

Bayesian Parameter Identification in Plasticity

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Overview

- 1 Model
 - Plasticity Model

- 2 Forward and Inverse Problems
 - Identification of system's state

Plasticity Model

Chaboche Model

The resulting model for inelastic strain rate (Flow Rule), considering **hardenings**:

$$\dot{\epsilon}_p(t) = \frac{\partial \sigma_{ex}}{\partial \boldsymbol{\sigma}} \dot{p}$$

where

- The over-stress: $\sigma_{ex} = \sigma_{eq} - \sigma_y - R(t)$
- The visco-plastic multiplier rate: $\dot{p} = \dot{\epsilon}_0 \langle \frac{\sigma_{ex}}{k} \rangle^n$
 - The McAuley bracket: $\langle \cdot \rangle = \max(0, x)$
- The equivalent stress: $\sigma_{eq} = \sqrt{\frac{3}{2} \text{tr}((\boldsymbol{\sigma} - \boldsymbol{\chi})_D \cdot (\boldsymbol{\sigma} - \boldsymbol{\chi})_D)}$
 - like $\boldsymbol{\sigma}_D = \boldsymbol{\sigma} - \frac{1}{3} \text{tr} \boldsymbol{\sigma} \mathbf{1}$
- The isotropic hardening: $\dot{R} = b_R (H_R - R) \dot{p}$
- The kinematic hardening: $\dot{\boldsymbol{\chi}} = b_\chi (\frac{2}{3} H_\chi \frac{\partial \sigma_{eq}}{\partial \boldsymbol{\sigma}} - \boldsymbol{\chi}) \dot{p}$

Simulating the Model

■ Employing Finite Element method

κ	G	σ_y	n	k	b_R	H_R	b_x	H_x
1.66e9	7.69e8	1.7e8	1	1.5e8	50	0.5e8	50	0.5e8

applying a cyclic load with the initial magnitude $2.5e8$ for 30 seconds

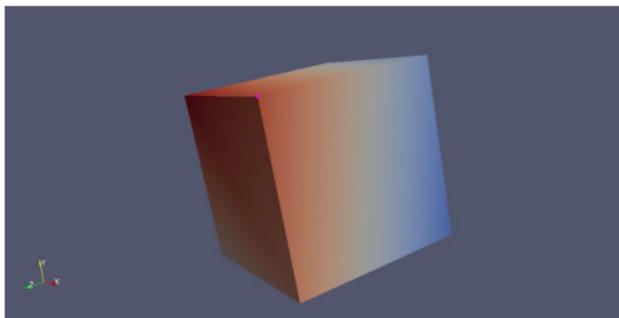


Figure : 3D element

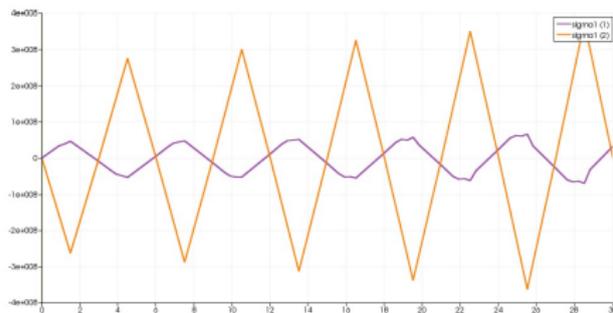


Figure : Decomposed applied force

Simulating the Model

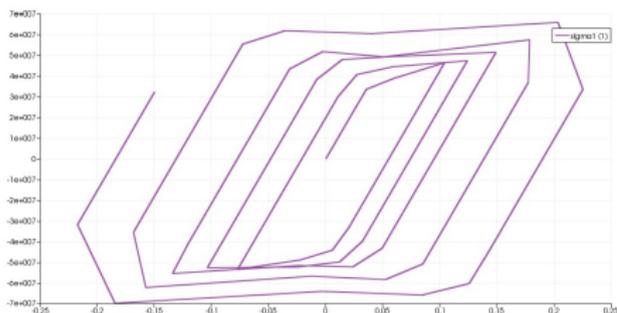


Figure : σ - ϵ in plane direction

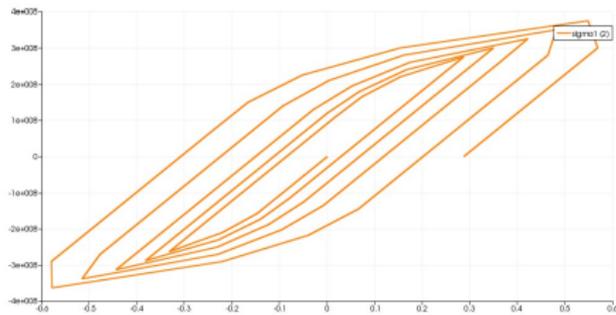


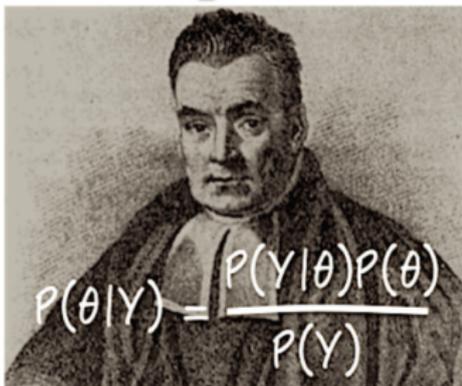
Figure : σ - ϵ in normal direction

- Vector of desired parameters $\theta = [\kappa \ G \ b_R \ b_\chi \ \sigma_y]$

Forward and Inverse Problems

Forward and Inverse Problems

Forward: $F(\theta) + \varepsilon$



Inverse: $P(\theta|Y)$

PCE based update

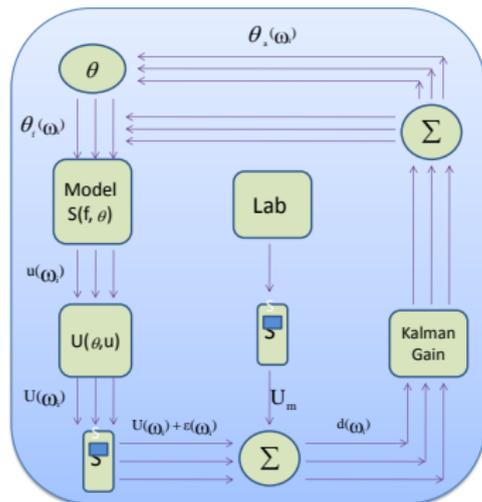
Polynomial Chaos Expansion filter:

$$\underbrace{\hat{\theta}_a}_{\text{updated}} = \underbrace{\hat{\theta}_f}_{\text{prior}} + \underbrace{\mathbf{k}}_{\text{Kalman gain}} \underbrace{(\hat{\mathbf{u}}_m - \hat{\mathbf{u}}_f)}_{\text{innovation}}$$

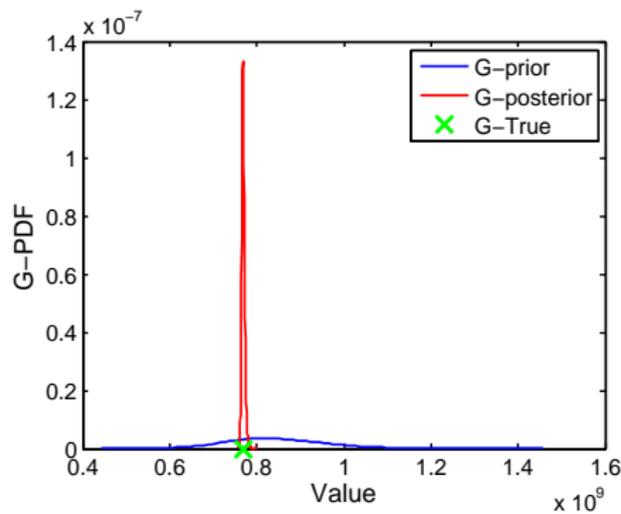
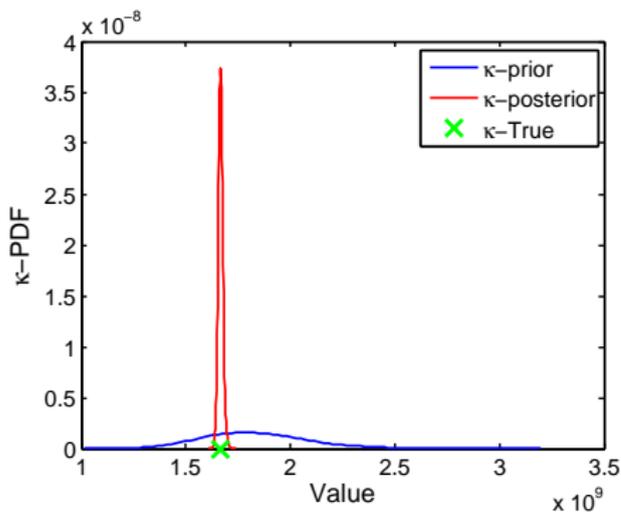
where

- $\mathbf{k} = C_{\theta_f, \mathbf{u}_f} (C_{\mathbf{u}_f, \mathbf{u}_f} + C_{\epsilon, \epsilon})^{-1}$
- $C_{\theta_f, \mathbf{u}_f} := \sum_{\alpha > 0} \alpha! \theta_f^\alpha (\mathbf{u}_f^\alpha)^T$

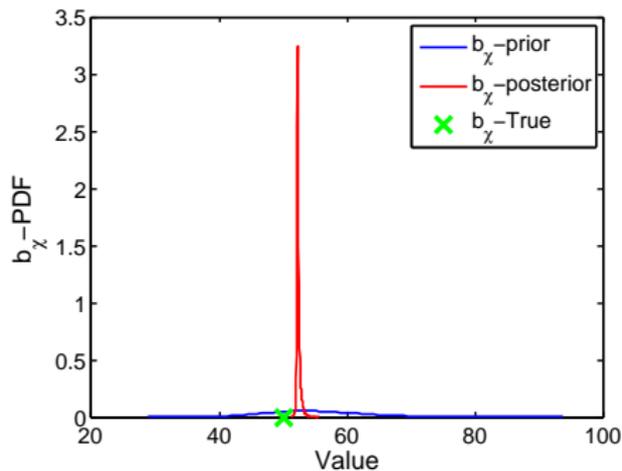
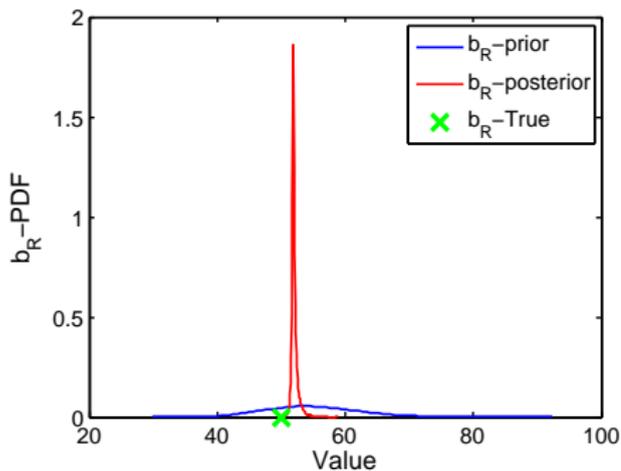
[Matthies et al., 2016]



Numerical Results



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