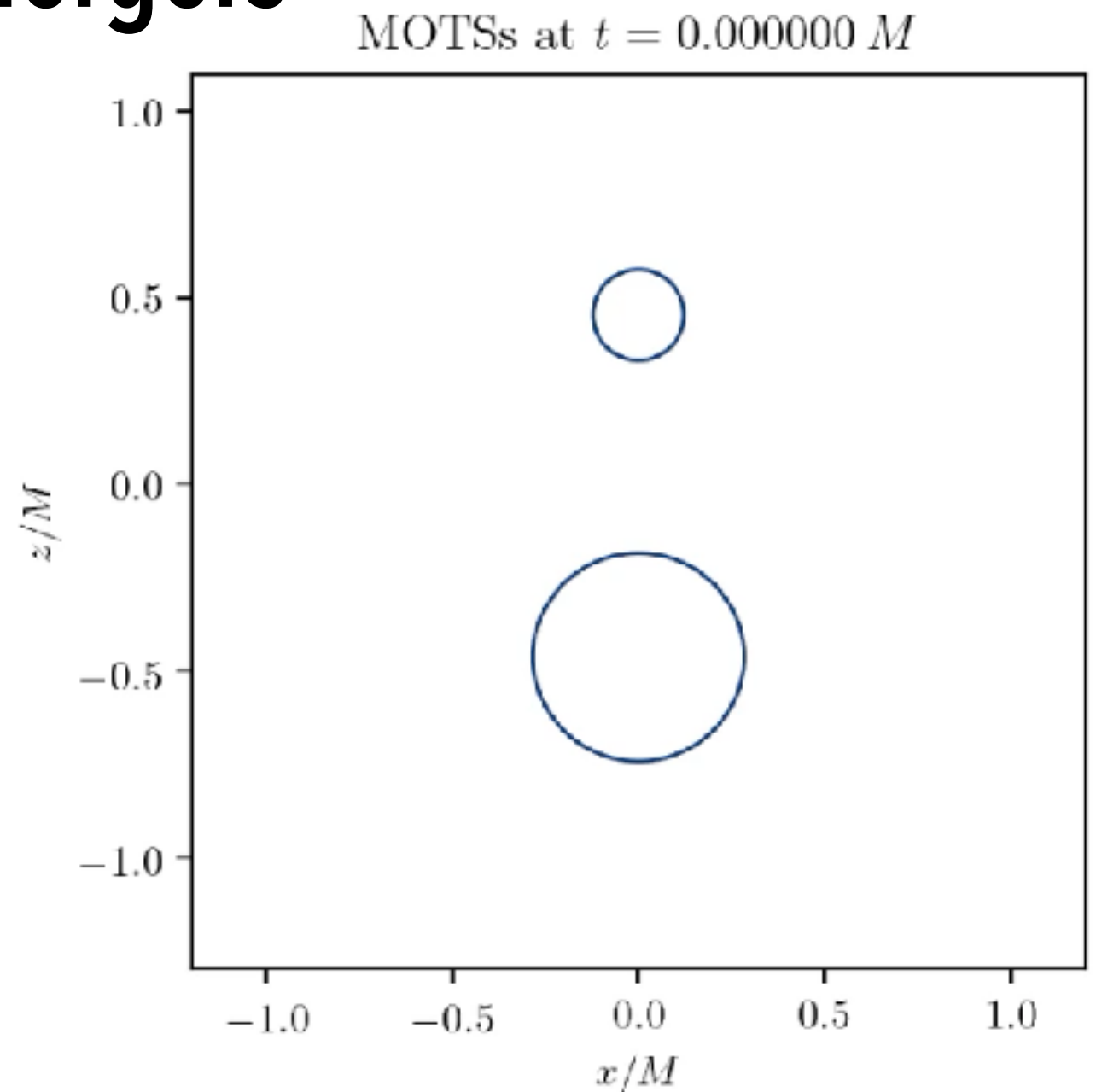
Blue = unstable MOTS

Fading = lost for numerical reasons

MOTS during black hole mergers



L_Σ has a vanishing eigenvalue at
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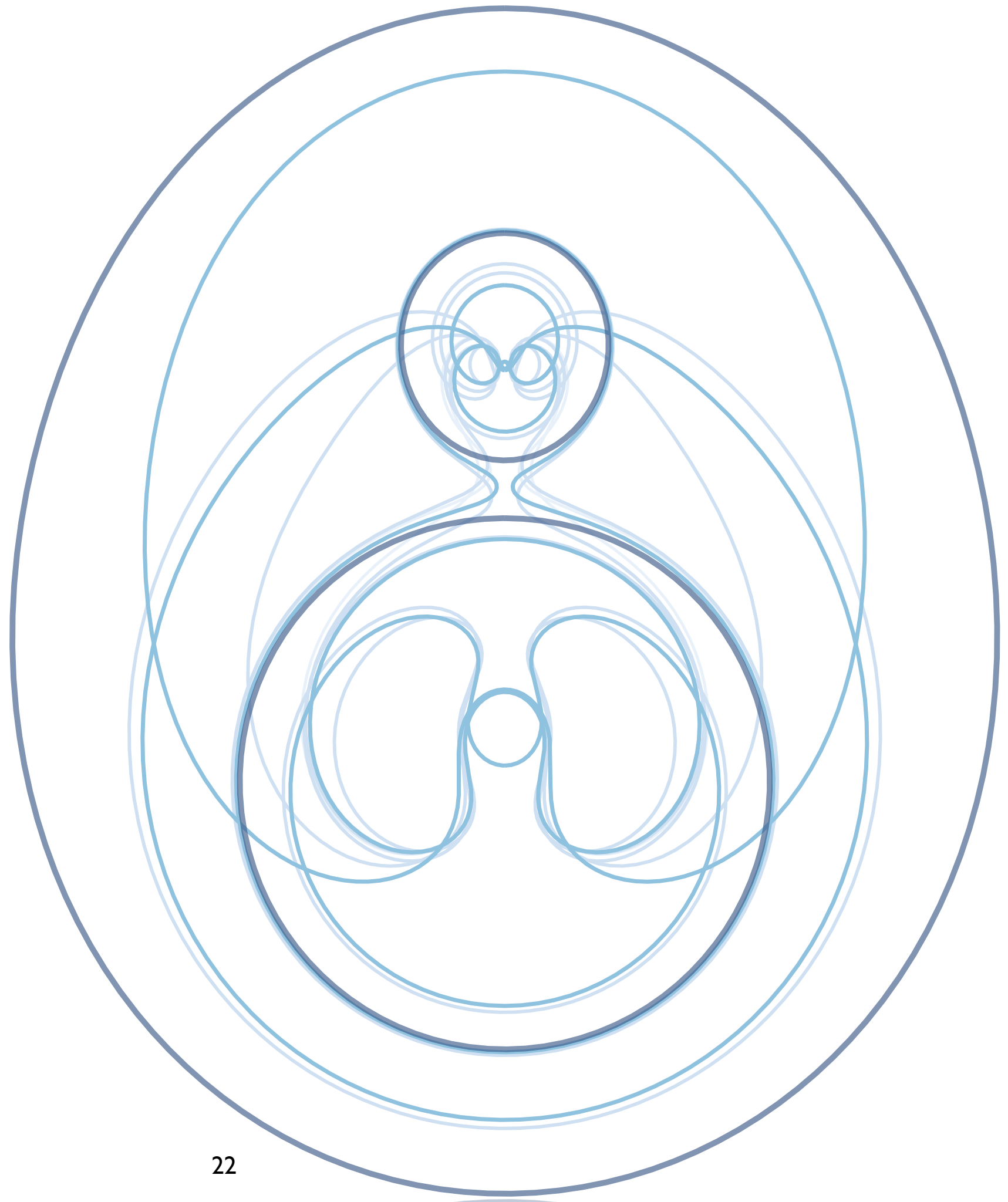


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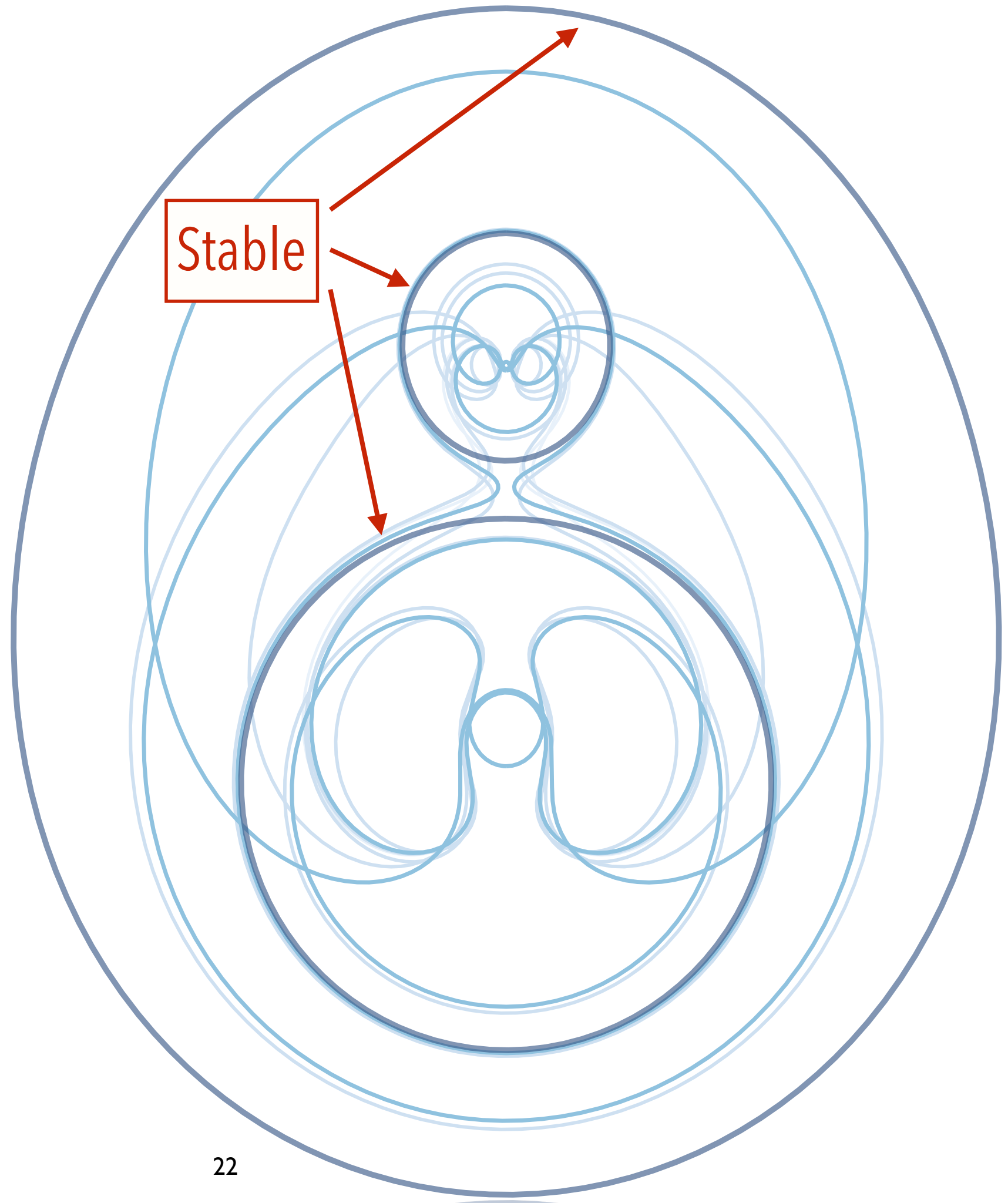
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Binary Mergers

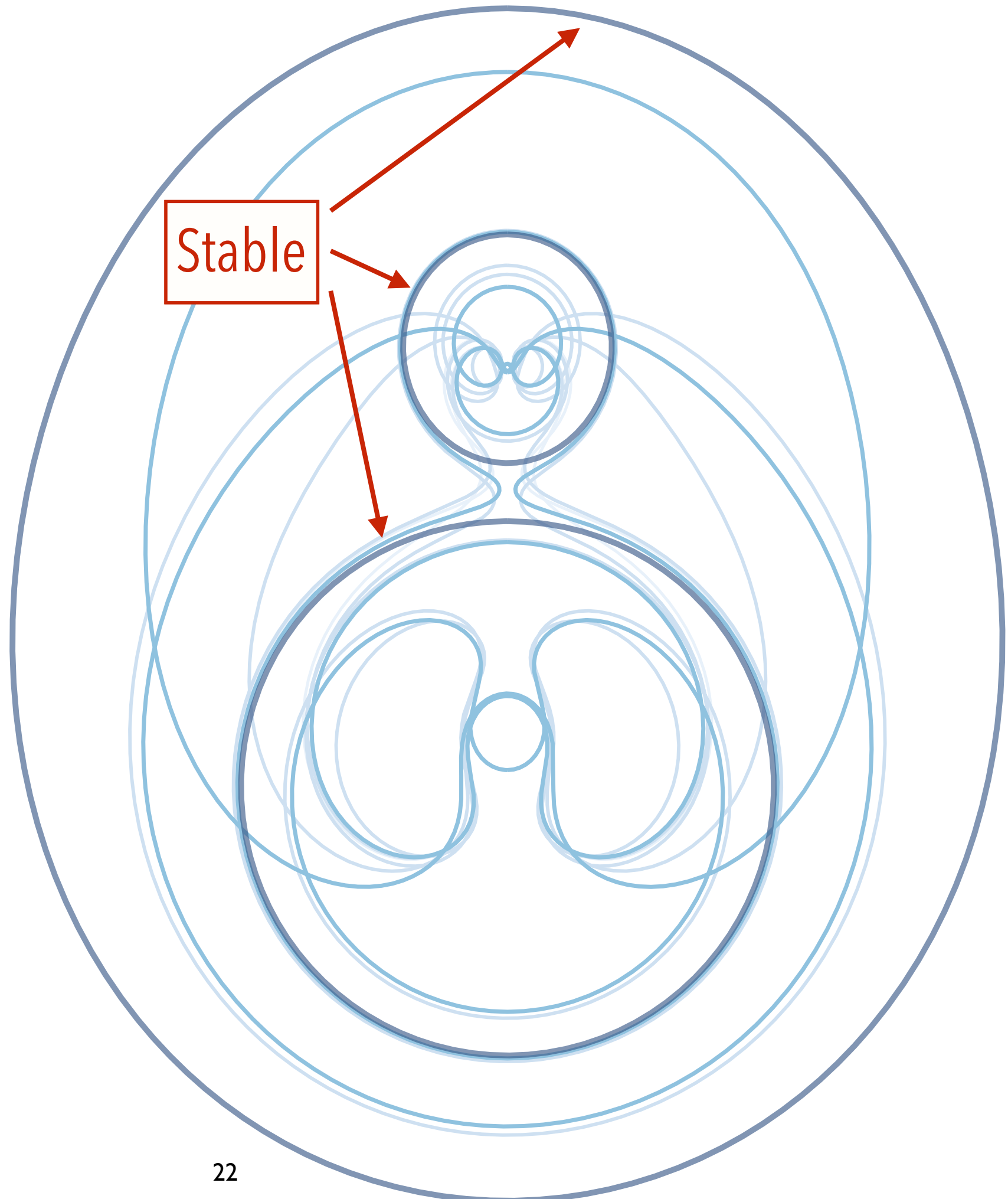


Binary Mergers



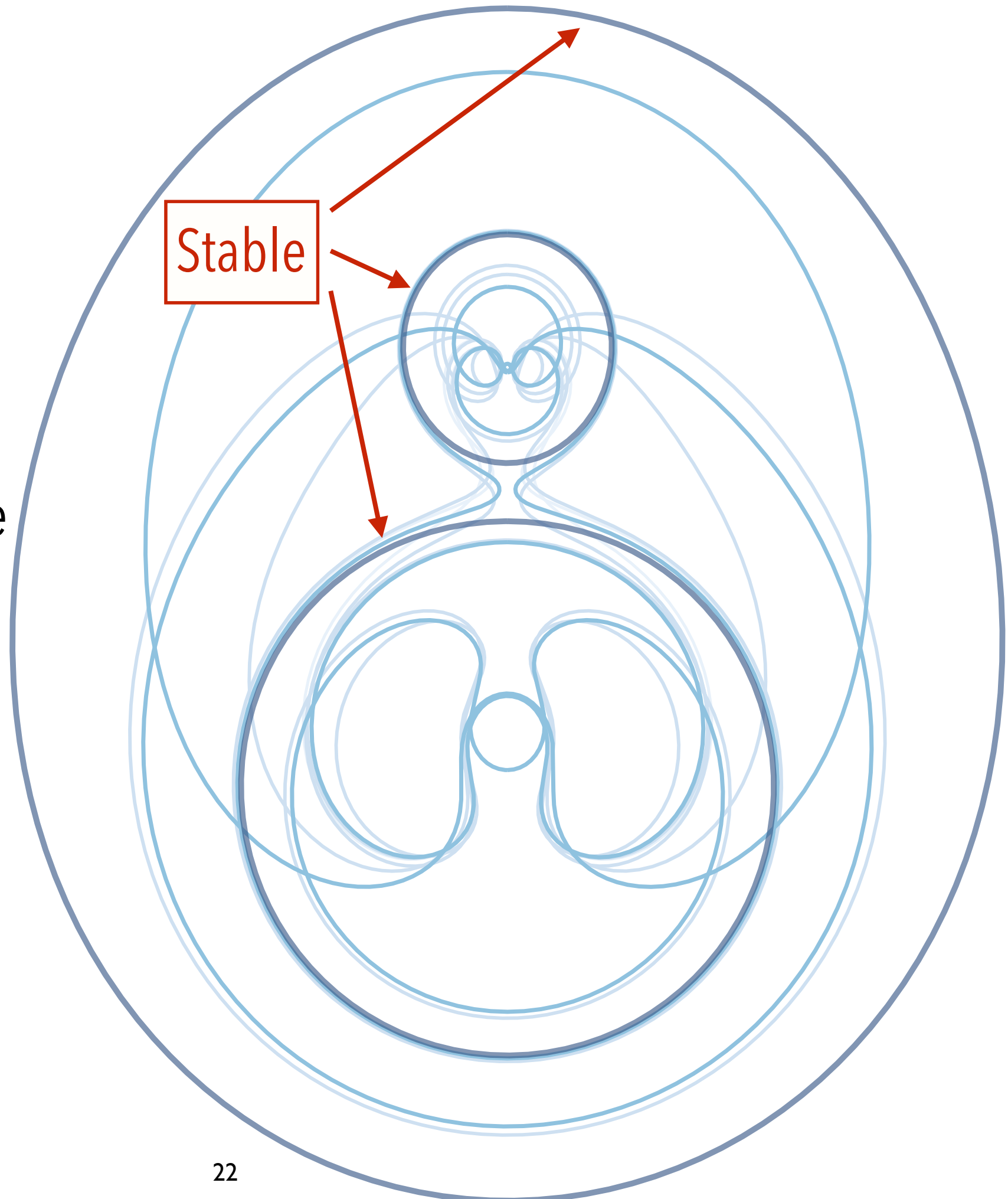
Binary Mergers

- Only the initial and final outer AHs are stable



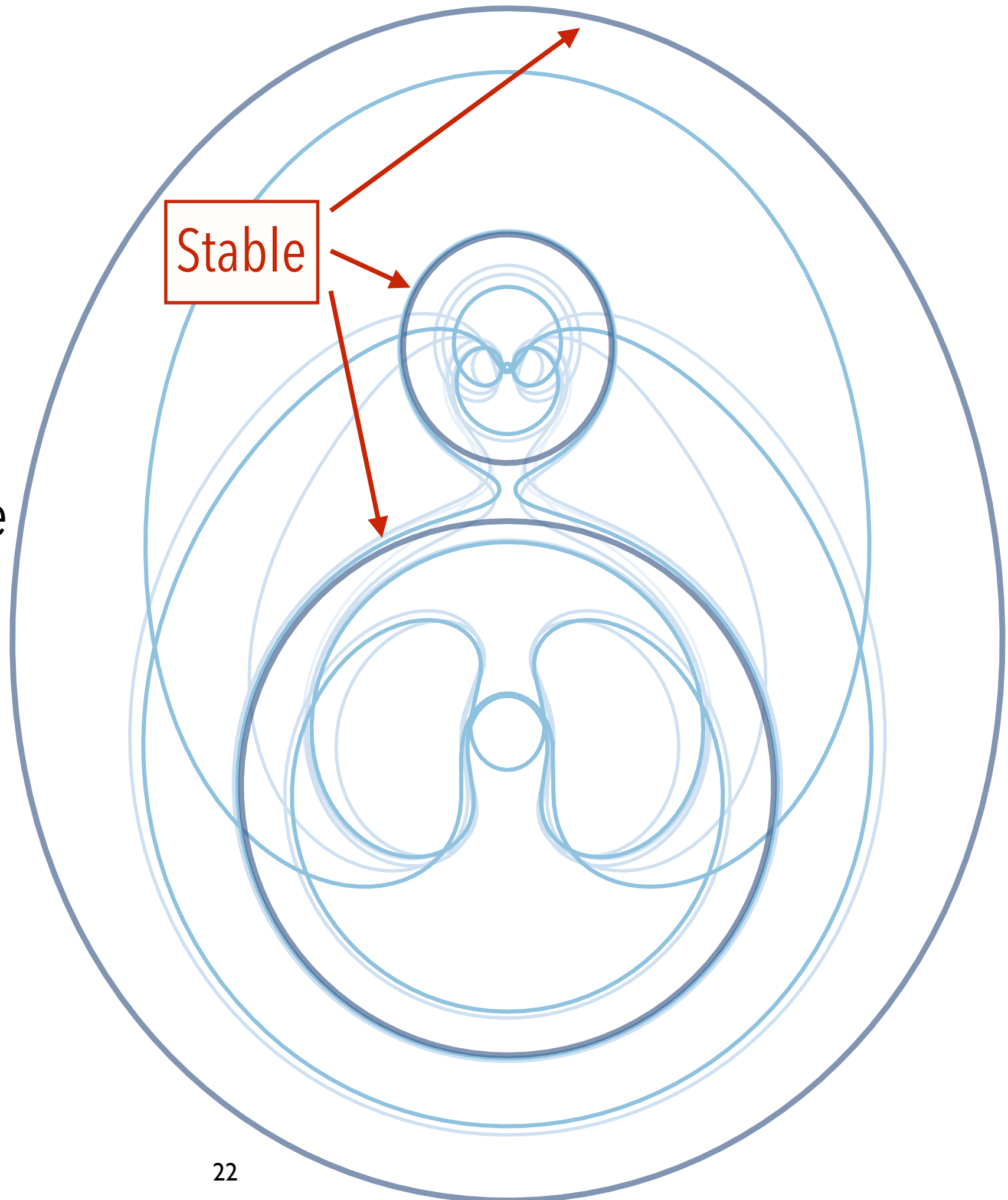
Binary Mergers

- Only the initial and final outer AHs are stable
- Other MOTS are unstable and do not bound trapped regions



Binary Mergers

- Only the initial and final outer AHs are stable
- Other MOTS are unstable and do not bound trapped regions
- Eigenvalues vanish at creation/annihilation events

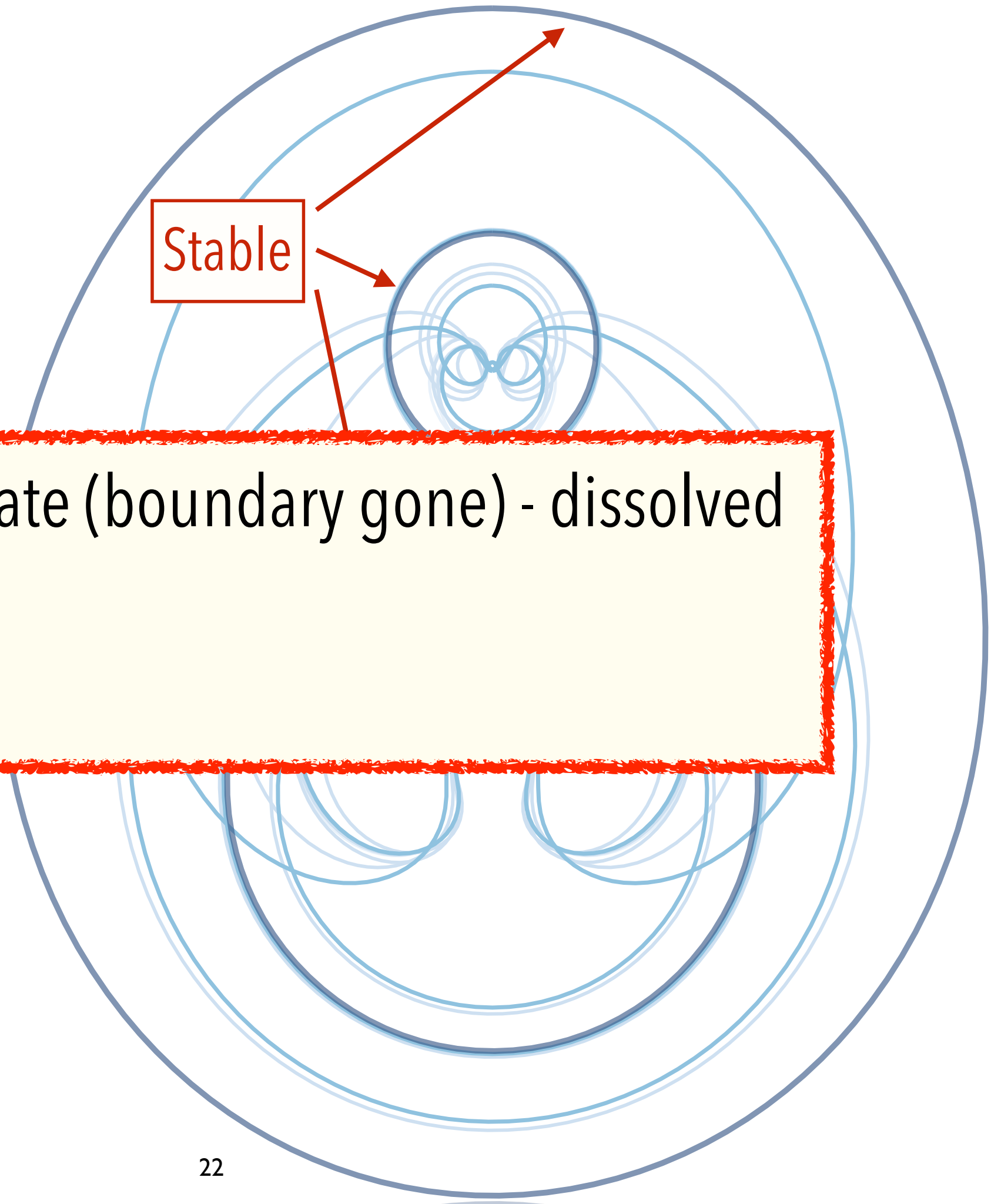


Binary Mergers

- Only the initial and final outer AHs are stable

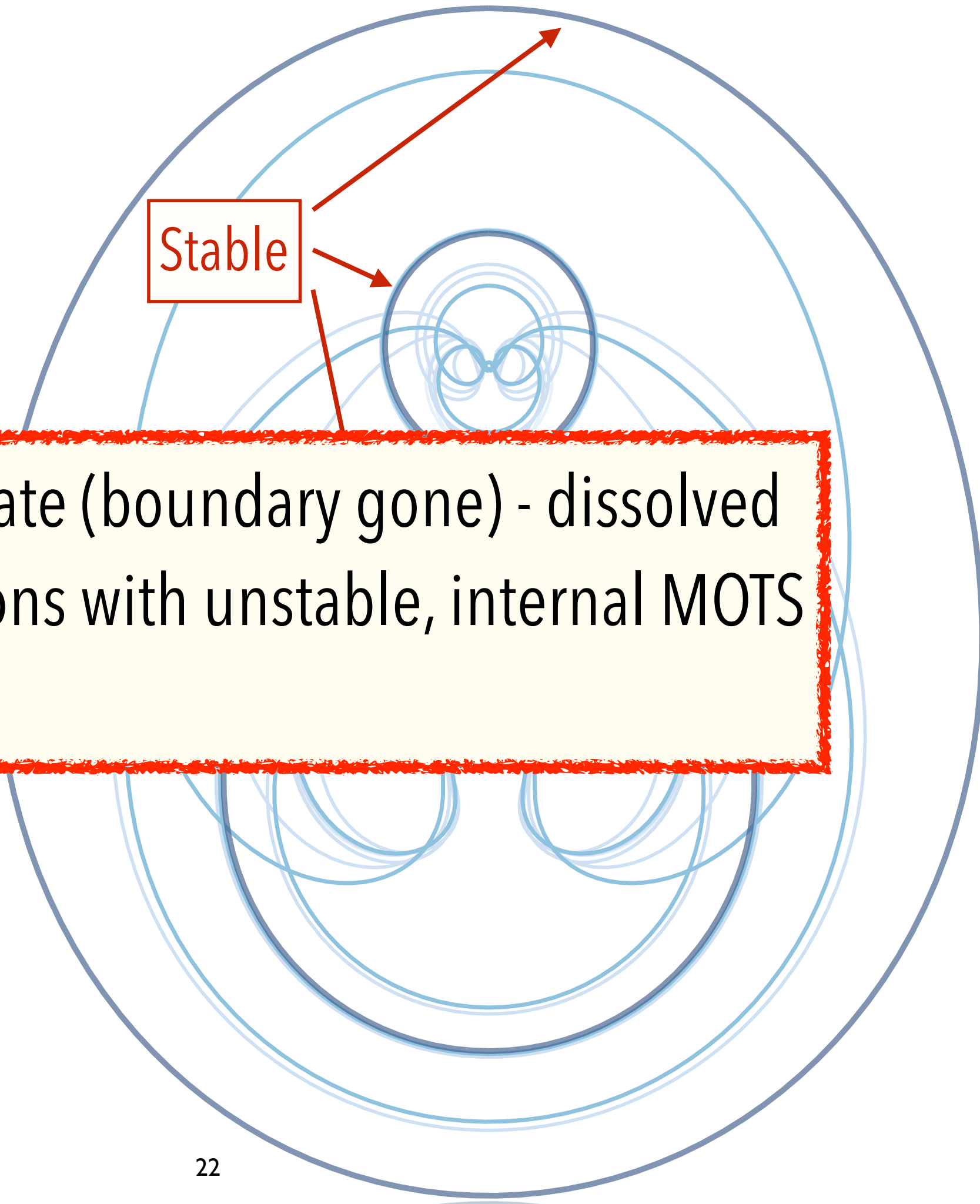
- MOTS can annihilate (boundary gone) - dissolved

- Eigenvalues vanish at creation/annihilation events



Binary Mergers

- Only the initial and final outer AHs are stable



The diagram illustrates the spacetime geometry during a binary black hole merger. It features several concentric, roughly circular lines representing apparent horizons (AHs) and marginally outer trapped surfaces (MOTS). A red box labeled 'Stable' has three arrows pointing to different regions: one points to the outermost AH, another points to a MOTS, and a third points to the region between them. A red arrow also points from the 'Stable' box towards the top right corner of the image.

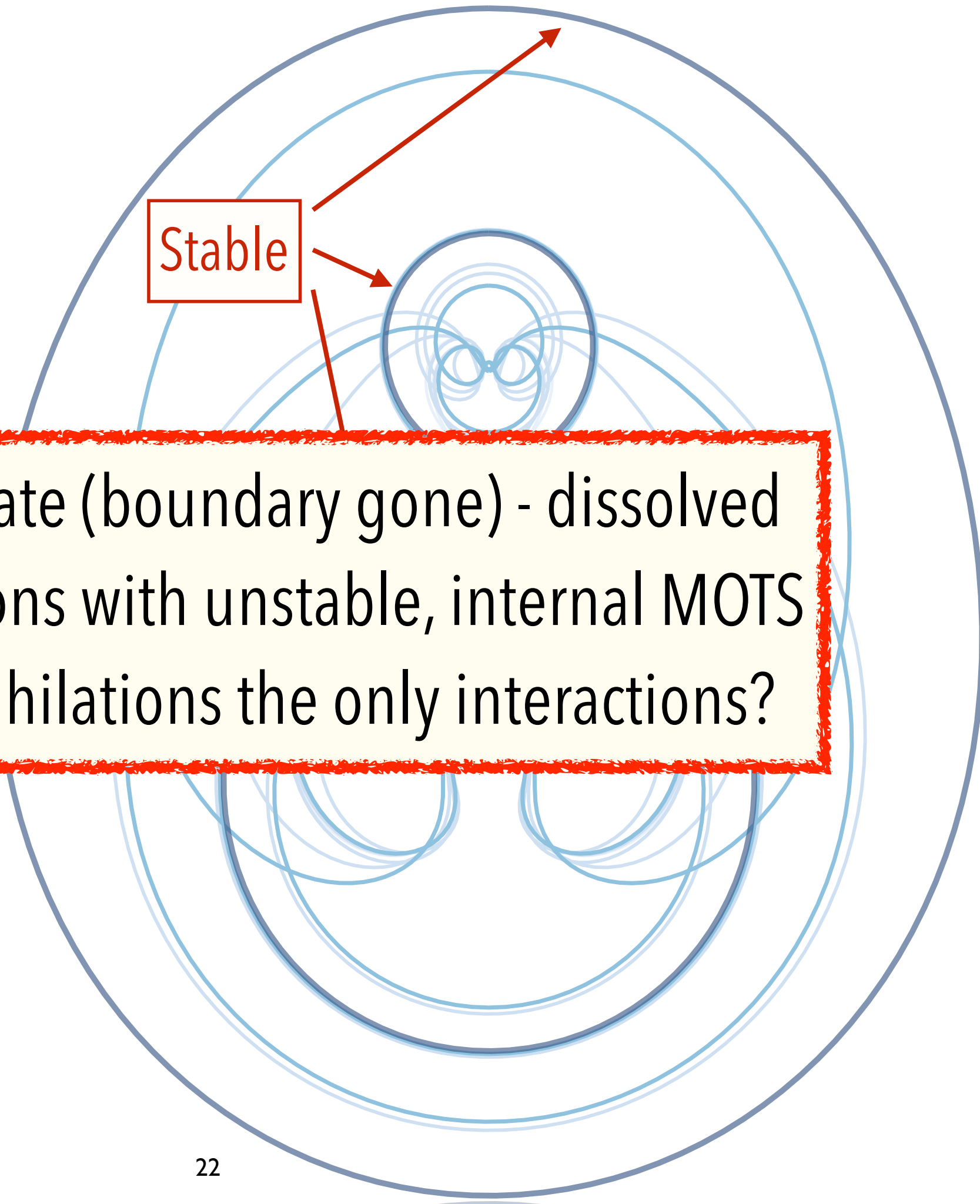
Stable

- MOTS can annihilate (boundary gone) - dissolved
 - Involves interactions with unstable, internal MOTS
- Eigenvalues vanish at creation/annihilation events

Binary Mergers

- Only the initial and final outer AHs are stable

Stable



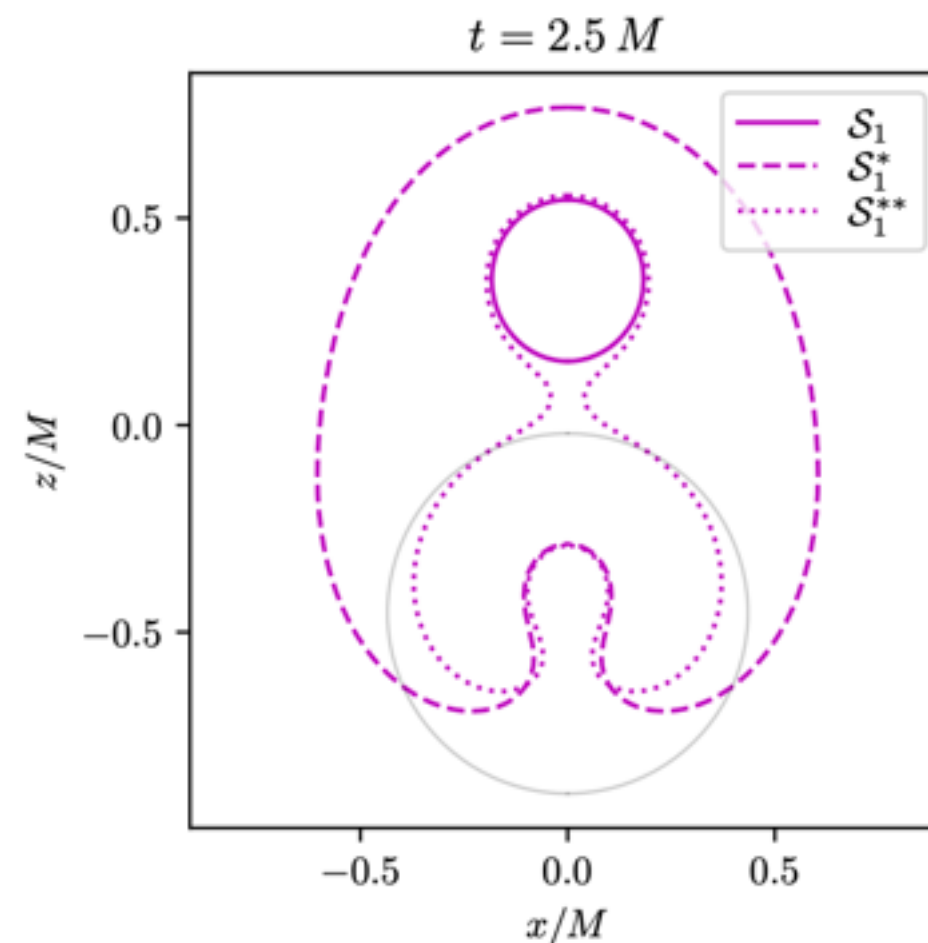
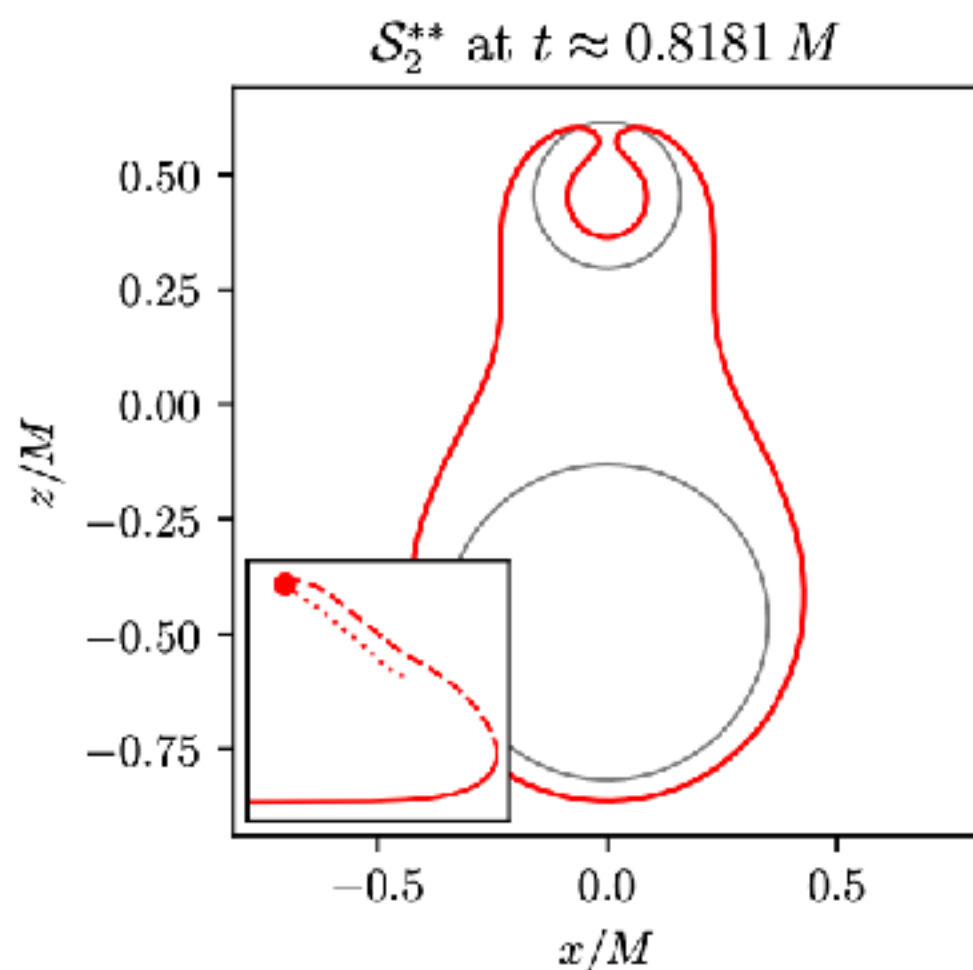
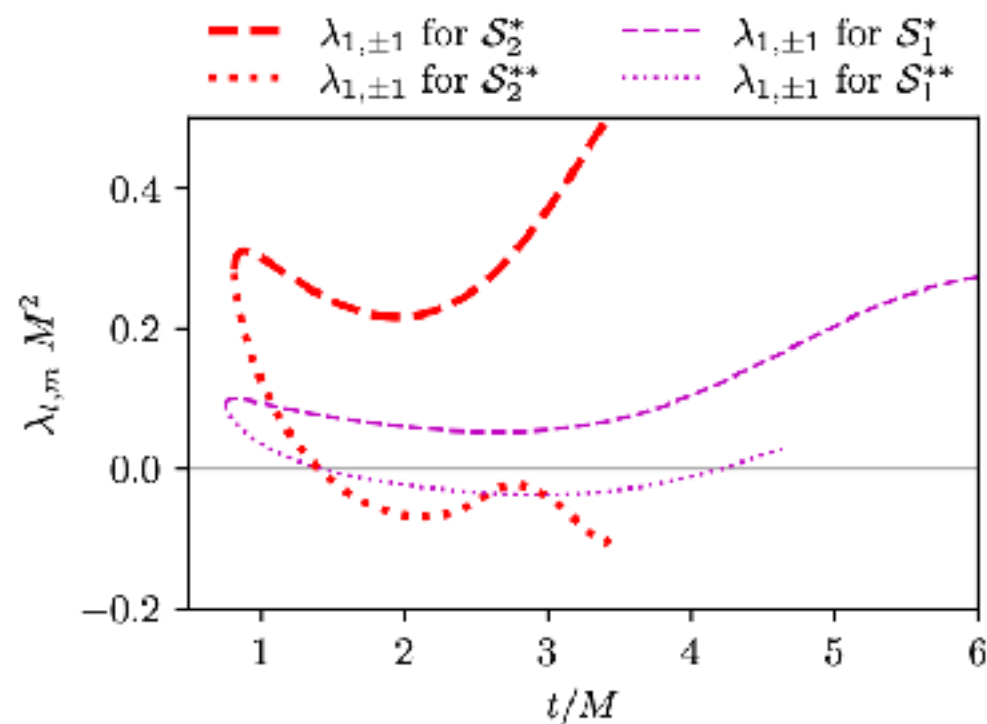
- - MOTS can annihilate (boundary gone) - dissolved
 - Involves interactions with unstable, internal MOTS
 - Are creations/annihilations the only interactions?
- Eigenvalues vanish at creation/annihilation events

Clue: Vanishing eigenvalues, smooth evolution

Pook-Kolb, Booth,
Hennigar, PRD 2021
"Ultimate fate...II.."

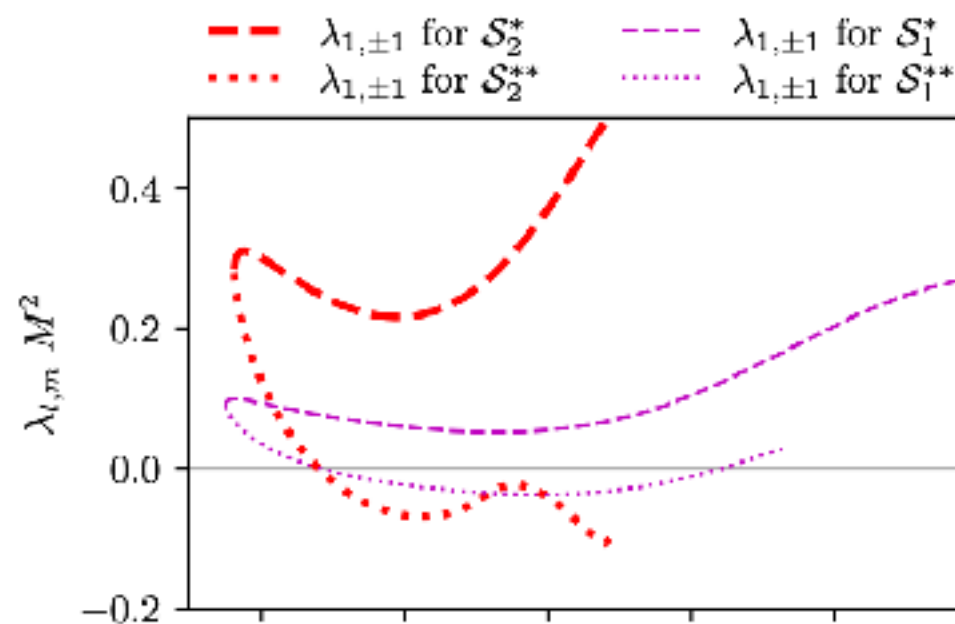
spacetime deformation

Non-axisymmetric
eigenvalues



Clue: Vanishing eigenvalues, smooth evolution

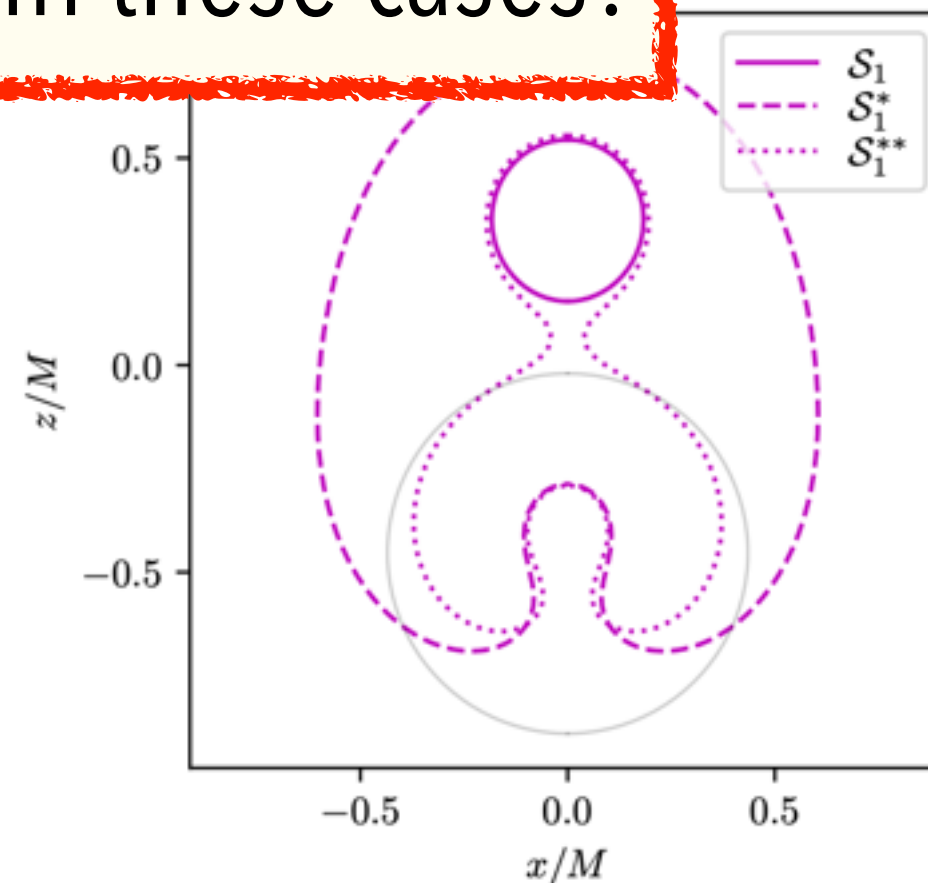
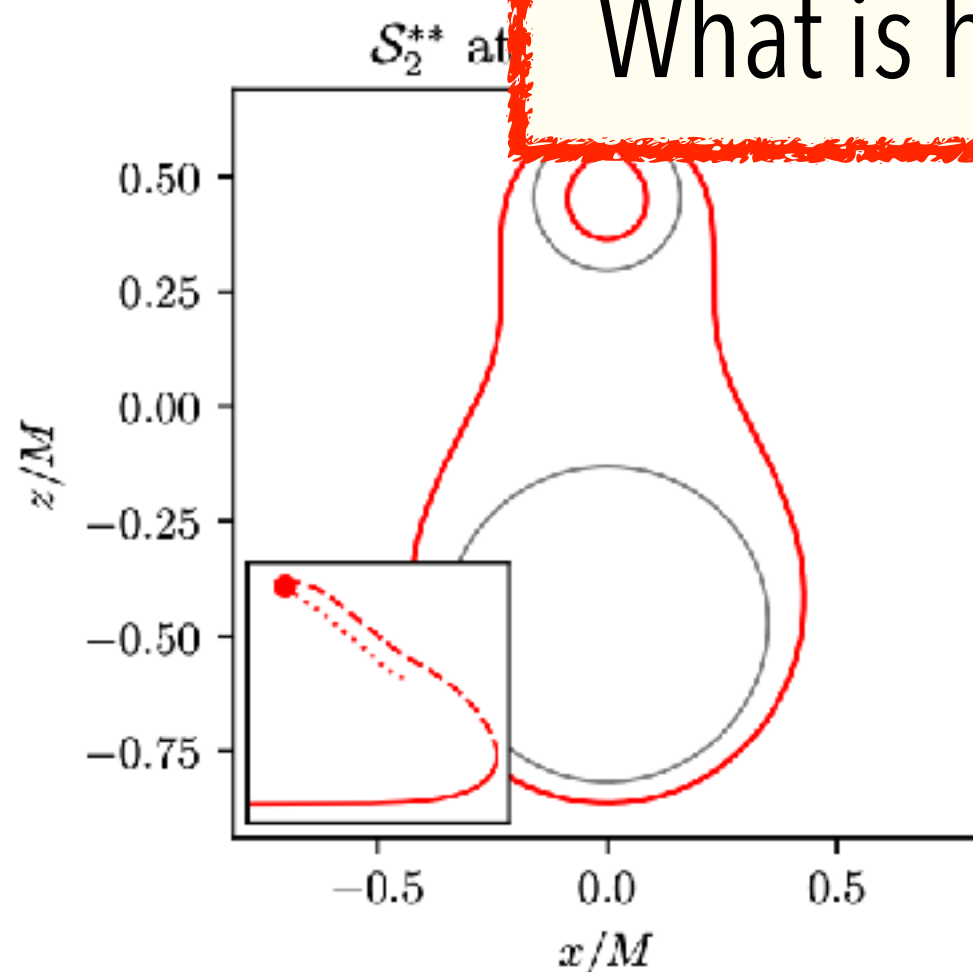
Pook-Kolb, Booth,
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spacetime deformation

Non-axisymmetric
eigenvalues

What is happening in these cases?



Recall bifurcation theory for dynamical systems...

Fixed points for differential equations

$$\dot{x} = \alpha + x^2$$

$$\dot{x} = x(\alpha + x)$$

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Recall bifurcation theory for dynamical systems...

Fixed points for differential equations

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$\alpha < 0$ has fixed points:

$$x_o = \pm \sqrt{|\alpha|}$$

$$\dot{x} = x(\alpha + x)$$

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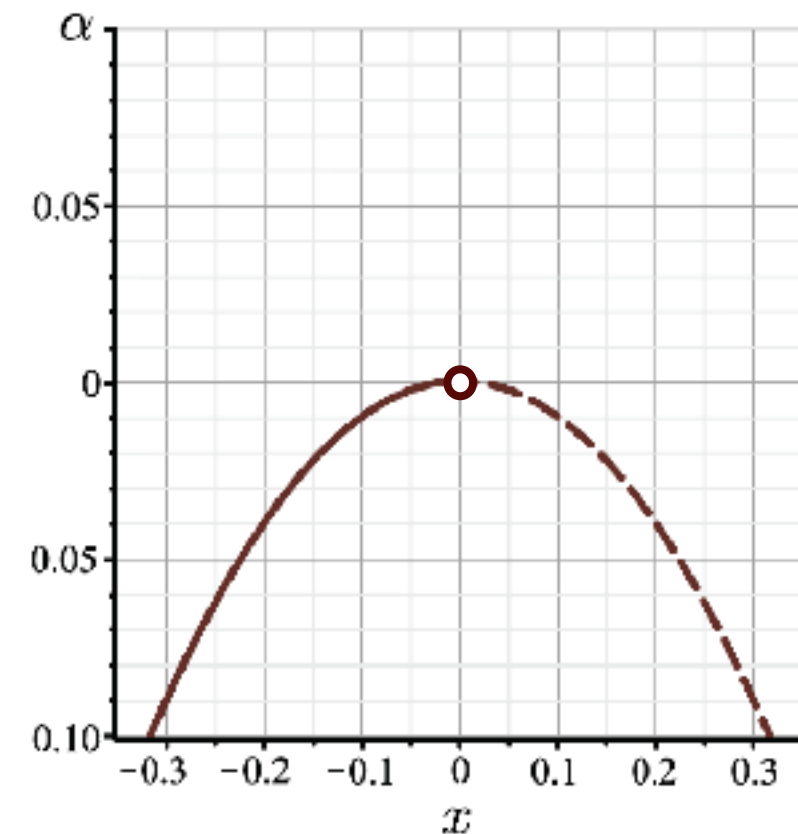
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Recall bifurcation theory for dynamical systems...

Fixed points for differential equations

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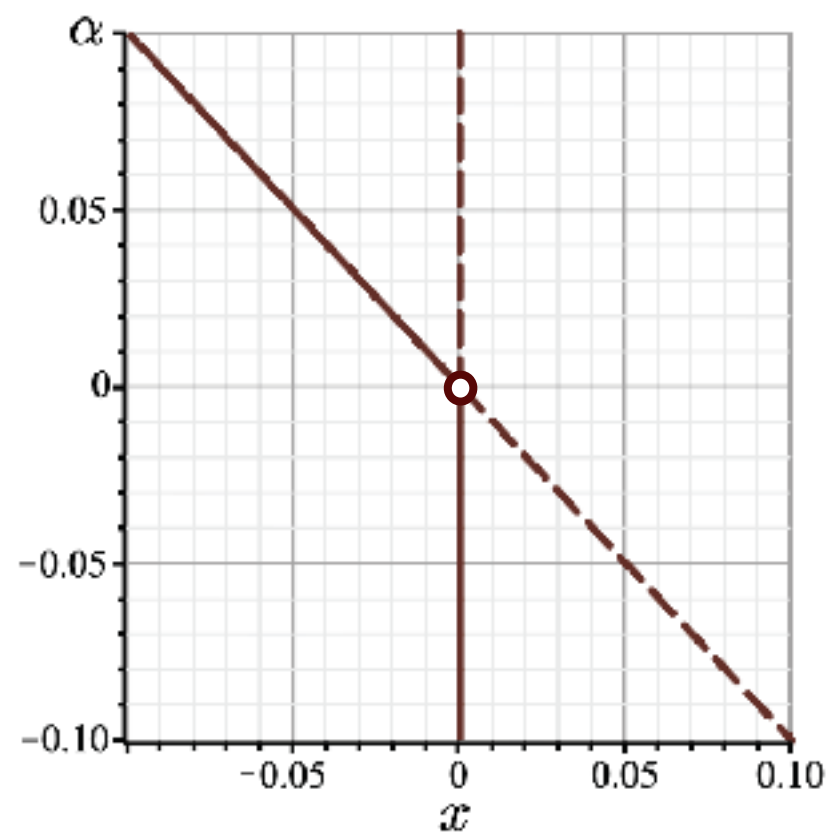
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a) Saddle-node

$$\dot{x} = x(\alpha + x)$$

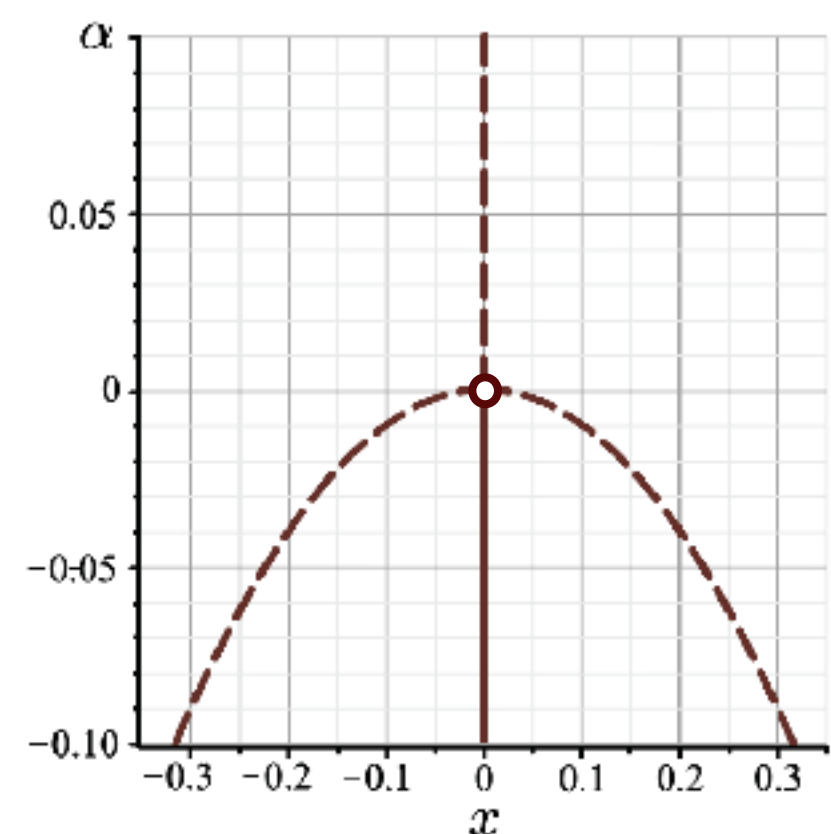
fixed points:
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b) Transcritical

$$\dot{x} = x(\alpha + x^2)$$

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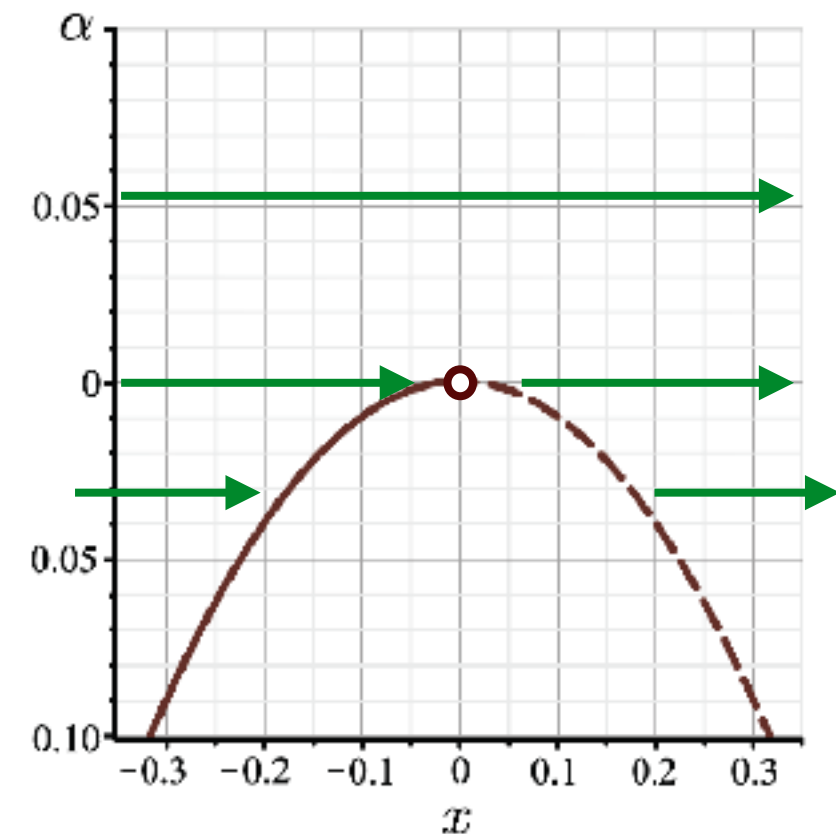
c) Pitchfork

Recall bifurcation theory for dynamical systems...

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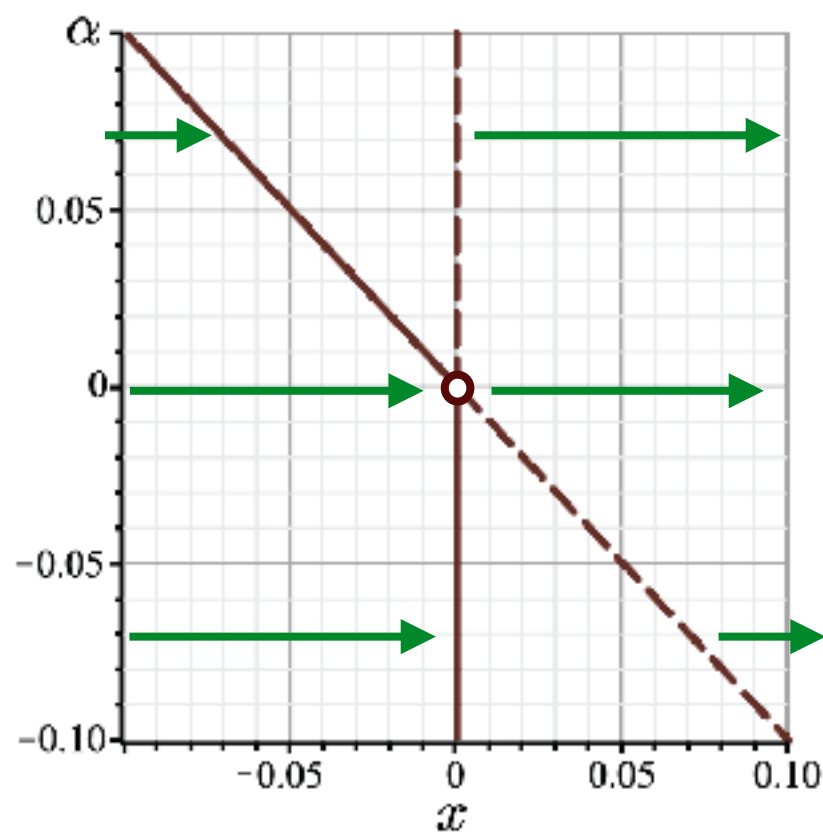
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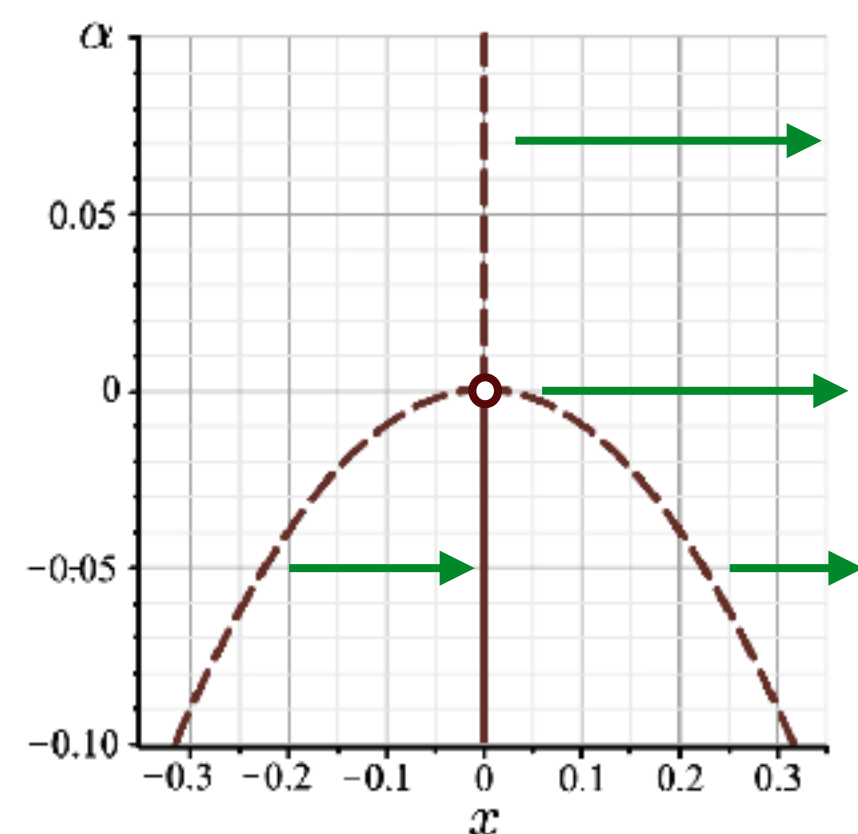
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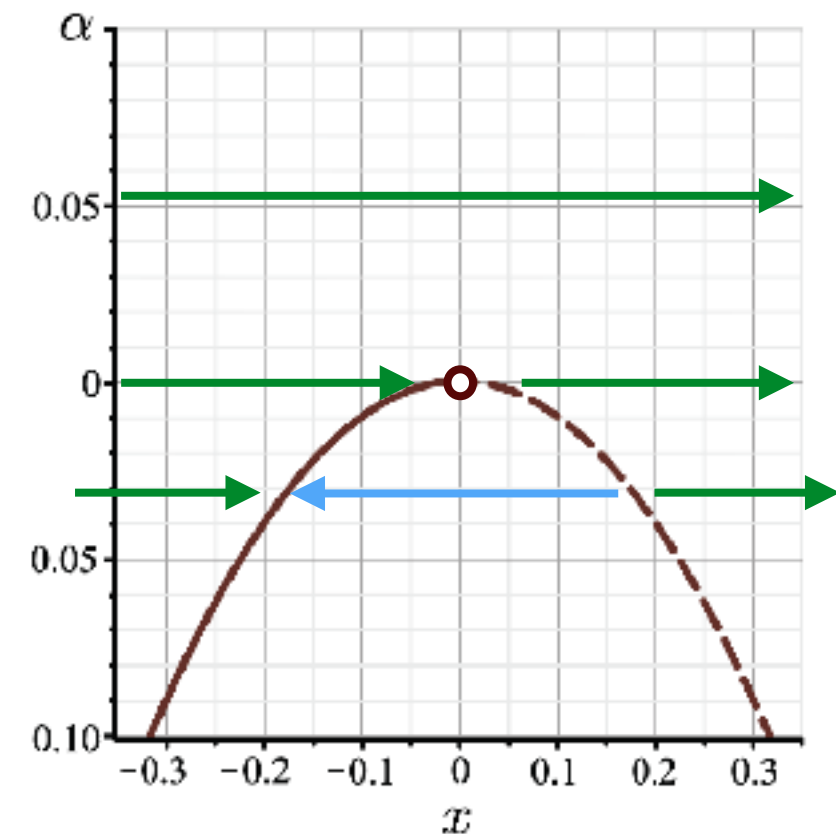
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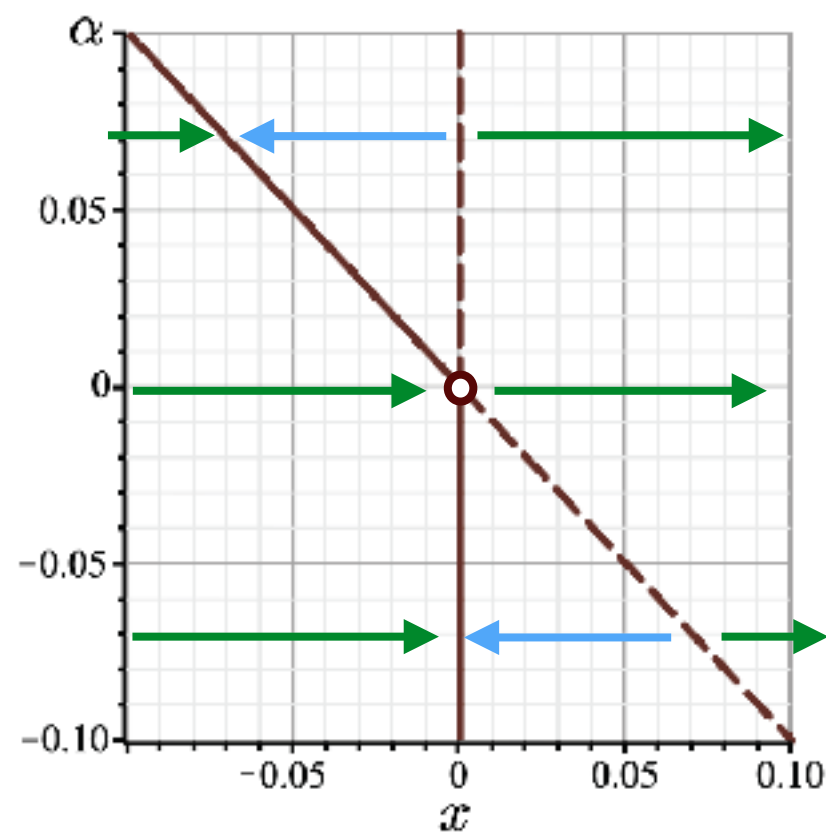
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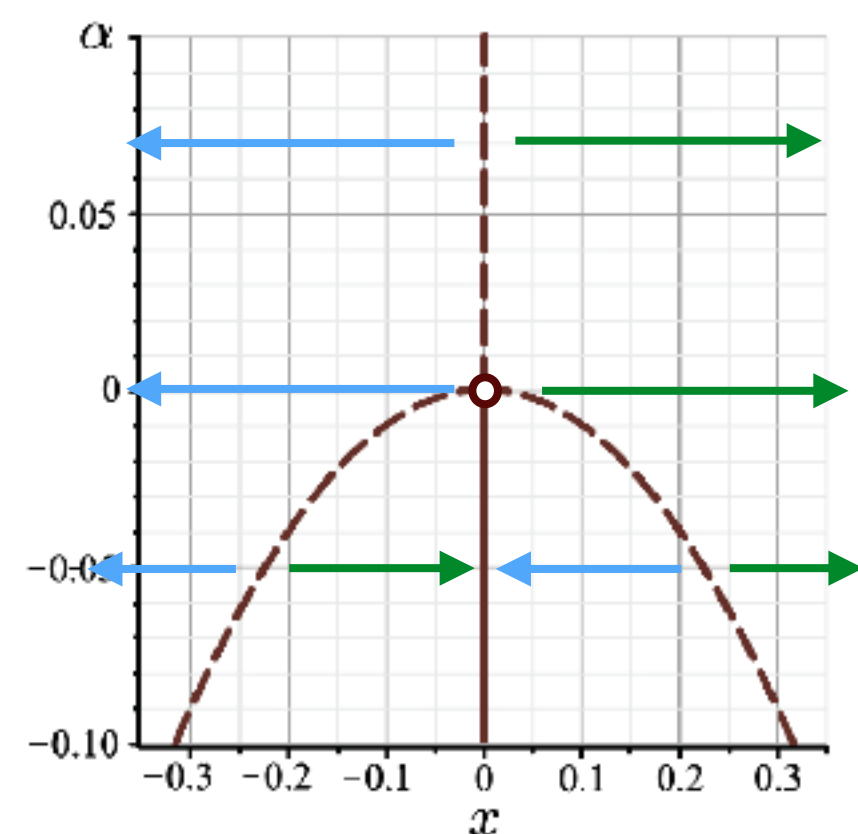
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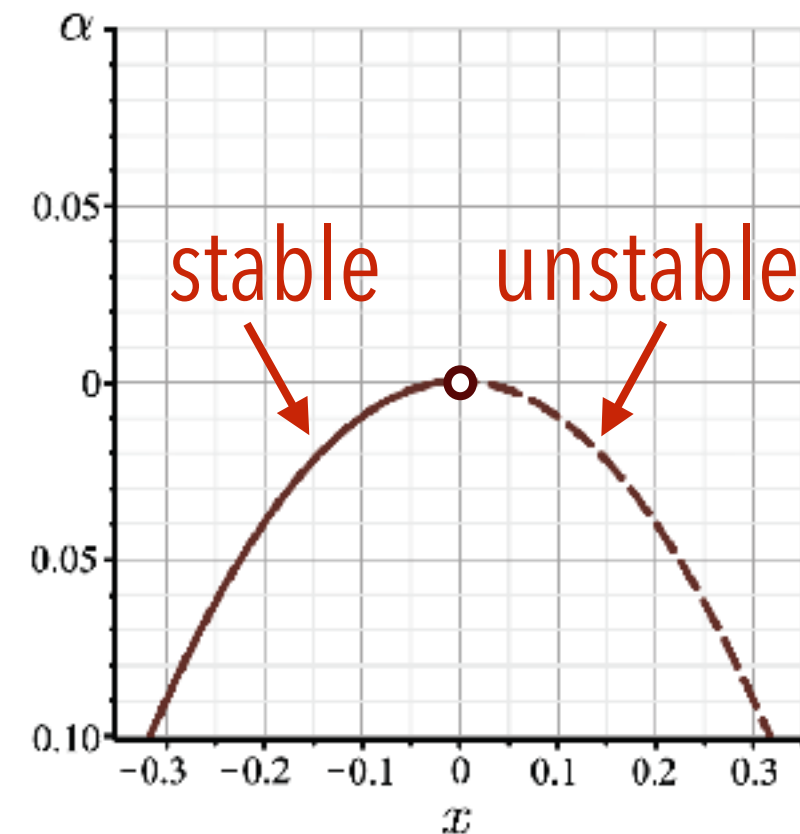
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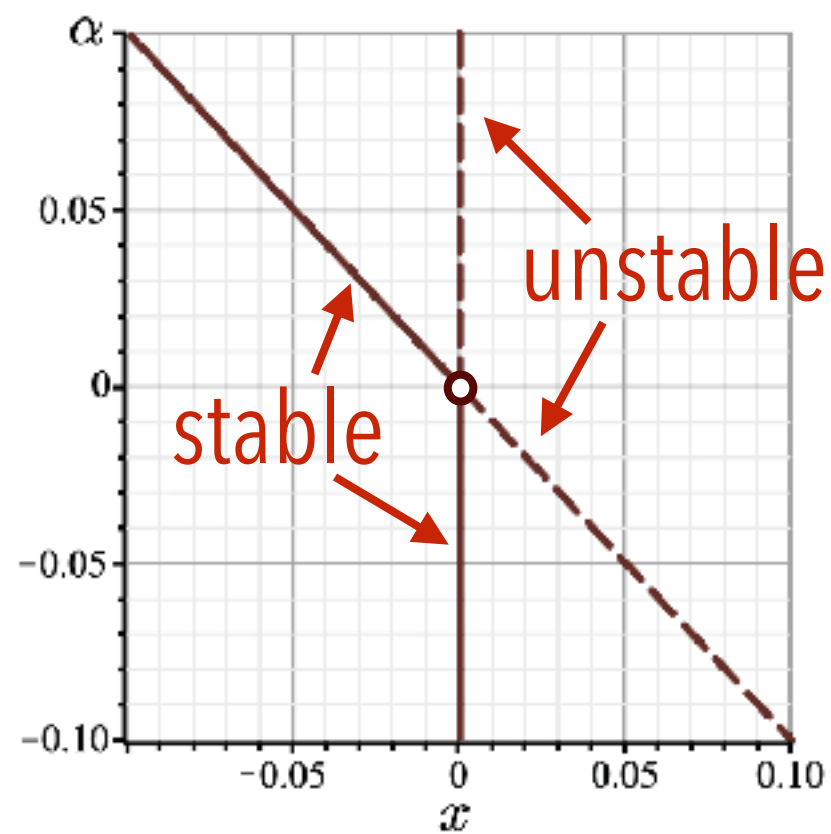
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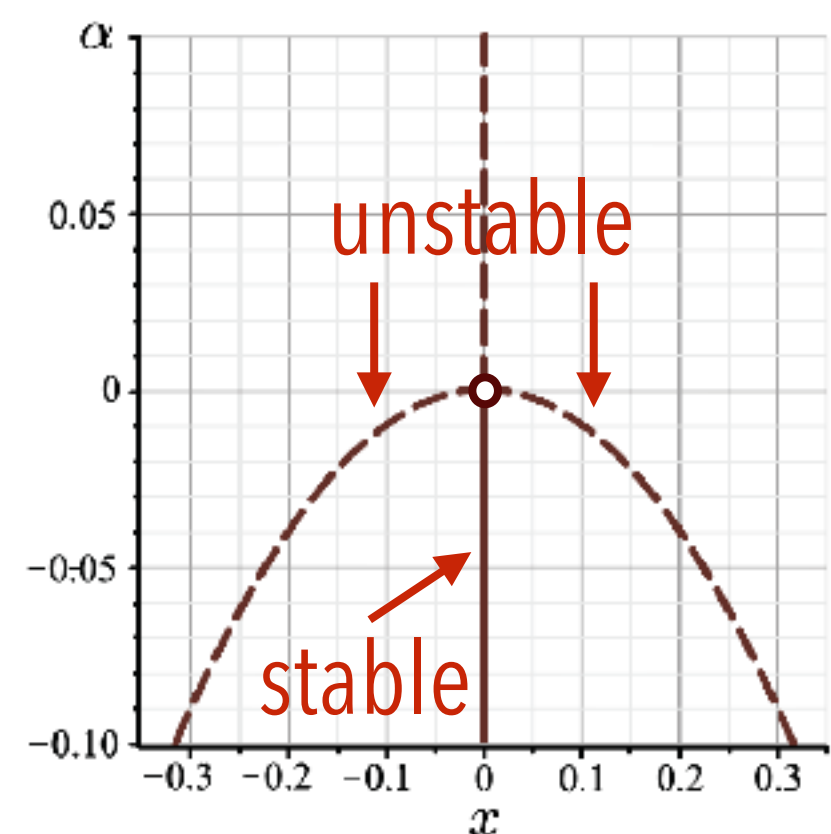
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so that $f^i(\alpha, X^j(\alpha)) = 0$:

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- If Df has a vanishing eigenvalue, $\frac{dX^j}{d\alpha}$ is unconstrained in that direction.
- Vanishing eigenvalue $\iff$ non-invertible $\iff$ bifurcation point

And now: bifurcation theory for MOTSs - fix notation

ODEs

MOTSs

And now: bifurcation theory for MOTSs - fix notation

ODEs

MOTSs

Phase space

coordinates: x^i

(finite dimensional)

surfaces S : $X^\beta(\theta, \phi)$

(infinite dimensional)

And now: bifurcation theory for MOTSs - fix notation

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Linearization

$$x^i \rightarrow x^i + \epsilon \Delta x^i$$

$$X^\beta \rightarrow X^\beta + \epsilon \psi N^\beta$$

And now: bifurcation theory for MOTSs - fix notation

	<u>ODEs</u>	<u>MOTSs</u>
Phase space	coordinates: x^i (finite dimensional)	surfaces S : $X^\beta(\theta, \phi)$ (infinite dimensional)
Fixed points	$f^j(\alpha, x^i) = 0$	$\theta_\ell(X^\beta(\theta, \phi)) = 0$
Linearization	$x^i \rightarrow x^i + \epsilon \Delta x^i$ $(\partial_\alpha f^i) \Delta \alpha + [Df]_j^i \Delta x^j = 0$	$X^\beta \rightarrow X^\beta + \epsilon \psi N^\beta$ $(\delta_\alpha \theta_+) \Delta \alpha + L_S \psi = 0$

And now: bifurcation theory for MOTSs - fix notation

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MOTSs

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Stability

all eigenvalues of Df
negative

all eigenvalues of L_S
positive

opposite name
conventions!!!

And now: bifurcation theory for MOTSs - fix notation

ODEs

MOTSs

Phase space

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vanishing λ_ν of Df

vanishing λ_ν of L_S

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And now: bifurcation theory for MOTSs - fix notation

ODEs

MOTSs

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surfaces S : $X^\beta(\theta, \phi)$
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vanishing λ_ν of Df

vanishing λ_ν of L_S

"Direction" of
bifurcation

eigenvector v_ν

eigenfunction ψ_ν

opposite name
conventions!!!

Spherical Symmetry

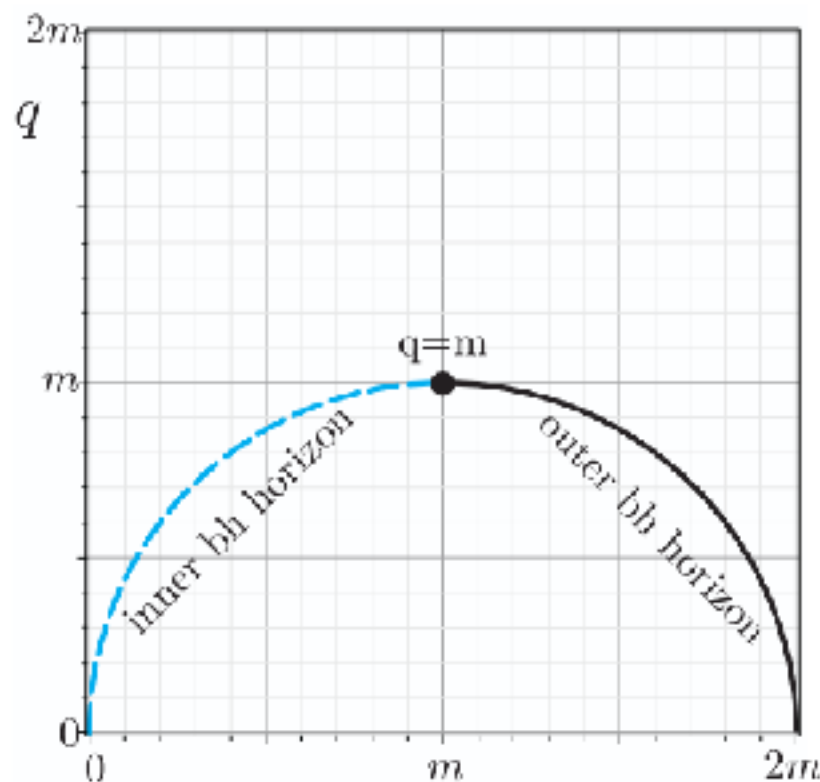
Reissner-Nordström-deSitter

$$ds^2 = -F dv^2 + 2dvdr + r^2 d\Omega^2$$

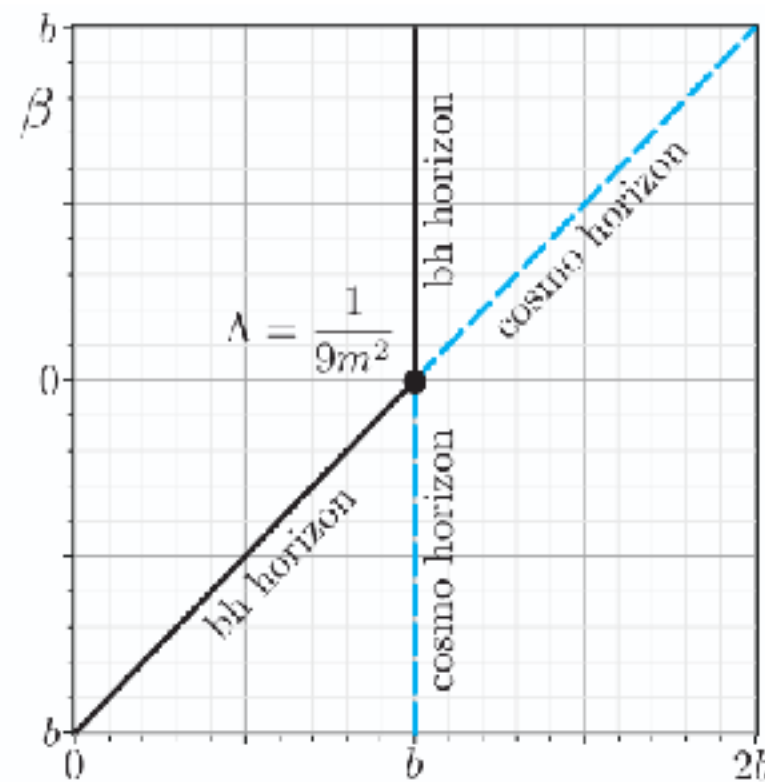
$$F = -\frac{\Lambda}{3}r^2 + 1 - \frac{2m}{r} + \frac{q^2}{r^2} \quad \text{for functions } \Lambda(\alpha), m(\alpha), q(\alpha)$$

MOTSs bifurcations are **exactly** ODE bifurcations (modulo naming) with

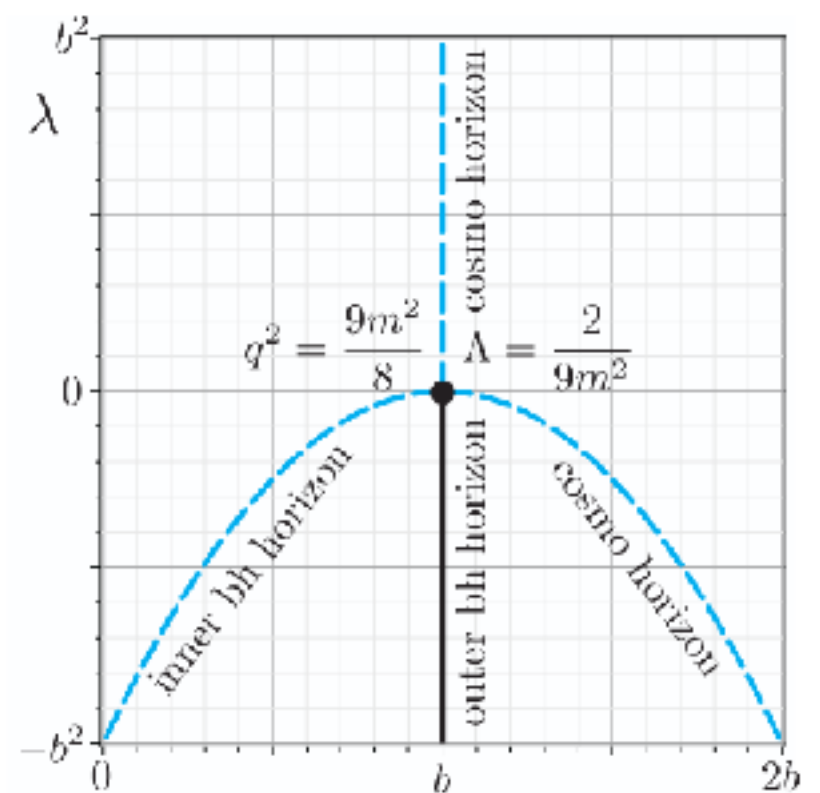
$$\dot{r} = \frac{dr}{dv} = f = \frac{F}{2} \quad (\text{radial null geodesics})$$



a) Reissner-Nordström:
saddle-node



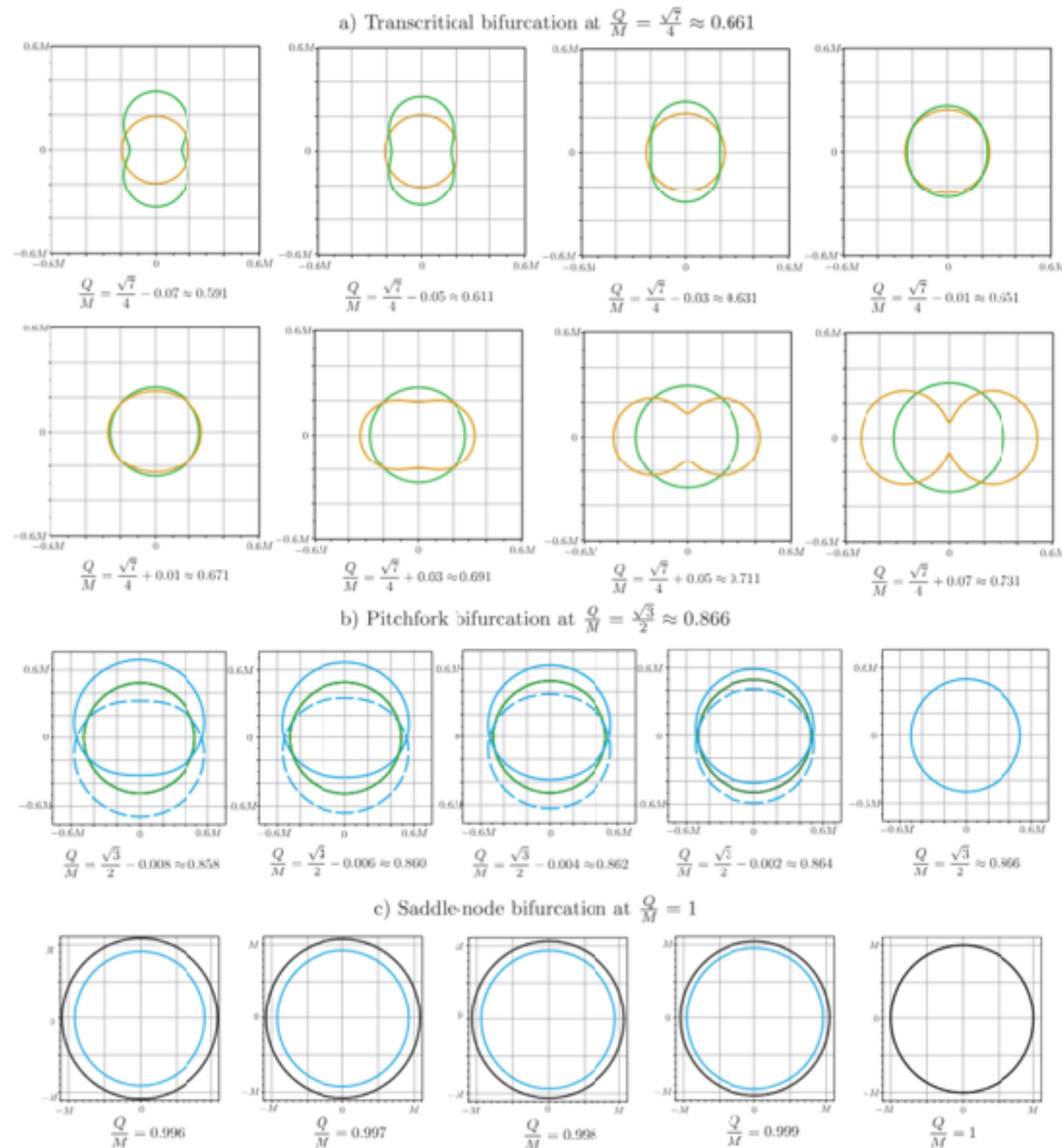
b) Schwarzschild-deSitter:
transcritical



c) Reissner-Nordström-deSitter:
pitchfork

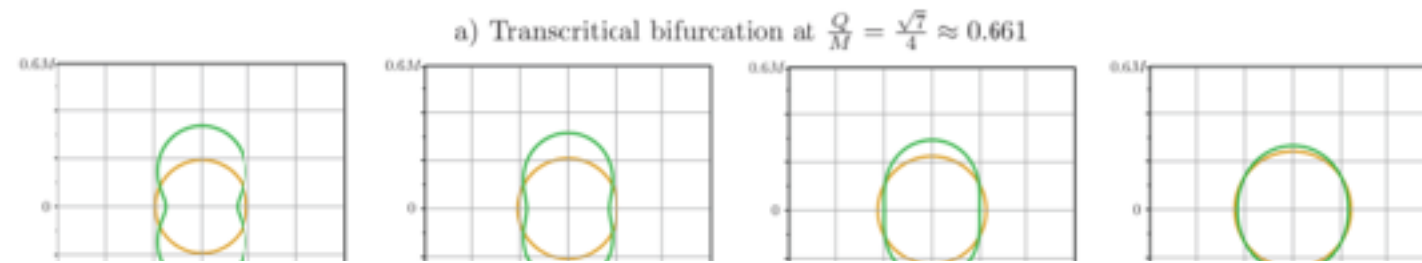
Axi-symmetric
bifurcations
from
spherical symmetry

Back to Reissner-Nordström: order emerges



Axi-symmetric
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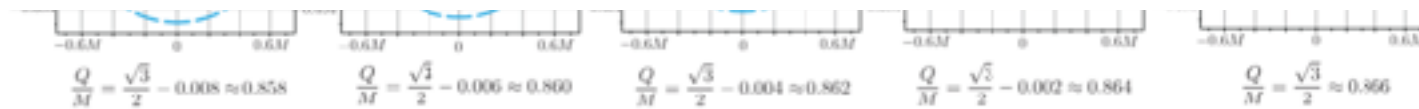
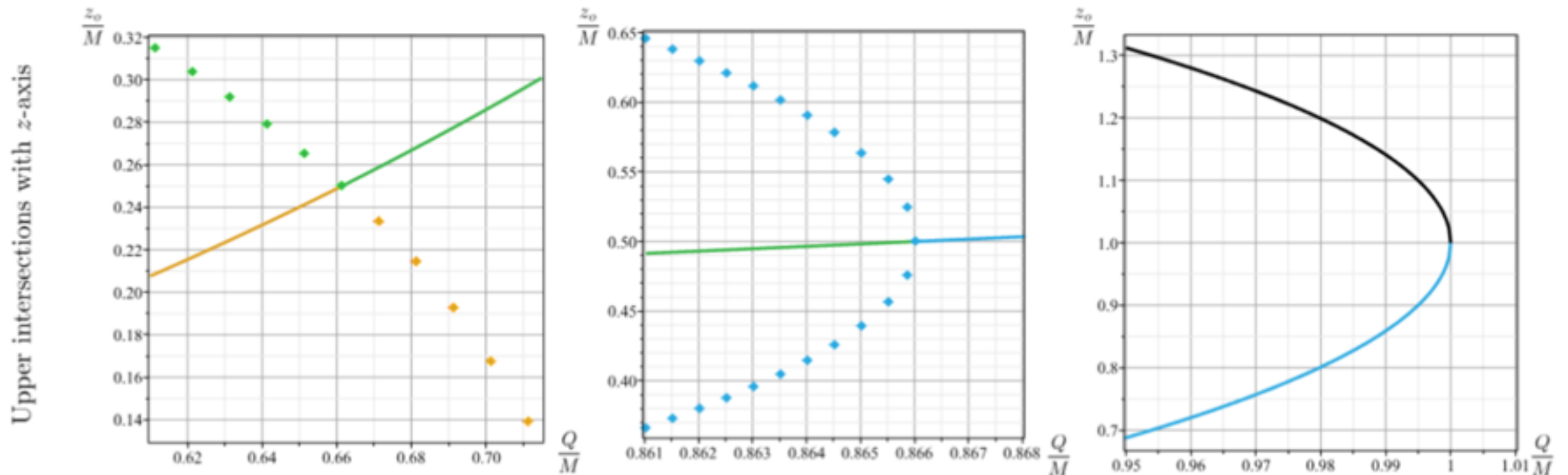
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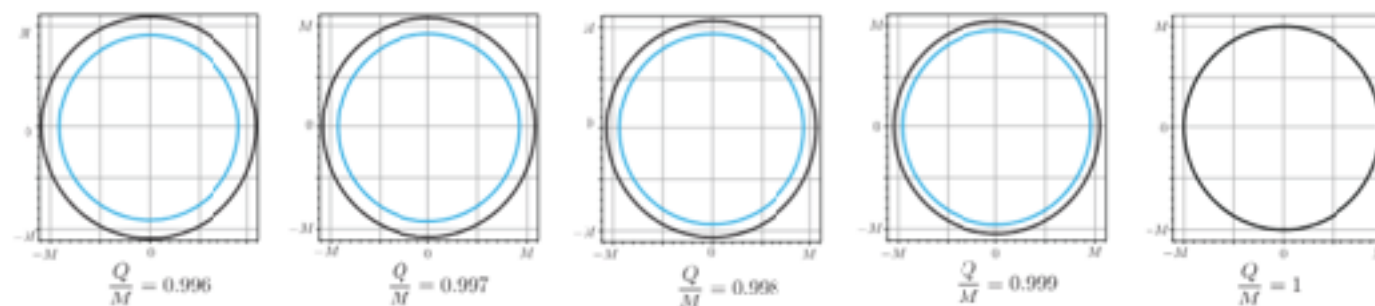
a) Transcritical bifurcation at $\frac{Q}{M} = \frac{\sqrt{7}}{4}$

b) Pitchfork bifurcation at $\frac{Q}{M} = \frac{\sqrt{3}}{2}$

c) Saddle-node bifurcation at $\frac{Q}{M} = 1$



c) Saddle-node bifurcation at $\frac{Q}{M} = 1$



Weyl-Schwarzschild

- All static, axisymmetric metrics can be written in the form

$$ds^2 = -e^U dt^2 + e^{-2U+2V} (dz^2 + d\rho^2) + e^{-2U} \rho^2 d\phi^2$$

where $U = U(\rho, z)$ and $V = V(\rho, z)$.

- These are vacuum solutions if U is a solution of the flat space Laplace equation:

$$\frac{\partial^2 U}{\partial \rho^2} + \frac{1}{\rho} \frac{\partial U}{\partial \rho} + \frac{\partial^2 U}{\partial z^2} = 0$$

$$\text{and } \frac{\partial V}{\partial \rho} = \rho \left(\left[\frac{\partial U}{\partial \rho} \right]^2 + \left[\frac{\partial U}{\partial z} \right]^2 \right), \quad \frac{\partial V}{\partial z} = 2\rho \frac{\partial U}{\partial \rho} \frac{\partial U}{\partial z}.$$

- U solutions can be classified in the usual way: monopole, dipole, quadrupole, octopole etc.

Weyl-distorted Schwarzschild

$$ds^2 = -e^{2U} \left(1 - \frac{2m}{r}\right) + e^{-2U+2V} \left(\frac{dr^2}{1 - \frac{2m}{r}} + r^2 d\theta^2\right) + e^{-2U} r^2 \sin^2 \theta d\phi^2$$

- If we demand no conical singularities on the horizon and deform from infinity, then the metric on the horizon at $r=2m$ is:

$$dS^2 = 4m^2 e^{-2U} (e^{4U-4u_o} d\theta^2 + \sin^2 \theta d\phi^2)$$

where $U(2m, \theta) = \sum_{i=0}^{\infty} \alpha_i P_i(\cos \theta)$ and $V(2m, \theta) = 2U(2m, \theta) - 2u_o$

with $U(2m, 0) = U(2m, \pi) = u_o$, $\sum_{k=1}^{\infty} \alpha_{2k-1} = 0$, $\sum_{k=1}^{\infty} \alpha_{2k} = u_o$

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Focus on quadrupole case

Weyl-distorted Schwarzschild II

T.Pilkington, A.Melanson,
J. Fitzgerald, IB
CQG 28:125018,2011

Weyl-distorted Schwarzschild II

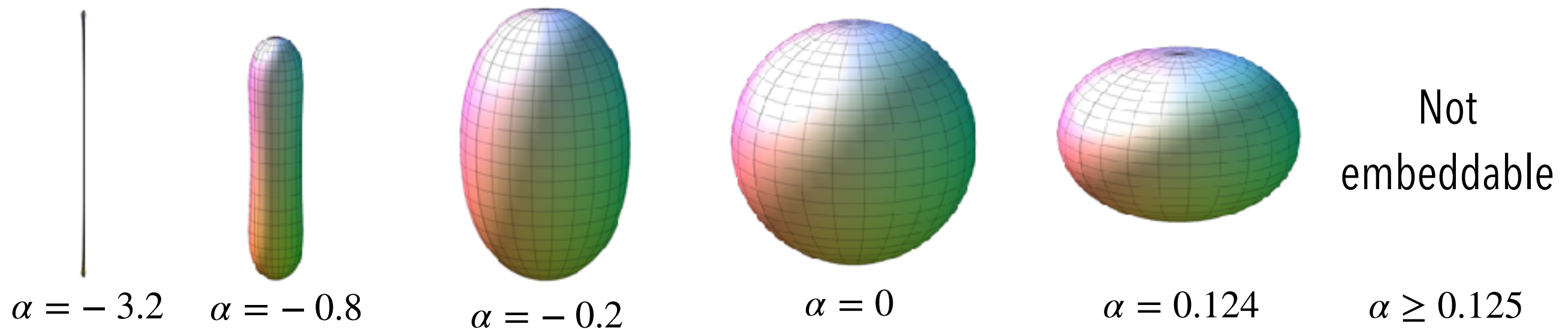
T.Pilkington, A.Melanson,
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- Quadrupole solutions give a one-parameter (α) family of distortions

Weyl-distorted Schwarzschild II

T.Pilkington, A.Melanson,
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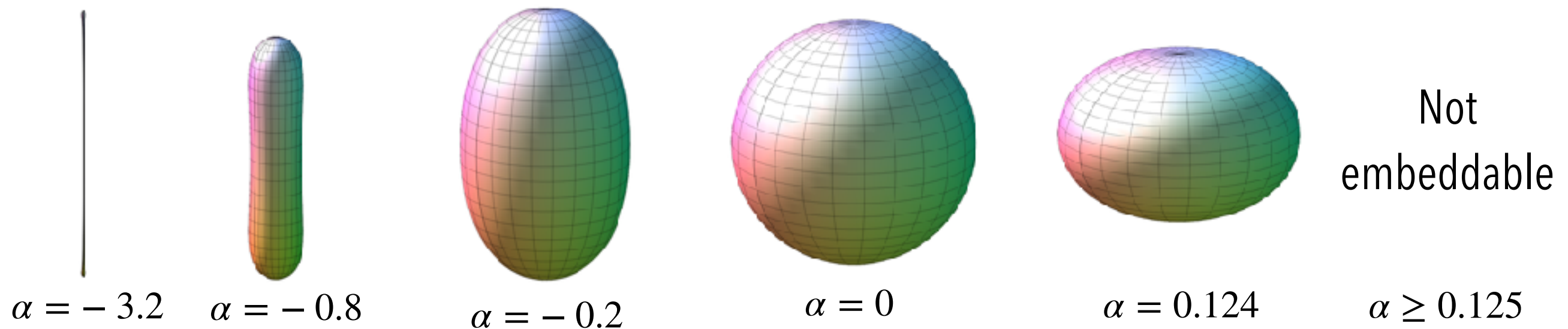
- Quadrupole solutions give a one-parameter (α) family of distortions
- $r = 2m$ bends but it doesn't break!



Weyl-distorted Schwarzschild II

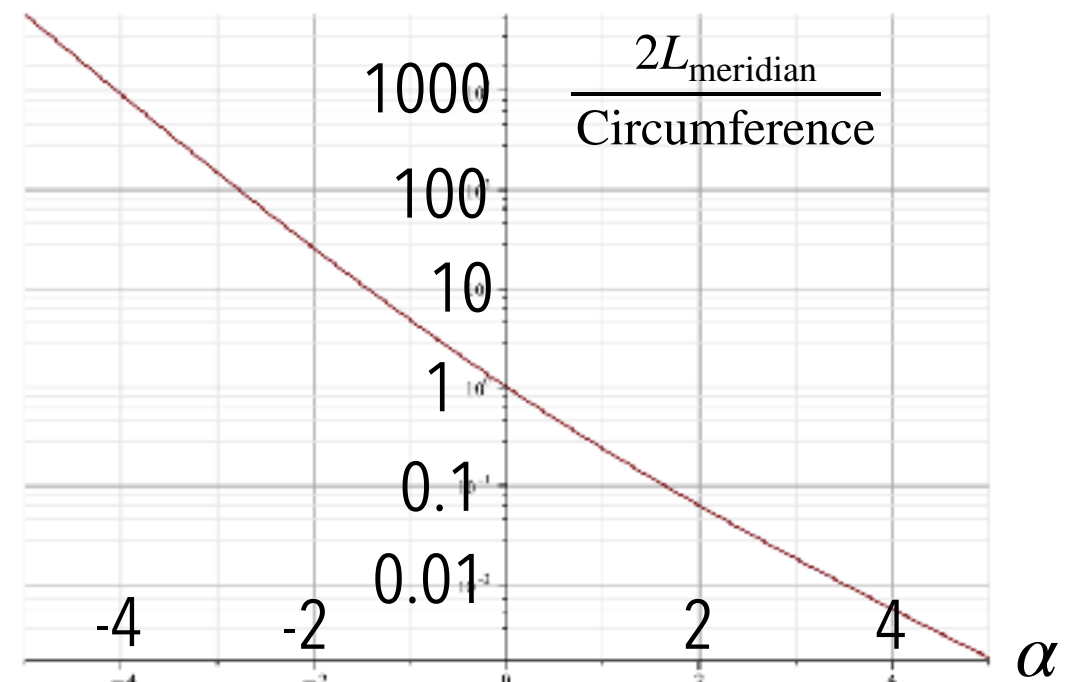
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CQG 28:125018,2011

- Quadrupole solutions give a one-parameter (α) family of distortions
- $r = 2m$ bends but it doesn't break!

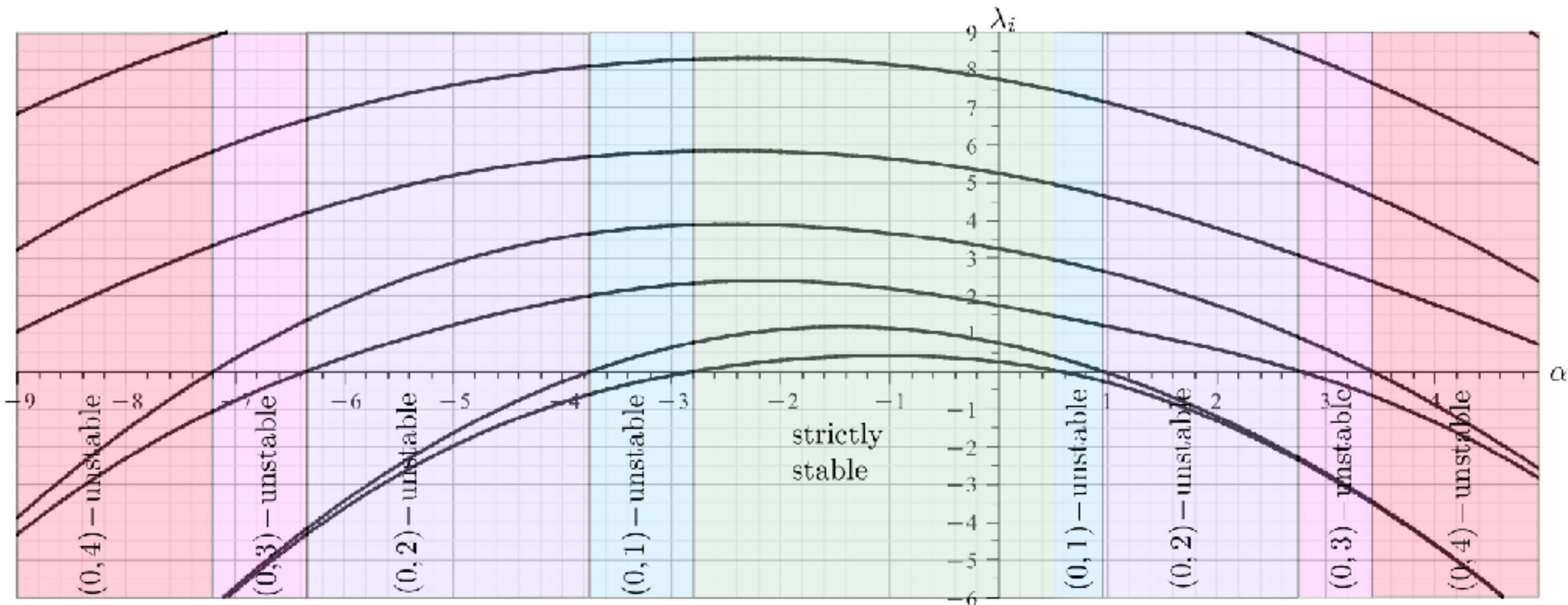
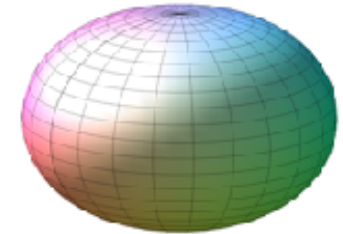
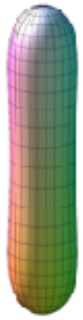


$$\text{Area} = 16\pi^2 m^2 e^{-2\alpha}$$

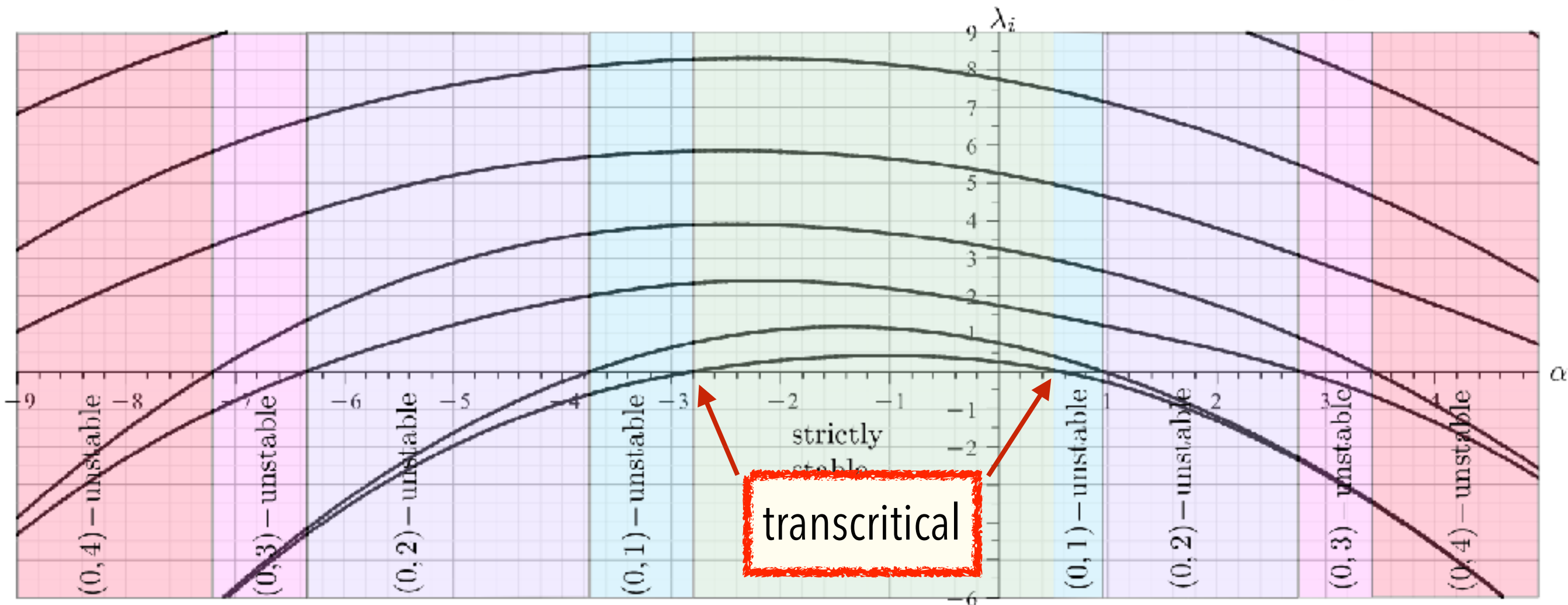
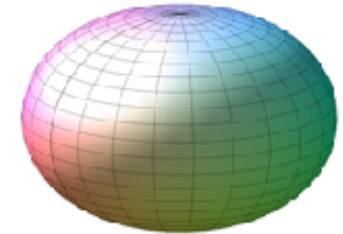
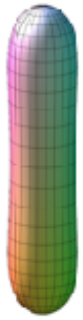
$$\text{Circumference} = 4\pi m$$



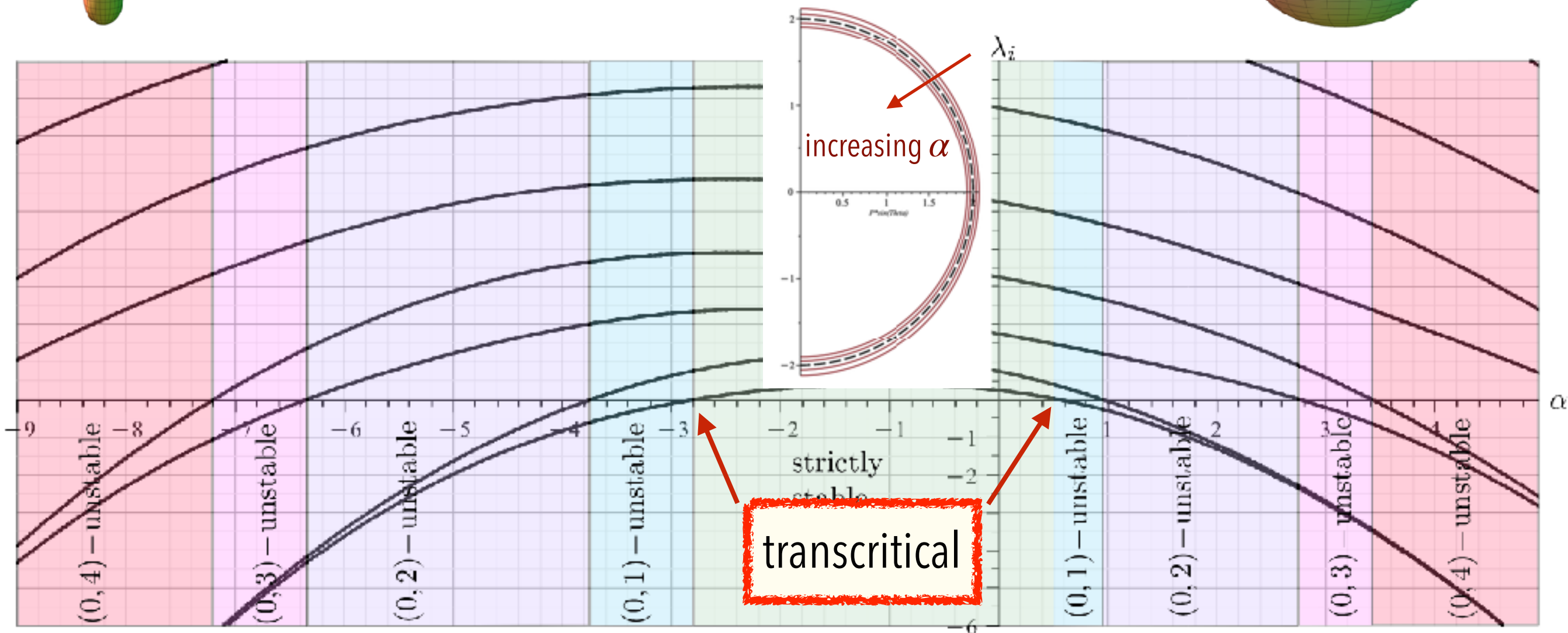
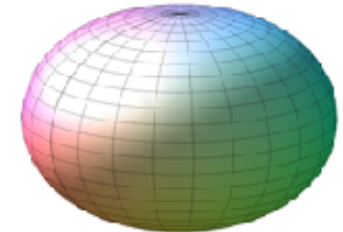
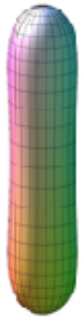
Eigenvalues of quadrupole-distorted Schwarzschild



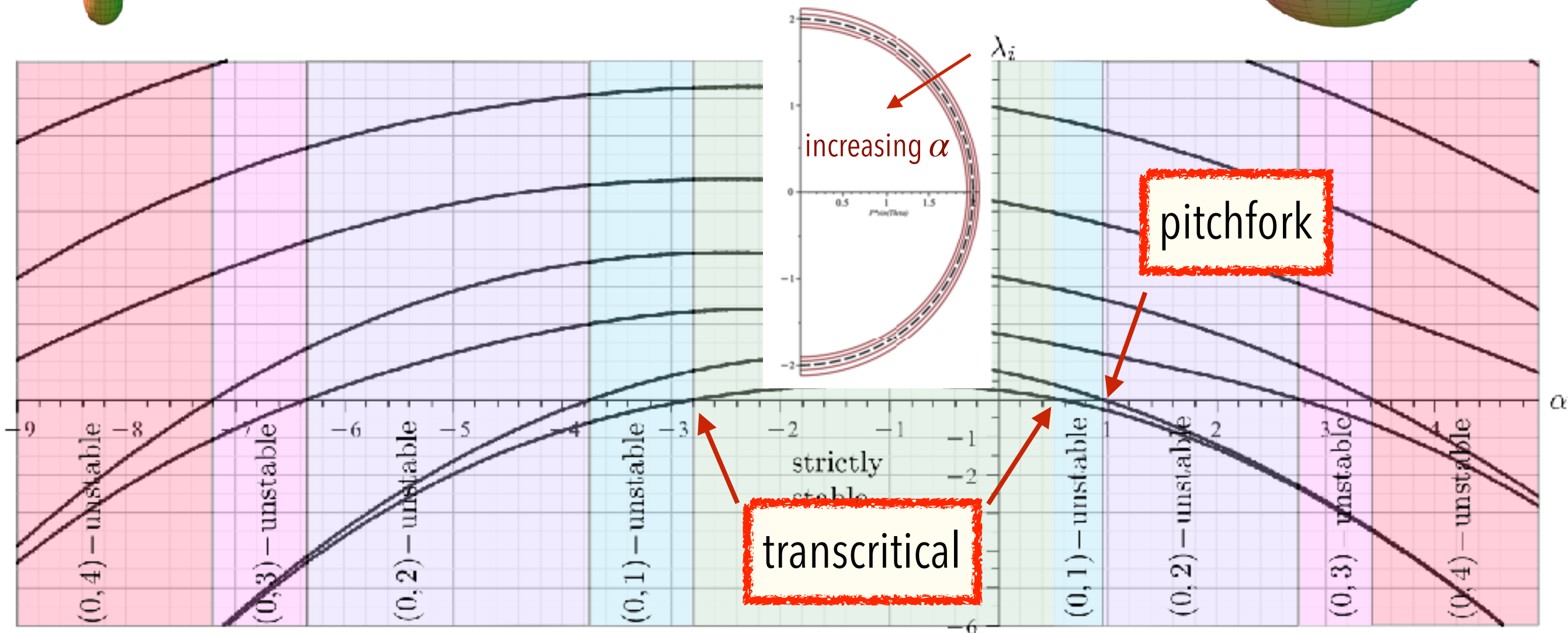
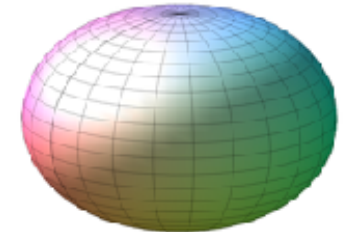
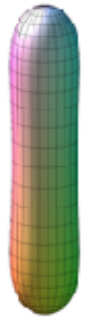
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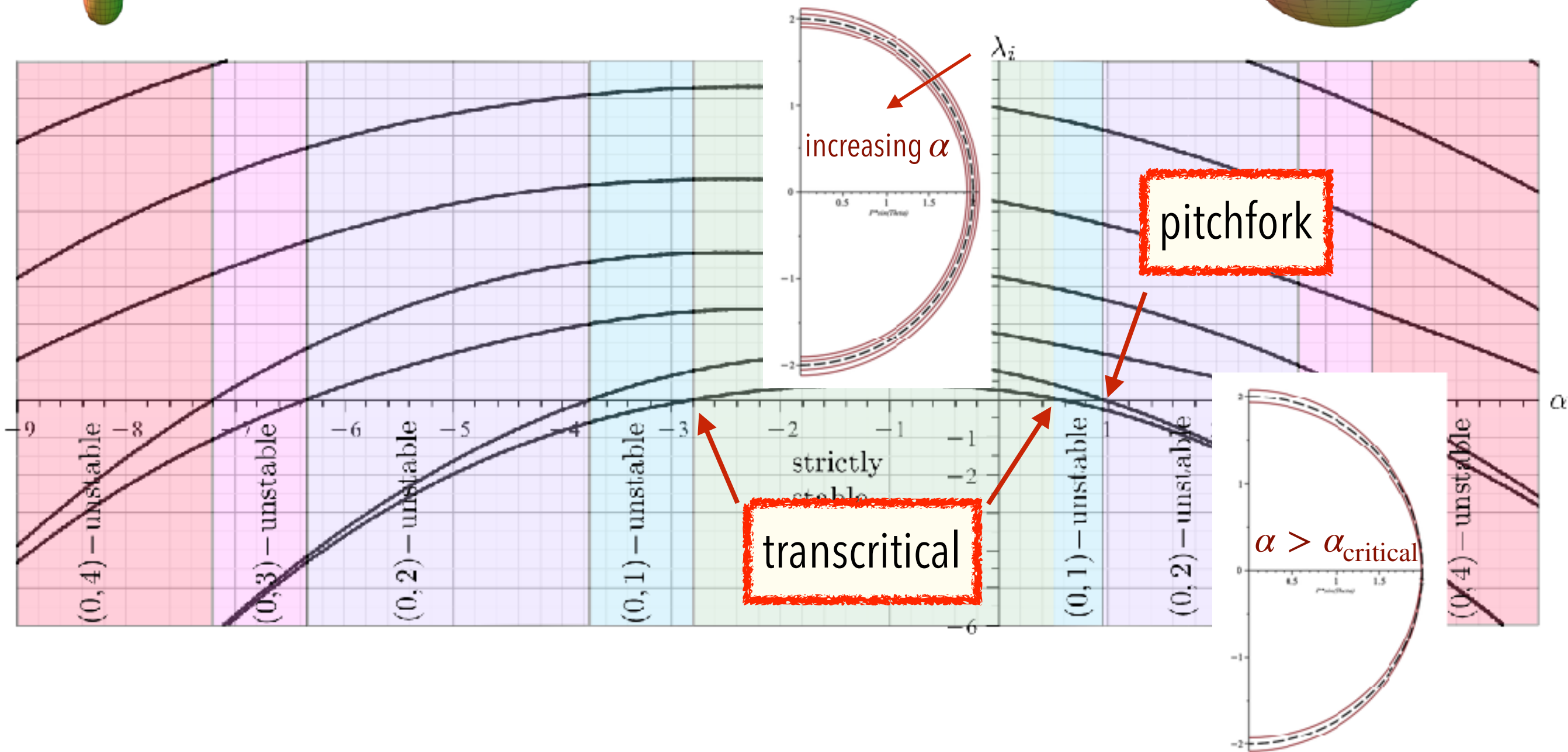
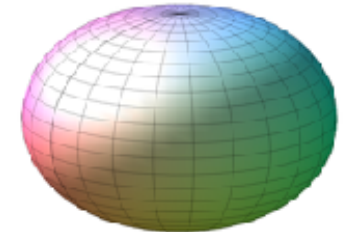
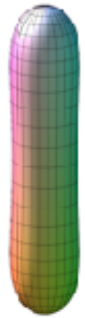
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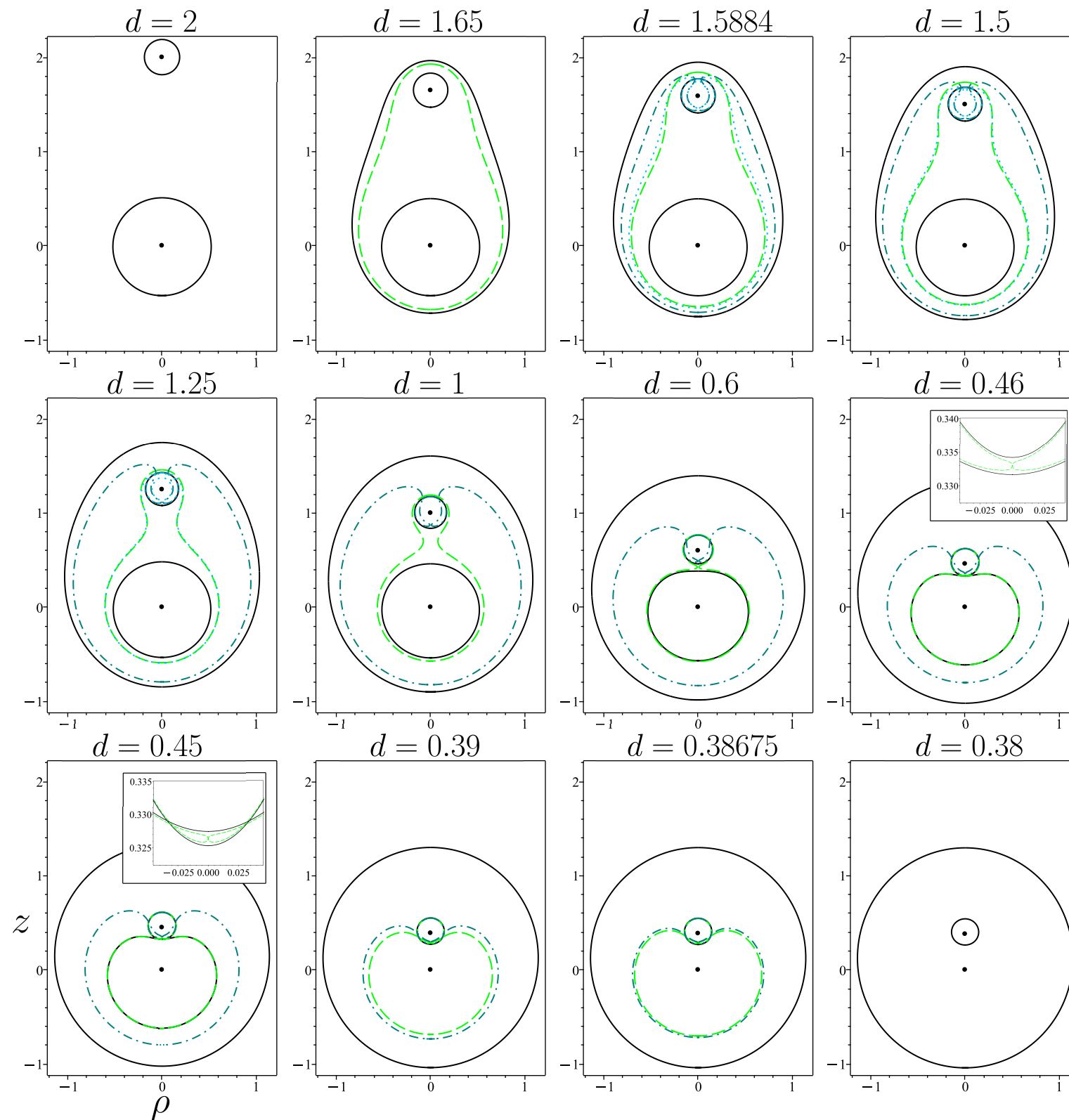
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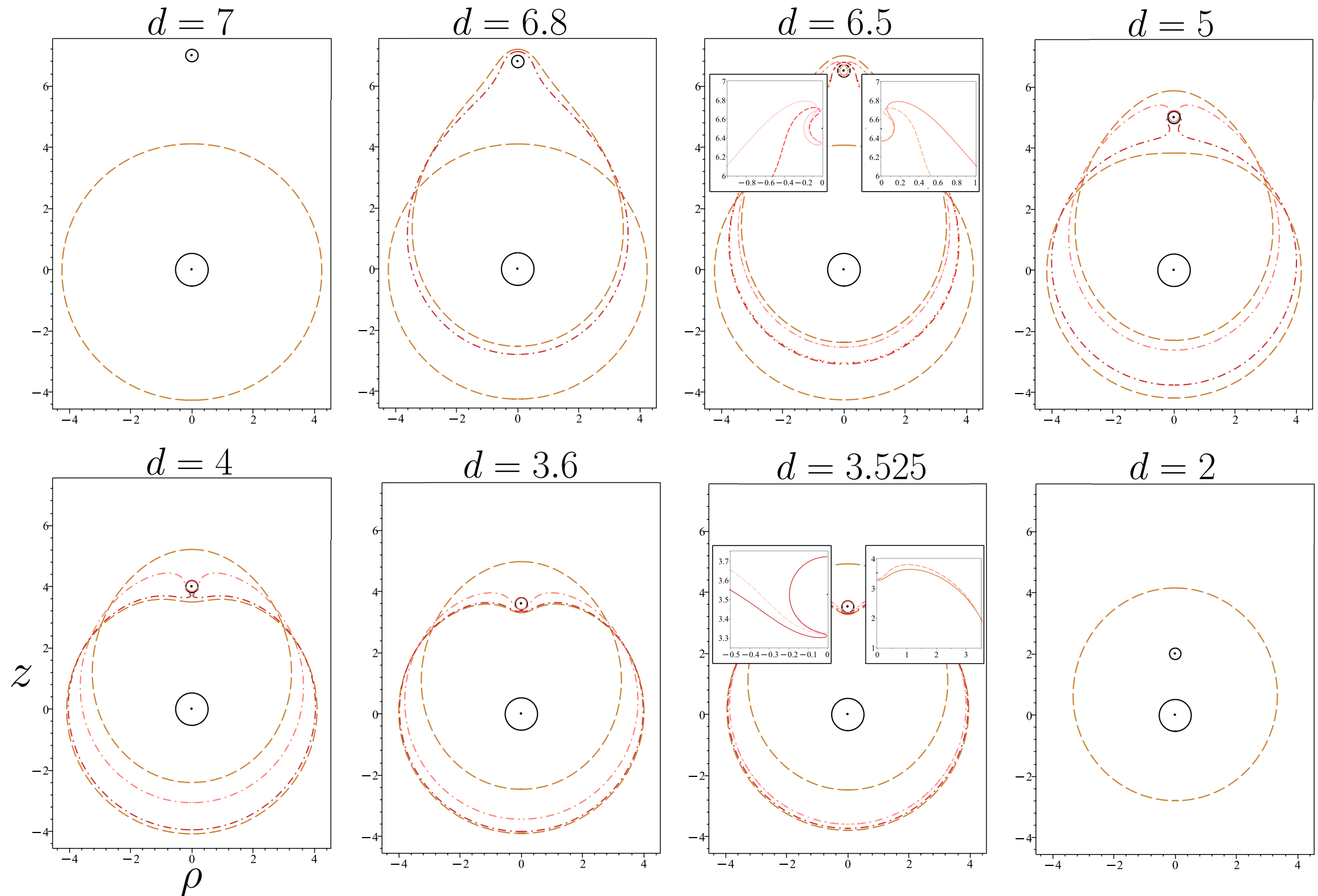
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- Are there further restrictions for physical processes??

BLdS "crossing the cosmological horizon"



F. Elizondo Lopez, IB (in progress)

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